Evolution equations on two overlapping random walk structures

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## Nonlocal PDEs in $\mathbb{R}^N$

Let  $J : \mathbb{R}^N \to \mathbb{R}$  be a nonnegative, radially symmetric and continuous function with  $\int_{\mathbb{R}^N} J(z) dz = 1$ . Nonlocal evolution problems of the type

$$u_t(x,t) = \int_{\mathbb{R}^N} J(y-x) \left( u(y,t) - u(x,t) \right) dy$$

appear in relation to phase transition or image processing models.

- G. Alberti and G. Bellettini, Math. Ann. **310** (1998).
- S. Kindermann, S. Osher and P. Jones, SIAM J. Multiscale Model. Simul. 4 (2005).

## PDEs in graphs

Consider a locally finite weighted discrete graph G with vertices V(G) and edges E(G). If  $(x, y) \in E(G)$ , we assign to this edge a positive weight  $w_{xy} = w_{yx}$ ; otherwise,  $w_{xy} = 0$ .

One may study PDEs in this setting by introducing the weighted gradient

$$(\nabla_w f)(x, y) = \sqrt{w(x, y)} \left( f(y) - f(x) \right)$$

and the weighted divergence

$$(\operatorname{div}_w F)(x) = \frac{1}{2} \sum_{(x,y)\in E} \sqrt{w(x,y)} \left(F(x,y) - F(y,x)\right).$$

With this definition, both operators are linear, and  $\operatorname{div}_w = -\nabla_w^*$ .

# PDEs in graphs

The theory for PDEs in weighted graphs was developed primarily in the 90s and 00s, and a common framework may be found in

G. Gilboa and S. Osher, SIAM J. Multiscale Model. Simul. 7 (2008).

The PDEs in weighted graphs have many applications in machine learning and image processing. As a simple example of a second-order differential operator in this setting, the graph Laplacian is defined as

$$egin{aligned} &(\Delta_w f)(x) := (\operatorname{div}_w (
abla_w f))(x) \ &= \sum_{(x,y)\in E} w(x,y)(f(y)-f(x)), \end{aligned}$$

and it corresponds to the energy functional

$$\mathcal{E}(f):=\frac{1}{2}\|\nabla_w f\|_{L^2(E(G))}^2.$$

# Looking for a joint framework

In both examples, the 'nonlocal gradient'

u(y) - u(x)

- is 'integrated' with respect to some 'kernel'. Other common features are
- $\rightarrow$  lack of singularities;
- $\rightarrow$  existence of invariant measures;
- $\rightarrow$  symmetry of interactions.
- A joint framework including these features is called a *random walk space*.
  - Y. Ollivier, J. Funct. Anal. **256** (2009).
  - J.M. Mazón, M. Solera, J. Toledo, Variational and Diffusion Problems in Random Walk Spaces, Birkhäuser, 2023.

# Outline of the talk



- 2 Nonlocal differential operators
- 3 Two random walk structures
- Partition of the random walk

#### 🔋 W. Górny, J.M. Mazón, J. Toledo, arXiv:2410.15203.

## Outline of the talk

### Random walk spaces

- 2 Nonlocal differential operators
- 3 Two random walk structures
- Partition of the random walk

Basic ingredients:

- $(X, \mathcal{B})$  a measurable space with a countably generated  $\sigma$ -field;
- A random walk *m* on  $(X, \mathcal{B})$ , i.e., a family of probability measures  $(m_x)_{x \in X}$  on  $\mathcal{B}$  such that

 $x \mapsto m_x(B)$ 

is a measurable function on X for each fixed  $B \in \mathcal{B}$ .

The probability measure  $m_x$  acts as a replacement of a ball around  $x \in X$ .

#### Definition

Let *m* be a random walk on  $(X, \mathcal{B})$  and  $\nu$  a  $\sigma$ -finite measure on *X*. The convolution of  $\nu$  with *m* on *X* is the measure

$$u * m(A) := \int_X m_x(A) \, d\nu(x) \quad \forall A \in \mathcal{B}.$$

#### Definition

If *m* is a random walk on  $(X, \mathcal{B})$ , a  $\sigma$ -finite measure  $\nu$  on *X* is *invariant* with respect to the random walk *m* if

 $\nu * m = \nu$ .

The measure  $\nu$  is said to be *reversible* if moreover

$$dm_x(y) d\nu(x) = dm_y(x) d\nu(y).$$

In fact, reversibility of  $\nu$  implies its invariance.

Wojciech Górny (U. Vienna, U. Warsaw)

### Definition

Let  $(X, \mathcal{B})$  be a measurable space with a countably generated  $\sigma$ -field. Let m be a random walk on  $(X, \mathcal{B})$  and  $\nu$  a  $\sigma$ -finite measure which is invariant and reversible with respect to m. Then, we call the quadruple  $[X, \mathcal{B}, m, \nu]$  a random walk space.

#### Definition

Let  $(X, \mathcal{B})$  be a measurable space with a countably generated  $\sigma$ -field. Let m be a random walk on  $(X, \mathcal{B})$  and  $\nu$  a  $\sigma$ -finite measure which is invariant and reversible with respect to m. Then, we call the quadruple  $[X, \mathcal{B}, m, \nu]$  a random walk space.

 $\rightarrow$  Sometimes reversibility is omitted (but it is crucial for PDEs!);

 $\rightarrow$  Sometimes a requirement that  $\mathcal{B}$  is generated by a metric d is added; then,  $[X, d, m, \nu]$  is called a metric random walk space.

# Example 1: Euclidean spaces

#### Example

Consider the metric measure space  $(\mathbb{R}^N, d_{\text{Eucl}}, \mathcal{L}^N)$  and let  $\mathcal{B}$  be the Borel  $\sigma$ -algebra. Let  $J : \mathbb{R}^N \to [0, +\infty)$  be a measurable, nonnegative and radially symmetric function verifying  $\int_{\mathbb{R}^N} J(x) \, dx = 1$ . Let  $m^J$  be the following random walk on  $(\mathbb{R}^N, \mathcal{B})$ :

$$m_x^J(A) := \int_A J(x-y) \, dy$$
 for  $x \in \mathbb{R}^N$  and Borel  $A \subset \mathbb{R}^N$ .

Applying the Fubini theorem, it is easy to see that  $\mathcal{L}^N$  is reversible with respect to  $m^J$ . Therefore,  $[\mathbb{R}^N, \mathcal{B}, m^J, \mathcal{L}^N]$  is a random walk space.

# Example 2: Weighted graphs

#### Example

Consider a locally finite weighted discrete graph G with vertices V(G) and edges E(G). If  $(x, y) \in E(G)$ , we assign to this edge a positive weight  $w_{xy} = w_{yx}$ ; otherwise,  $w_{xy} = 0$ .

For  $x \in V(G)$  we define

$$d_{\mathsf{x}} := \sum_{(\mathsf{x}, \mathsf{y}) \in E(G)} w_{\mathsf{x}\mathsf{y}}; \qquad m_{\mathsf{x}} := \frac{1}{d_{\mathsf{x}}} \sum_{(\mathsf{x}, \mathsf{y}) \in E(G)} w_{\mathsf{x}\mathsf{y}} \, \delta_{\mathsf{y}}.$$

It is not difficult to see that the measure  $\boldsymbol{\nu}$  defined as

$$u(A) := \sum_{x \in A} d_x \quad ext{for } A \subset V(G)$$

is reversible with respect to m. Therefore,  $[V(G), \mathcal{B}, m, \nu]$  is a random walk space, where  $\mathcal{B}$  is the  $\sigma$ -algebra of all subsets of V(G).

# Outline of the talk

1 Random walk spaces

### 2 Nonlocal differential operators

3 Two random walk structures



### Gradient and divergence

Given  $u: X \to \mathbb{R}$ , we define its nonlocal gradient  $\nabla u: X \times X \to \mathbb{R}$  as

$$abla u(x,y) := u(y) - u(x) \quad \forall x, y \in X.$$

For  $z : X \times X \to \mathbb{R}$ , its *m*-divergence  $\operatorname{div}_m z : X \to \mathbb{R}$  is defined as

$$(\operatorname{div}_m \mathbf{z})(x) := \frac{1}{2} \int_X (\mathbf{z}(x, y) - \mathbf{z}(y, x)) \, dm_x(y).$$

## Gradient and divergence

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They are connected by the following integration by parts formula.

### Theorem (integration by parts)

If  $v \in L^p(X, \nu)$  and  $\mathbf{z} \in L^{p'}(X \times X, \nu \otimes m_x)$ , then

$$\int_X v(x) \operatorname{div}_m(\mathbf{z})(x) \, d\nu(x) = -\frac{1}{2} \int_{X \times X} \mathbf{z}(x, y) \, \nabla v(x, y) \, d(\nu \otimes m_x)(x, y).$$

## Memo: subdifferential

#### Definition

Let  $\mathcal{F}: E \to (-\infty, +\infty]$  be proper (i.e.  $\mathcal{F} \not\equiv +\infty$ ) and convex. The subdifferential (or subgradient)  $\partial \mathcal{F}$  of the functional  $\mathcal{F}$  is defined as

$$\partial \mathcal{F}(x) = \left\{ x^* \in E^* : \mathcal{F}(y) - \mathcal{F}(x) \ge \langle x^*, y - x \rangle \quad \forall y \in E \right\},$$

where  $E^*$  denotes the dual of E. Equivalently, if we identify a multivalued operator with its graph, it is a subset of  $E \times E^*$  defined by

$$\partial \mathcal{F} = igg\{(x,x^*) \in E imes E^*: \ \mathcal{F}(y) - \mathcal{F}(x) \geq \langle x^*,y-x 
angle \quad orall y \in Eigg\}.$$

Example

Let  $E = \mathbb{R}^N$  and  $f : \mathbb{R}^N \to \mathbb{R}$  be differentiable. Then,  $\partial f(x) = \{\nabla f(x)\}$ .

#### Example

Let  $\Omega$  be an open bounded subset of  $\mathbb{R}^N$  with smooth boundary. Let  $\mathcal{F}: L^2(\Omega) \to [0, +\infty]$  be given by

$$\mathcal{F}(u) = \begin{cases} \int_{\Omega} |\nabla u|^2 dx & \text{if } u \in W_0^{1,2}(\Omega); \\ +\infty & \text{if } u \in L^2(\Omega) \setminus W_0^{1,2}(\Omega). \end{cases}$$

Then,  $\partial \mathcal{F}(u) = -\Delta u$  and  $D(\partial \mathcal{F}) = W^{2,2}(\Omega) \cap W_0^{1,2}(\Omega)$ .

The subdifferentials of convex functions in Banach spaces are important in the optimization theory due to the following fact: observe that

$$0 \in \partial \mathcal{F}(x) \iff \mathcal{F}(y) \ge \mathcal{F}(x) \quad \forall y \in E,$$

so  $0 \in \partial \mathcal{F}(x)$  is the *Euler-Lagrange equation* of the variational problem

$$\mathcal{F}(x) = \min_{y \in E} \mathcal{F}(y).$$

Memo: evolution equations in Hilbert spaces

#### Definition

If E is a Hilbert space H equipped with a scalar product  $(\cdot, \cdot)$  and a norm

$$\|x\|_H := \sqrt{(x,x)},$$

we will say that an operator A in H is monotone if

$$(x-\hat{x},y-\hat{y})\geq 0$$
 for all  $(x,y),(\hat{x},\hat{y})\in A$ .

If  $\mathcal{F}$  is defined on a Hilbert space H,  $\partial \mathcal{F}$  is a monotone operator in H.

Moreover, if  $\mathcal{F}$  is lower semicontinuous, then the subdifferential  $\partial \mathcal{F}$  has a dense domain and is *maximal monotone*, i.e., it is maximal with respect to inclusion among monotone operators.

## Memo: evolution equations in Hilbert spaces

Consider the abstract Cauchy problem

$$\begin{cases} \frac{du}{dt} + \partial \mathcal{F}(u(t)) \ni f(t, \cdot), & t \in (0, T), \\ u(0) = u_0, & u_0 \in H. \end{cases}$$
(P)

### Definition

We say that  $u \in C([0, T]; H)$  is a *strong solution* of problem (P), if the following conditions hold:  $u \in W_{loc}^{1,2}(0, T; H)$ ; for almost all  $t \in (0, T)$  we have  $u(t) \in D(\partial F)$ ; and it satisfies (P).

#### Theorem (Brezis-Komura theorem)

Let  $\mathcal{F} : H \to (-\infty, \infty]$  be a proper, convex, and lower semicontinuous functional. Given  $u_0 \in \overline{D(\partial \mathcal{F})}$  and  $f \in L^2(0, T; H)$ , there exists a unique strong solution u(t) of the abstract Cauchy problem (P).

## Nonlocal *p*-Laplacian

For p > 1, we consider the functional

$$\mathcal{F}_{p,m}: L^2(X,\nu) \to (-\infty,+\infty]$$

defined by

$$\mathcal{F}_{p,m}(u) := \frac{1}{2p} \int_{X \times X} |u(y) - u(x)|^p d(\nu \otimes m_x)(x,y)$$

if  $\nabla u \in L^p(X \times X, \nu \otimes m_x)$  and  $+\infty$  otherwise. Observe that

$$L^p(X,\nu)\cap L^2(X,\nu)\subset D(\mathcal{F}_{p,m}).$$

## Nonlocal *p*-Laplacian

Since  $\mathcal{F}_{p,m}$  is convex and lower semicontinuous, the subdifferential

$$\partial_{L^2(X,\nu)}\mathcal{F}_{p,m}$$

is a maximal monotone operator with a dense domain.

To have a definition consistent with the standard case, we *define* the (multivalued) nonlocal *p*-Laplacian operator  $\Delta_p^m$  by

$$(u,v)\in\Delta_{\rho}^{m}\iff (u,-v)\in\partial_{L^{2}(X,\nu)}\mathcal{F}_{\rho,m}.$$

# Nonlocal *p*-Laplacian

### Theorem (G.-Mazón-Toledo 2024)

Let p > 1.  $(u, v) \in \Delta_p^m$  if and only if the following conditions hold:

•  $u, v \in L^2(X, \nu);$ 

• 
$$\nabla u \in L^p(X \times X, \nu \otimes m_x);$$

• 
$$v(x) = \operatorname{div}_m(|\nabla u|^{p-2}\nabla u)(x) = \int_X |\nabla u(x,y)|^{p-2} \nabla u(x,y) \, dm_x(y).$$

This result was known already for p = 2; a proof will be presented below.

J.M. Mazón, M. Solera, J. Toledo, J. Math. Anal. Appl. 483 (2020).

## Proof of the characterisation

*Proof.* For every (u, -v),  $(\hat{u}, -\hat{v}) \in \Delta_p^m$ , by the integration by parts formula, we have

$$\begin{split} &\int_{X} (u-\hat{u})(v-\hat{v}) \, d\nu \\ &= -\int_{X} (u-\hat{u}) (\Delta_{p}^{m}u - \Delta_{p}^{m}\hat{u}) \, d\nu \\ &= -\int_{X} (u-\hat{u}) \cdot \Delta_{p}^{m}u \, d\nu + \int_{X} (u-\hat{u}) \cdot \Delta_{p}^{m}\hat{u} \, d\nu \\ &= \frac{1}{2} \int_{X \times X} |\nabla u|^{p-2} \, \nabla u \, \nabla (u-\hat{u}) \, d(\nu \otimes m_{x}) \\ &\quad -\frac{1}{2} \int_{X \times X} |\nabla \hat{u}|^{p-2} \, \nabla \hat{u} \, \nabla (u-\hat{u}) \, d(\nu \otimes m_{x}) \\ &= \frac{1}{2} \int_{X \times X} \left( |\nabla u|^{p-2} \, \nabla u - |\nabla \hat{u}|^{p-2} \, \nabla \hat{u} \right) \nabla (u-\hat{u}) \, d(\nu \otimes m_{x}) \geq 0, \end{split}$$

so the operator  $-\Delta_p^m$  is monotone.

## Proof of the characterisation

Since  $\partial \mathcal{F}_{p,m}$  is maximal monotone, it suffices to show that

$$\partial \mathcal{F}_{p,m} \subset -\Delta_p^m.$$

Let  $(u, v) \in \partial \mathcal{F}_{p,m}$ . Then, for every  $w \in L^1(X, \nu) \cap L^{\infty}(X, \nu)$  and t > 0, we have

$$rac{\mathcal{F}_{m{
ho},m}(u+tw)-\mathcal{F}_{m{
ho},m}(u)}{t} \geq \int_X vw \ d
u.$$

Then, taking limit as  $t \rightarrow 0^+$ , we obtain that

$$\frac{1}{2}\int_{X\times X}|\nabla u(x,y)|^{p-2}\nabla u(x,y)\nabla w(x,y)\,dm_x(y)\,d\nu(x)\geq \int_X vw\,d\nu.$$

## Proof of the characterisation

Since this inequality is also true for -w, we have

$$\frac{1}{2}\int_{X\times X}|\nabla u(x,y)|^{p-2}\nabla u(x,y)\nabla w(x,y)\,dm_x(y)\,d\nu(x)=\int_X vw\,d\nu.$$

Then, applying again the integration by parts formula, we get

$$-\int_X \Delta_p^m u(x) w(x) d\nu(x) = \int_X vw d\nu \quad \forall w \in L^1(X, \nu) \cap L^\infty(X, \nu).$$

From here, we deduce that  $v = -\Delta_p^m u$ , and consequently  $(u, -v) \in \Delta_p^m$ .

## Nonlocal 1-Laplacian

We define the space of *functions of bounded variation* in  $[X, \mathcal{B}, m, \nu]$  as

$$BV_m(X,\nu) := \left\{ u: X \to \mathbb{R} : \int_{X \times X} |\nabla u(x,y)| \, dm_x(y) \, d\nu(x) < \infty 
ight\}.$$

The total variation functional  $\mathcal{F}_{1,m}: L^2(X,\nu) o (-\infty,+\infty]$  is defined by

$$\mathcal{F}_{1,m}(u) := \frac{1}{2} \int_{X \times X} |u(y) - u(x)| d(\nu \otimes m_x)(x,y)$$

if  $u \in BV_m(X, \nu)$  and  $+\infty$  otherwise. Observe that

 $L^1(X,\nu)\cap L^2(X,\nu)\subset D(\mathcal{F}_{1,m}).$ 

## Nonlocal 1-Laplacian

To have a definition consistent with the standard case, we *define* the (multivalued) nonlocal 1-Laplacian operator  $\Delta_1^m$  by

$$(u,v)\in\Delta_1^m\iff (u,-v)\in\partial_{L^2(X,\nu)}\mathcal{F}_{1,m}.$$

An equivalent characterisation is the following: there exists an antisymmetric function  $\mathbf{g} \in L^{\infty}(X \times X, \nu \otimes m_x)$  such that

$$\|\mathbf{g}\|_{L^{\infty}(X \times X, \nu \otimes m_x)} \leq 1;$$
  
$$v(x) = \int_X \mathbf{g}(x, y) \, dm_x^1(y) \quad \text{for } \nu\text{-a.e. } x \in X;$$
  
$$\mathbf{g}(x, y) \in \text{sign}(u(y) - u(x)) \quad \text{for } (\nu \otimes m_x)\text{-a.e. } (x, y) \in X \times X.$$

J.M. Mazón, M. Solera, J. Toledo, Calc. Var. PDE 59 (2020).

# Outline of the talk

Random walk spaces

- 2 Nonlocal differential operators
- 3 Two random walk structures
- Partition of the random walk

## Nonlocal equations with inhomogeneous growth

Our goal is to propose a framework to study evolution problems with inhomogeneous growth on random walk spaces. We consider two cases:

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 $\rightarrow$  The measurable space  $(X, \mathcal{B})$  supports two random walk structures  $m^1$  and  $m^2$  (with invariant measures  $\nu_1$  and  $\nu_2$ ), which may overlap, and the functional has different growth on the two structures;

## Nonlocal equations with inhomogeneous growth

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 $\rightarrow$  We have a single random walk space  $[X, \mathcal{B}, m, \nu]$  and a partition of m, where again the functional has different growth on the two pieces.

Let  $[X, \mathcal{B}, m^1, \nu_1]$  and  $[X, \mathcal{B}, m^2, \nu_2]$  are two random walk spaces defined on the same measurable space. We assume that

$$\nu_2 \ll \nu_1$$

and

$$\mu:=\frac{d\nu_2}{d\nu_1}\in L^\infty(X,\nu_1),$$

where  $\mu > 0 \nu_1$ -a.e. Due to these assumptions, we may consider the evolution in a joint Hilbert space, denoted by

$$H:=L^2(X,\nu_1).$$

(This is satisfied by our most of the standard examples.)

For  $1 \leq q \leq p$ , consider the functionals  $\mathcal{F}_{q,m^1} : L^2(X,\nu_1) \to (-\infty,+\infty]$ and  $\mathcal{F}_{p,m^2} : L^2(X,\nu_1) \to (-\infty,+\infty]$  given by

$$\mathcal{F}_{q,m^1}(u) := rac{1}{2q} \int_{X \times X} |u(y) - u(x)|^q \ d(\nu_1 \otimes m_x^1)(x,y)$$

if  $|
abla u|^q \in L^1(X imes X, 
u_1 \otimes m^1_x)$  and  $+\infty$  otherwise, and

$$\mathcal{F}_{p,m^2}(u) := \frac{1}{2p} \int_{X \times X} |u(y) - u(x)|^p d(\nu_2 \otimes m_x^2)(x,y)$$

if  $|\nabla u|^p \in L^1(X \times X, \nu_2 \otimes m_x^2)$  and  $+\infty$  otherwise. Both functionals are convex and lower semicontinuous in H.

Theorem (G.-Mazón-Toledo 2024)

Let  $1 \leq q \leq p$ . Assume that

$$\mu:=\frac{d\nu_2}{d\nu_1}\in L^\infty(X,\nu_1),$$

and there exists c > 0 such that  $\mu \ge c \nu_1$ -a.e.

Suppose that one of the following conditions holds: (a)  $\nu_1(X) < \infty$  and  $q \le 2$ ; (b)  $\nu_1(X) = +\infty$  and  $q \le \frac{p}{p-1} \le 2 \le p$ . Then, we have

$$\partial_{\mathcal{H}}\left(\mathcal{F}_{q,m^{1}}+\mathcal{F}_{p,m^{2}}\right)=-\Delta_{q}^{m^{1}}-\mu\Delta_{p}^{m^{2}}.$$

Moreover, this operator has a dense domain in H.

Under these conditions, we get the following existence result.

#### Theorem (G.-Mazón-Toledo 2024)

Let T > 0. For any  $u_0 \in L^2(X, \nu_1)$  and  $f \in L^2(0, T; L^2(X, \nu_1))$ , the following problem has a unique strong solution:

$$\begin{cases} u_t - \Delta_q^{m^1} u - \mu \Delta_p^{m^2} u \ni f & on [0, T] \\ u(0) = u_0. \end{cases}$$

(1)

In the case  $f \equiv 0$ , we can get more information concerning the asymptotic behaviour of solutions to the problem

$$\begin{cases} u_t - \Delta_q^{m^1} u - \mu \Delta_p^{m^2} u \ni 0 \quad \text{on } [0, T] \\ u(0) = u_0. \end{cases}$$
(2RW)

For this, we need to assume a structural condition on the random walk space. Let  $\nu_1(X) < \infty$ . We say that  $\mathcal{F}_{q,m^1}$  satisfies a (q, 2)-Poincaré inequality, if there us a constant  $\lambda_2(\mathcal{F}_{q,m^1}) > 0$  such that

$$\lambda_2(\mathcal{F}_{q,m^1}) \|u - \overline{u}\|_{L^2(X,\nu_1)}^q \leq \mathcal{F}_{q,m^1}(u) \quad \forall u \in L^2(X,\nu_1),$$

where

$$\overline{u}:=\frac{1}{\nu_1(X)}\int_X u\,d\nu_1.$$

### Theorem (G.-Mazón-Toledo 2024)

Assume that  $\nu_1(X) < \infty$  and  $\mathcal{F}_{q,m^1}$  satisfies a (q, 2)-Poincaré inequality. For  $u_0 \in L^2(X, \nu_1)$ , let u(t) be the solution of (2RW) with q < 2. Then,

$$\|u(t)-\overline{u_0}\|_{L^2(X,\nu_1)}^{2-q} \leq \left(\|u_0-\overline{u_0}\|_{L^2(X,\nu_1)}^{2-q}-\lambda_2(\mathcal{F}_{q,m^1})t\right)^+ \quad \forall t>0.$$

In particular, if we denote by

$$T_{\mathrm{ex}}(u_0) := \inf\{T > 0 : u(t) = \overline{u_0} \ \forall t \ge T\}$$

the extinction time, it is finite and we have the following bound

$$T_{\mathrm{ex}}(u_0) \leq \frac{\|u_0 - \overline{u_0}\|_{L^2(X,\nu_1)}^{2-q}}{(2-q)\lambda_2(\mathcal{F}_{q,m^1})}.$$

Results of this type hold also for  $\nu_1(X) = +\infty$  and q = 2.

# The (1,2)-Laplace equation on a linear graph

#### Example

Consider a linear graph G = (V, E) with three vertices  $V = \{1, 2, 3\}$ , two edges  $E = \{(1, 2), (2, 3)\}$ , and with positive weights

$$w_{1,2} = a, \quad w_{2,3} = b.$$



We have

$$\nu(\{1\}) = a, \quad \nu(\{2\}) = a + b, \quad \nu(\{3\}) = b,$$

and the random walk m is given by

$$m_1 = \delta_2, \quad m_2 = rac{a}{a+b}\delta_1 + rac{b}{a+b}\delta_3, \quad m_3 = \delta_2.$$

#### Example

Consider the evolution problem

$$u_t = \Delta_1^m u + \Delta_2^m u$$
 in V.

Let us call x(t) := u(1, t), y(t) = u(2, t) and z(t) = u(3, t). Then, the above equation can be written as the following system of ODEs

$$\begin{aligned} \mathbf{y}'(t) &= \mathbf{g}_t(1,2) + y(t) - x(t); \\ y'(t) &= -\frac{a}{a+b}\mathbf{g}_t(1,2) + \frac{b}{a+b}\mathbf{g}_t(2,3) \\ &+ \frac{a}{a+b}(x(t) - y(t)) + \frac{b}{a+b}(z(t) - y(t)); \\ \mathbf{z}'(t) &= -\mathbf{g}_t(2,3) + y(t) - z(t). \end{aligned}$$

### Example

The antisymmetric functions  $\mathbf{g}_t(1,2), \mathbf{g}_t(2,3)$  satisfy

 $\mathbf{g}_t(1,2)\in \mathrm{sign}(y(t)-x(t)), \quad \mathbf{g}_t(2,3)\in \mathrm{sign}(z(t)-y(t)).$ 

We add the initial condition  $u(0) = c\chi_{\{1\}}$ , or equivalently

$$x(0) = c$$
,  $y(0) = 0$ ,  $z(0) = 0$ .

We now examine the behaviour of this system in three special cases.





Figure: Case B. a = b = 1, c = 10. x(t) continuous line; y(t) dashed line; z(t) dotted line. Valid for  $0 \le t \le 1.609438$ .





Figure: Case C. a = 10, b = 1, c = 1. x(t) continuous line; y(t) dashed line; z(t) dotted line. Valid for  $0 \le t \le 0.376844$ .



Figure: Case C. a = 10, b = 1, c = 1. x(t) = y(t) continuous line; z(t) dotted line. Valid for  $t \ge 0.376844$ . After  $t \approx 0.430724$ , x(t) = y(t) = z(t).

#### Example

The solution behaves much different depending in the three cases:

 $\rightarrow$  Case A: The value of *u* is at all times equal in the vertices 2 and 3;

 $\rightarrow$  Case B: The value of u is larger in the vertex 2 than 3, until at some point u(1) > u(2) = u(3);

 $\rightarrow$  Case C: The value of u is larger in the vertex 2 than 3, until at some point u(1) = u(2) > u(3).

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Still, there are two important shared properties:

- $\rightarrow$  There is a finite extinction time;
- $\rightarrow$  The mean of the initial data (with respect to  $\nu)$  is preserved.

# Outline of the talk

Random walk spaces

- 2 Nonlocal differential operators
- 3 Two random walk structures



## Partition of a random walk

Let  $[X, \mathcal{B}, m, \nu]$  be a random walk space. Fix measurable sets  $A_x, B_x$  with

$$\operatorname{supp}(m_x) = A_x \cup B_x.$$

The sets  $A_x$  and  $B_x$  may overlap. Consider the energy functional

$$\mathcal{F}(u) = \int_{X} \left( \frac{1}{2q} \int_{A_{x}} |u(y) - u(x)|^{q} dm_{x}(y) + \frac{1}{2p} \int_{B_{x}} |u(y) - u(x)|^{p} dm_{x}(y) \right)$$

where  $\mathcal{F}(u) = +\infty$  if the integral is not finite. By reversibility of  $\nu$  with respect to *m*, we have that

$$\begin{aligned} \mathcal{F}(u) &= \frac{1}{2q} \int_X \int_X |u(y) - u(x)|^q \frac{\chi_{A_x}(y) + \chi_{A_y}(x)}{2} \, dm_x(y) \, d\nu(x) \\ &+ \frac{1}{2p} \int_X \int_X |u(y) - u(x)|^p \frac{\chi_{B_x}(y) + \chi_{B_y}(x)}{2} \, dm_x(y) \, d\nu(x). \end{aligned}$$

## Partition of a random walk

Consider the symmetric functions  $K_A, K_B : X \to \mathbb{R}$  defined by

$$\mathcal{K}_{\mathcal{A}}(x,y):=rac{\chi_{\mathcal{A}_x}(y)+\chi_{\mathcal{A}_y}(x)}{2} \quad ext{and} \quad \mathcal{K}_{\mathcal{B}}(x,y):=rac{\chi_{\mathcal{B}_x}(y)+\chi_{\mathcal{B}_y}(x)}{2}.$$

Then, we define  $\mathcal{F}_{A,q,m}, \mathcal{F}_{B,p,m}: L^2(X,\nu) o (-\infty,+\infty]$  as

$$\mathcal{F}_{A,q,m}(u) := \frac{1}{2q} \int_{X \times X} |u(y) - u(x)|^q \, \mathcal{K}_A(x,y) \, d(\nu \otimes m_x)(x,y)$$

and

$$\mathcal{F}_{B,p,m}(u) := \frac{1}{2p} \int_{X \times X} |u(y) - u(x)|^p \, \mathcal{K}_B(x,y) \, d(\nu \otimes m_x)(x,y)$$

Both functionals are convex and lower semicontinuous with respect to convergence in  $L^2(X, \nu)$ .

## Partition of the random walk

For  $p \ge 1$ , we define the *m*-*p*-*B*-Laplacian operator  $\Delta_{p,B}^m$  in  $[X, \mathcal{B}, m, \nu]$  as

$$(u,v) \in \Delta^m_{\rho,B} \iff (u,-v) \in \partial_{L^2(X,\nu)} \mathcal{F}_{B,\rho,m}.$$
 (2)

#### Theorem

For p > 1, we have

$$\begin{aligned} (u,v) \in \Delta_{p,B}^{m} \iff u, v \in L^{2}(X,\nu), \ |\nabla u|^{p-1} \in L^{1}(X \times X, \nu \otimes m_{x}) \text{ and} \\ v(x) = \operatorname{div}_{m}(K_{B}|\nabla u|^{p-2}\nabla u)(x) \\ &= \int_{X} K_{B}(x,y)|\nabla u(x,y)|^{p-2}\nabla u(x,y) \, dm_{x}(y). \end{aligned}$$

## Partition of the random walk

We have a similar characterisation of the *m*-1-*A*-Laplacian operator  $\Delta_{p,A}^m$ .

#### Theorem

#### We have

$$(u,v) \in \partial_{L^2(X,\nu)} \mathcal{F}_{A,1,m} \iff u,v \in L^2(X,\nu)$$

and there exists  $\mathbf{g} \in L^{\infty}(X \times X, \nu \otimes m_x)$  antisymmetric with

$$\|\mathbf{g}\|_{L^{\infty}(X \times X, \nu \otimes m_x)} \leq 1;$$
  
 $v(x) = -\int_X \mathbf{g}(x, y) \mathcal{K}_{\mathcal{A}}(x, y) dm_x(y) \quad \textit{for } \nu\text{-a.e. } x \in X$ 

and

$$\mathbf{g}(x,y)\mathcal{K}_{\mathcal{A}}(x,y)\in \mathrm{sign}(u(y)-u(x))\mathcal{K}_{\mathcal{A}}(x,y) \quad (\nu\otimes m_x)\text{-a.e.}$$

# Partition of the random walk

#### Theorem (G.-Mazón-Toledo 2024)

Let  $1 \le q \le p$ . Suppose that one of the following conditions holds: (a)  $\nu(X) < \infty$ ,  $q \le 2$ ; (b)  $\nu(X) = +\infty$  and  $q \le \frac{p}{p-1} \le 2 \le p$ . Then, we have

$$\partial_{L^2(X,\nu)} \left( \mathcal{F}_{A,q,m} + \mathcal{F}_{B,p,m} \right) = -\Delta^m_{q,A} - \Delta^m_{p,B}.$$

Furthermore, this operator has a dense domain in  $L^2(X, \nu)$ .

We immediately obtain the corresponding existence and uniqueness result.

#### Example

Consider the graph G = (V, E) with vertices  $V = \{1, 2, 3, 4\}$  and edges  $E = \{(1, 4), (1, 2), (2, 3), (3, 4)\}$ . We assign to the edges positive weights

$$w_{1,2} = a, w_{2,3} = b, w_{3,4} = c, w_{4,1} = d.$$



The invariant measure  $\nu$  is

$$\nu(\{1\}) = a + d, \quad \nu(\{2\}) = a + b, \quad \nu(\{3\}) = b + c, \quad \nu(\{4\}) = c + d.$$



$$m_3 = rac{b}{b+c}\delta_2 + rac{c}{b+c}\delta_4, \quad m_4 = rac{c}{c+d}\delta_3 + rac{d}{c+d}\delta_1.$$





We make the following partition on the random walk:

$$A_1 = \{4\}, \quad A_2 = \{3\}, \quad A_3 = \{2\}, \quad A_4 = \{1\}$$

and

$$B_1=\{2\}, \quad B_2=\{1\}, \quad B_3=\{4\}, \quad B_4=\{3\}.$$

This corresponds to the 1-Laplacian in the edges (1, 4) and (2, 3), and the Laplacian in the edges (1, 2) and (3, 4).

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#### Example

We now consider the equation

$$u_t - \Delta^m_{1,A}(u) - \Delta^m_{2,B}(u) \ni 0.$$

We denote

$$x(t) := u(t,1), \quad y(t) := u(t,2), \quad z(t) := u(t,3), \quad w(t) := u(t,4),$$

and see how the evolution differs from the previous case.

### Example

The equation then becomes the following ODE

$$\begin{cases} x'(t) = \frac{d}{a+d} \mathbf{g}_t(1,4) + \frac{a}{a+d} (y(t) - x(t)); \\ y'(t) = \frac{b}{a+b} \mathbf{g}_t(2,3) + \frac{b}{a+b} (x(t) - y(t)); \\ z'(t) = -\frac{b}{b+c} \mathbf{g}_t(2,3) + \frac{c}{b+c} (w(t) - z(t))); \\ w'(t) = -\frac{d}{c+d} \mathbf{g}_t(1,4) + \frac{c}{c+d} (z(t) - w(t)) \end{cases}$$

for antisymmetric functions  $\mathbf{g}_t$  satisfying

$$\mathbf{g}_t(1,4)\in \mathrm{sign}(w(t)-x(t)), \ \mathbf{g}_t(2,3)\in \mathrm{sign}(z(t)-y(t)).$$

We take equal weights a = b = c = d = 1 and the initial datum

$$x(0) = 2$$
,  $y(0) = 0$ ,  $z(0) = 1$ ,  $w(0) = 0$ .

### Example



Figure: x(t): continuous line; y(t): dashed line; z(t): dotted line; w(t): dashed-dotted line. Valid for  $0 \le t \le 0.510826$ .

#### Example



Figure: x(t): continuous line; y(t) = z(t): dotted line; w(t): dashed-dotted line. Valid for 0.510826  $\leq t \leq 1.32176$ .

### Example



Figure: x(t) = z(t): continuous line; y(t) = z(t): dotted line. Valid for  $t \gtrsim 1.32176$ .

### Example

There are two main differences with respect to the previous example:

 $\rightarrow$  The solution converges to the mean of the initial data, but has an infinite extinction time.

 $\rightarrow$  The graph effectively splits into two pieces; the sets {1,4} and {2,3}. The evolution within them is primarily governed by the 1-Laplacian (and has a finite extinction time within the smaller set).

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 $\rightarrow$  The graph effectively splits into two pieces; the sets  $\{1,4\}$  and  $\{2,3\}.$  The evolution within them is primarily governed by the 1-Laplacian (and has a finite extinction time within the smaller set).

Due to the fact that the partition of the random walk in general bears no relation to the invariant measure, validity of a Poincaré inequality in this setting does not imply finite extinction time.