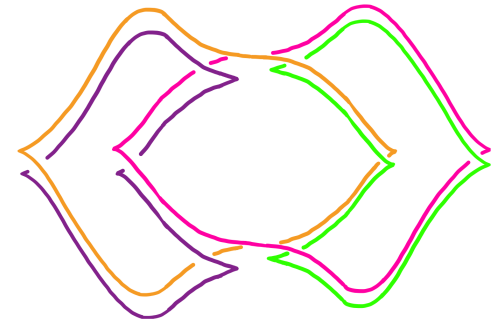
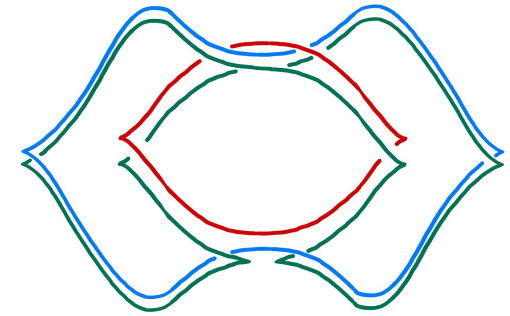


KIRBY'S THEOREM FOR CONTACT 3-MANIFOLDS

VERA VÉRTESI

JOINT WORK W/

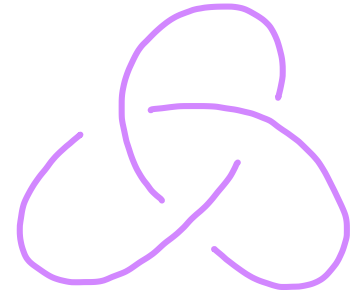
M. KEGEL, E. STENHEDE & D. ZUDDAS



KIRBY'S THM FOR SMOOTH 3-MANIFOLDS

- SURGERY ON KNOTS:

- GIVEN $K \hookrightarrow S^3$

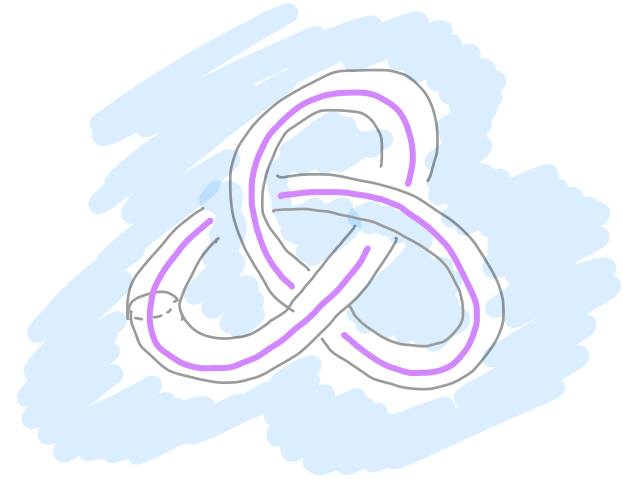


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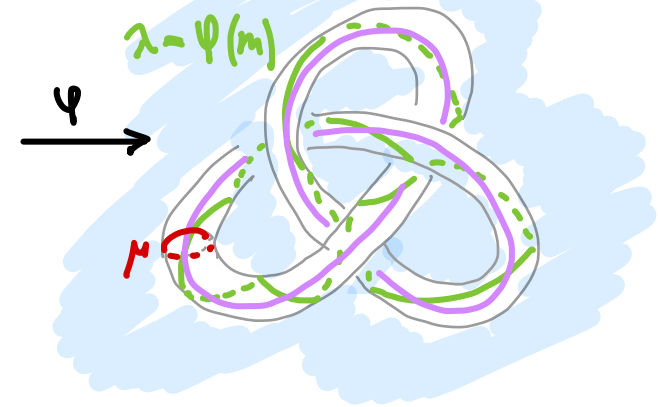
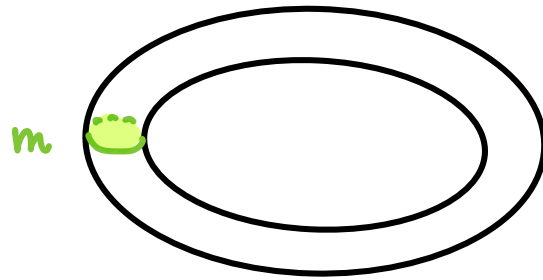
- $X := S^3 - N(K)$



KIRBY'S THM FOR SMOOTH 3-MANIFOLDS

• SURGERY ON KNOTS:

- GIVEN $K \hookrightarrow S^3$
- $X := S^3 - N(K)$
- GLUE A $D^2 \times S^1$ DIFFERENTLY
ALONG $\psi: \partial(D^2 \times S^1) \longrightarrow \partial X$



$$\leadsto M = S^3 - N(K) \cup_{\psi} (D^2 \times S^1) = S^3_{\lambda}(K)$$

M IS DETERMINED BY $\lambda = \psi(m)$: A FRAMING OF K

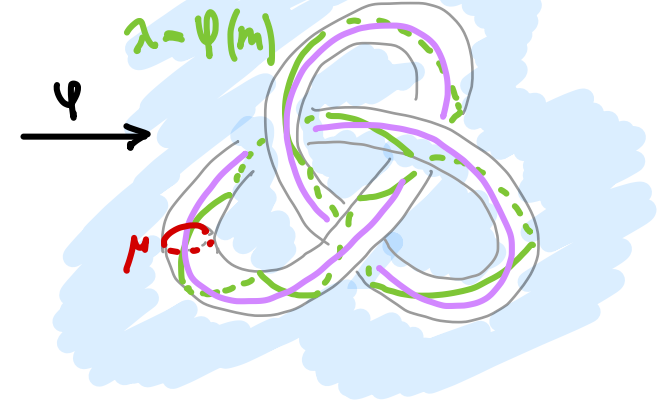
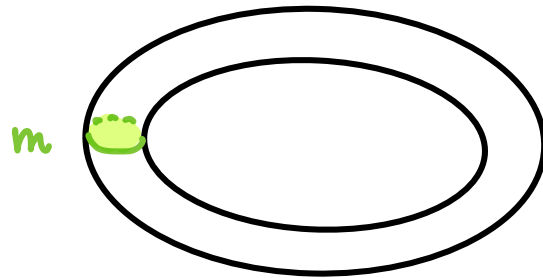
WE OFTEN COMPARE λ TO THE SEIFERT FRAMING ℓ OF K

$$\lambda = \ell + n\mu \leadsto S^3_n(K) = S^3_{\lambda}(K)$$

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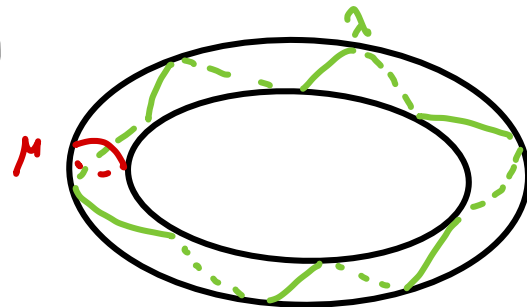
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E.G.: • $S^3_p(\mu) = L(1, -p)$



• $S^3_{\pm}(\mu) = S^3$

KIRBY'S THM FOR SMOOTH 3-MANIFOLDS

WE CAN DO SURGERY ON FRAMED LINKS $L \subset S^3$



IN FACT ANY 3-MFD CAN BE OBTAINED THIS WAY :

THM (LICKORISH '62, WALLACE '60): ANY CLOSED, CONNECTED, ORIENTED, SMOOTH 3-MANIFOLD M^3 IS OBTAINED VIA SURGERY ALONG A FRAMED LINK $L \subset S^3$

KIRBY'S THM FOR SMOOTH 3-MANIFOLDS

HOW MANY DIFFERENT WAYS CAN WE GET THE SAME M ?

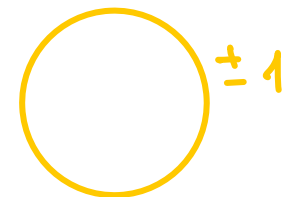


M

BLOW UP
→



$M \# S^3 \cong M$



KIRBY'S THM FOR SMOOTH 3-MANIFOLDS

HOW MANY DIFFERENT WAYS CAN WE GET THE SAME M ?



M

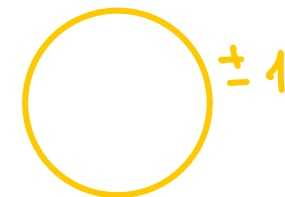
BLOW UP



BLOW
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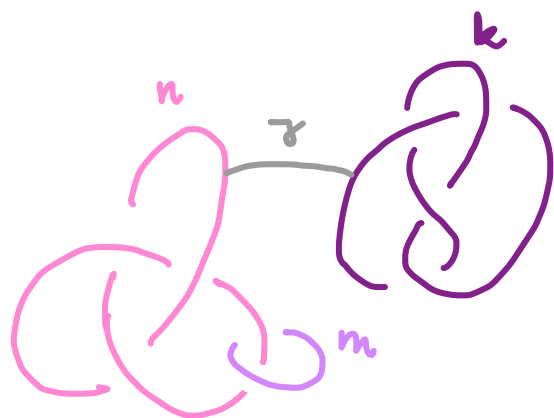
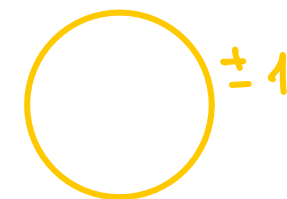
BLOW UP



BLOW DOWN



$M \# S^3 \cong M$



HANDLE-SLIDE



KIRBY'S THM FOR SMOOTH 3-MANIFOLDS

THM (KIRBY '78): SURGERY ALONG THE FRAMED LINKS $\mathbb{L}$ & $\mathbb{L}'$ CS^3 GIVE
DIFFEOMORPHIC MANIFOLDS IFF $\mathbb{L}$ & $\mathbb{L}'$ ARE RELATED VIA

- BLOW UPS & BLOW DOWNS
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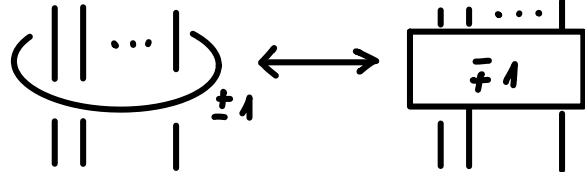
THESE MOVES ARE NOT LOCAL

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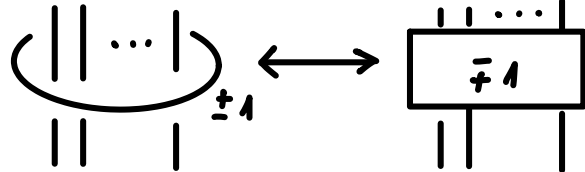
STILL NOT FINITE

KIRBY'S THM FOR SMOOTH 3-MANIFOLDS

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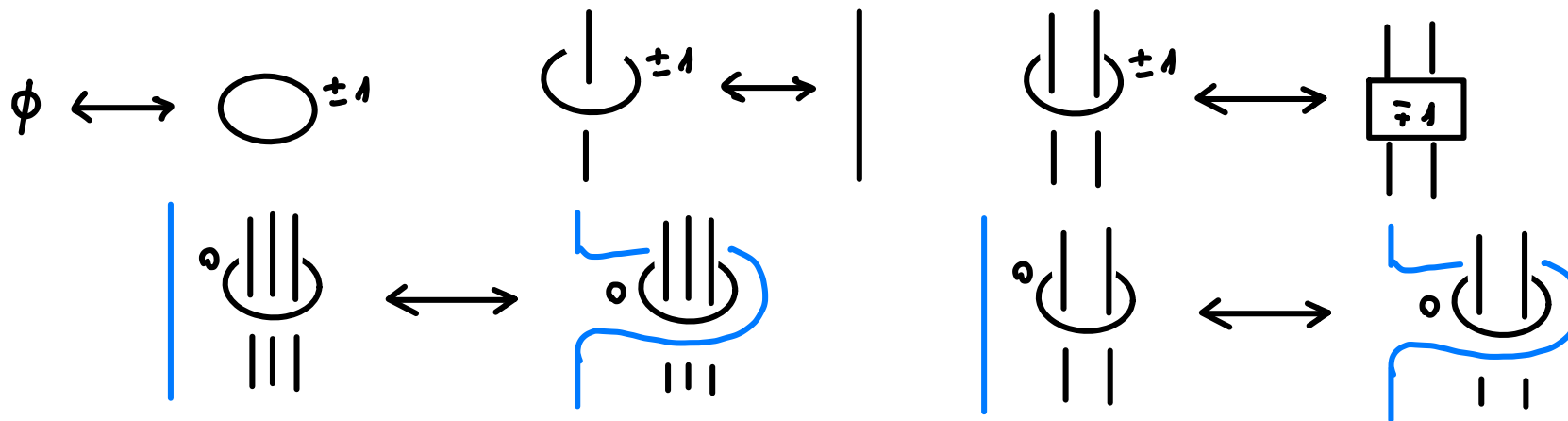
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THM (FENN-ROUKE '79): THE MOVES  ARE ENOUGH.

STILL NOT FINITE

THM (MARTELLI '11): THE FOLLOWING MOVES SUFFICE:



APPLICATION OF KIRBY'S THEOREM

BASICALLY EVERYWHERE IN LOW DIMENSIONAL TOPOLOGY

(179 CITATIONS)

MOST IMPORTANT 3D APPLICATIONS

- CASSON '86: THE "CASSON INVARIANT" IS AN INTEGRAL LIFT OF THE ARF INVARIANT
- RESHETIKHIN - TURAEV '91: 3-MANIFOLD INVARIANT

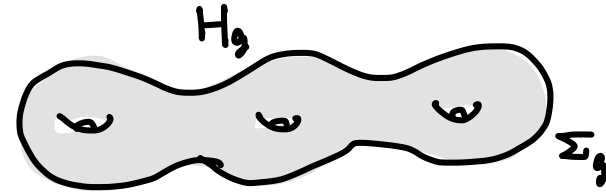
~ TOPOLOGICAL QUANTUM FIELD THEORY

THM (LICKORISH '62, WALLACE '60): ANY CLOSED, CONNECTED, ORIENTED, SMOOTH 3-MANIFOLD M^3 IS OBTAINED VIA SURGERY ALONG A FRAMED LINK $\mathbb{L} \subset S^3$

IDEA OF PROOF:

• HEEGAARD SPLITTING:

$M = U \cup_{\Sigma} V$ ← HANDLEBODY

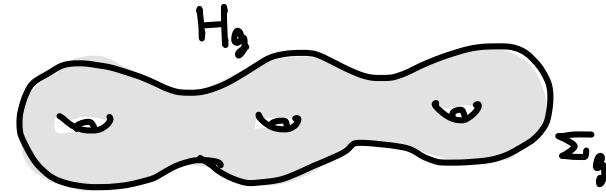


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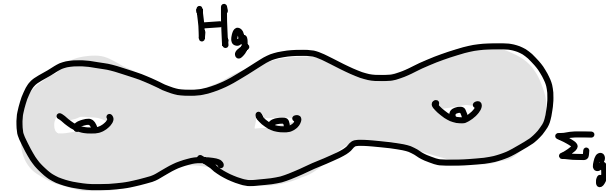


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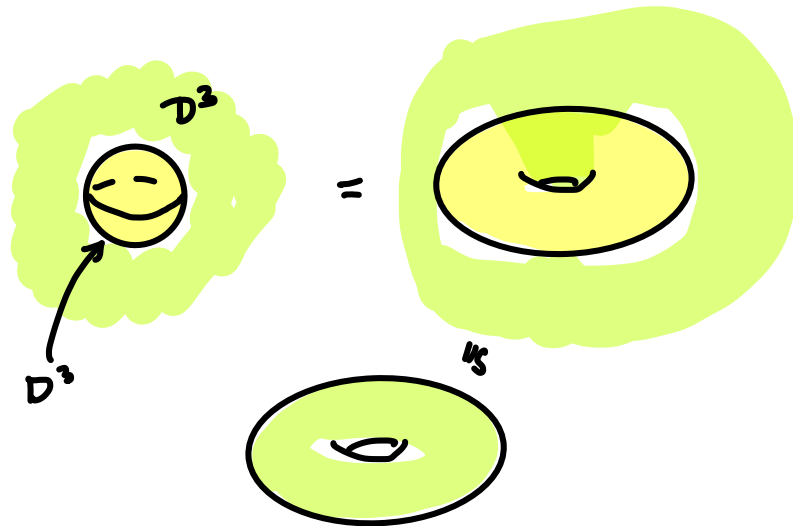
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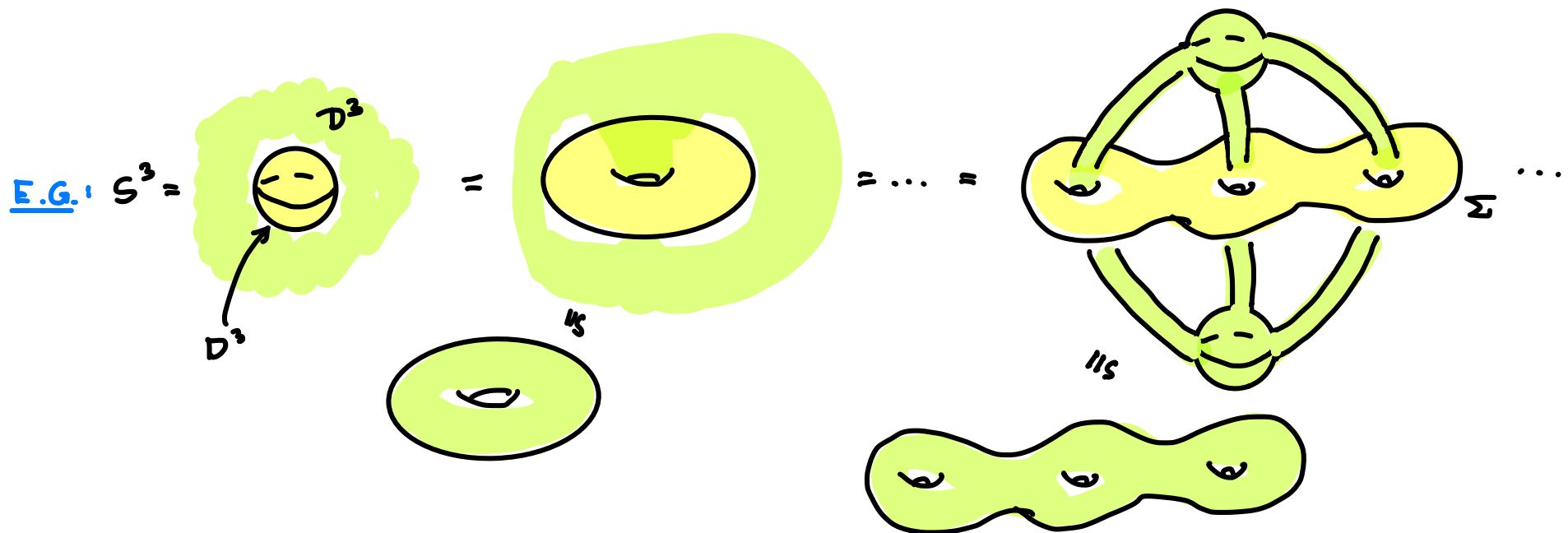
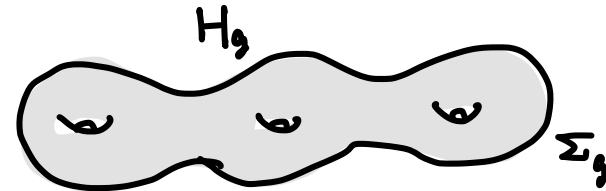


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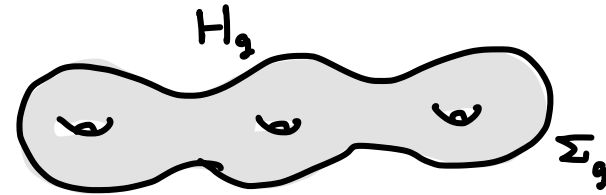
STANDARD HEEGAARD SPLITTING OF S^3 w/ GENUS g

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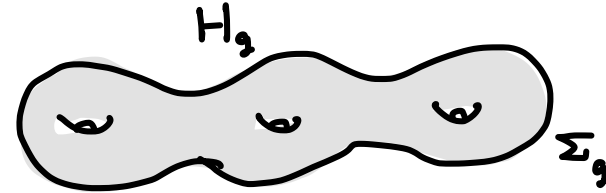
WE CAN THINK OF A HS AS $H_g \cup_{\psi} H_g$ GLUED ALONG $\psi: \Sigma_g \rightarrow \Sigma_g$

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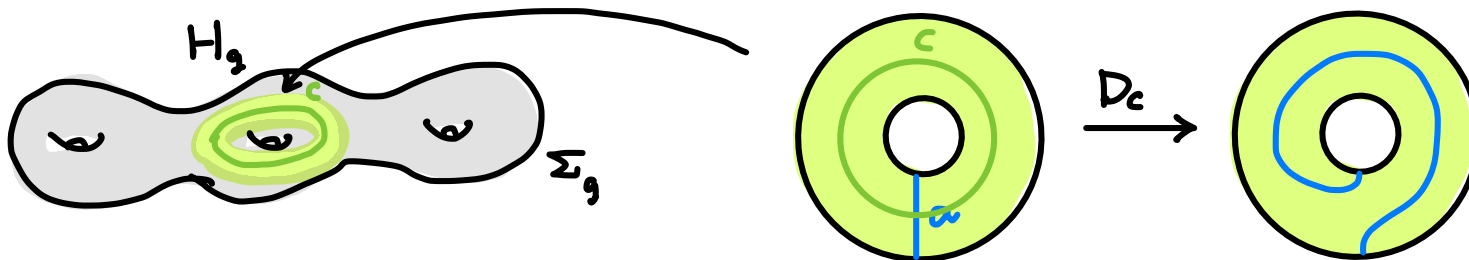
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- MAPPING CLASS GROUP: $MCG(\Sigma_g) = \{ \Psi: \Sigma_g \rightarrow \Sigma_g \} / \text{ISOTOPY}$

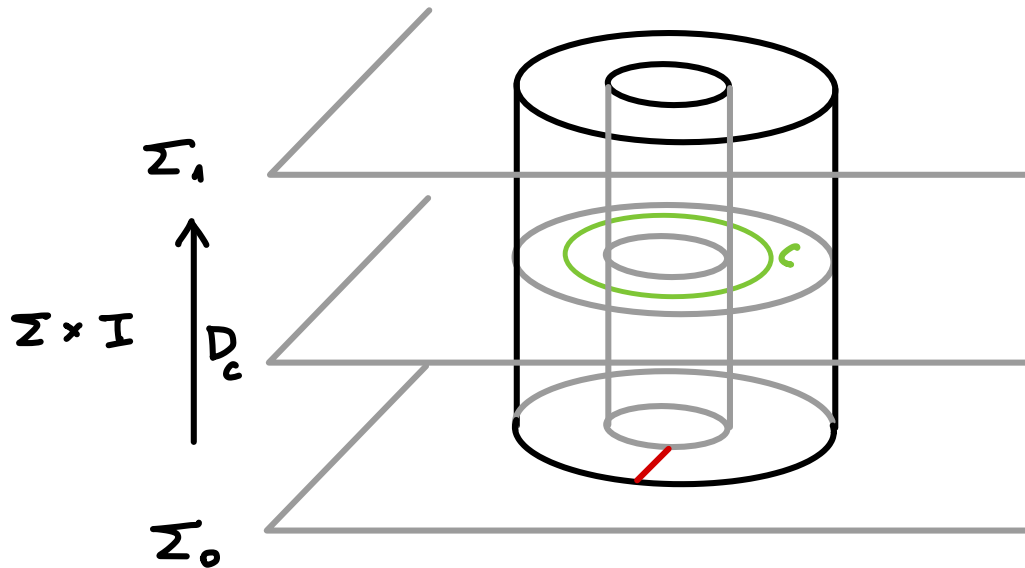
GENERATED BY DEHN TWISTS ALONG SIMPLE CLOSED CURVES



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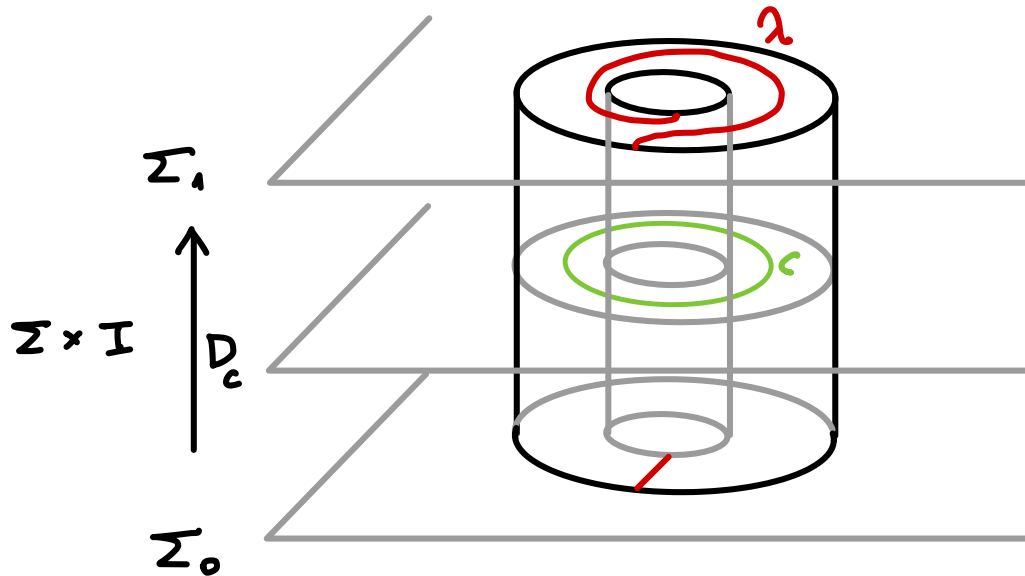
- NOTE: CONNECTION BTWN DEHN TWIST & SURGERY



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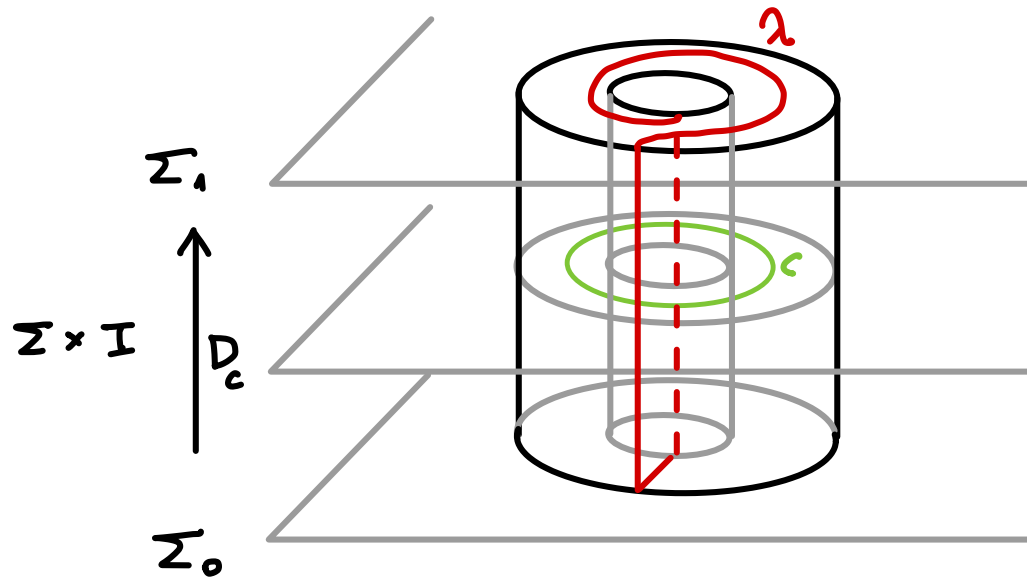
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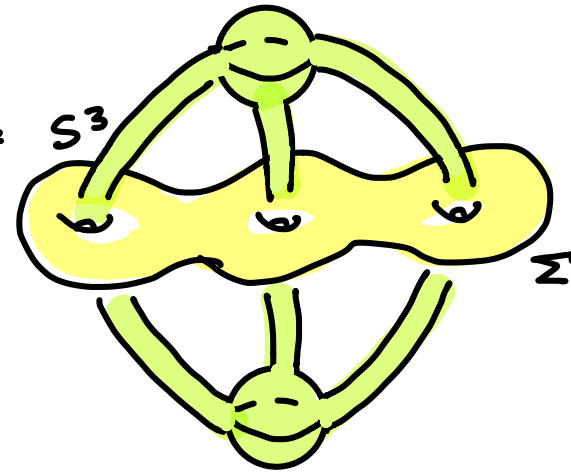


$\leadsto D_c \longleftrightarrow$ SURGERY ALONG c W/ FRAMING λ

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IDEA OF PROOF:

- TAKE A HS OF M : $M = H_g U_\psi H_g$
- TAKE THE STANDARD GENUS g HS OF S^3



OR $S^3 = H_g U_{\psi_0} H_g$

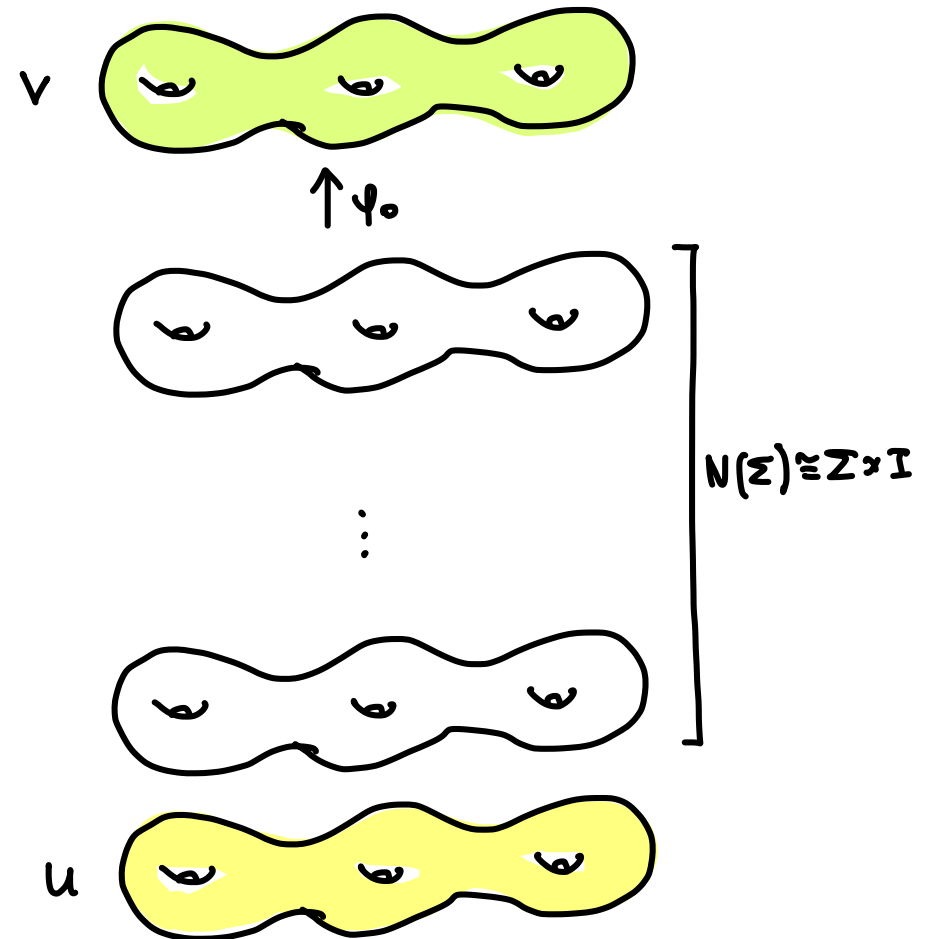
- DECOMPOSE $\psi \circ \psi_0^{-1} = D_{c_1} \circ \dots \circ D_{c_n}$ AS PRODUCT OF DEHN TWISTS

THM (LICKORISH '62, WALLACE '60): ANY CLOSED, CONNECTED, ORIENTED, SMOOTH 3-MANIFOLD M^3 IS OBTAINED VIA SURGERY ALONG A FRAMED LINK $L \subset S^3$

IDEA OF PROOF:

- $M = H_g \cup_{\psi} H_g$
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S^3

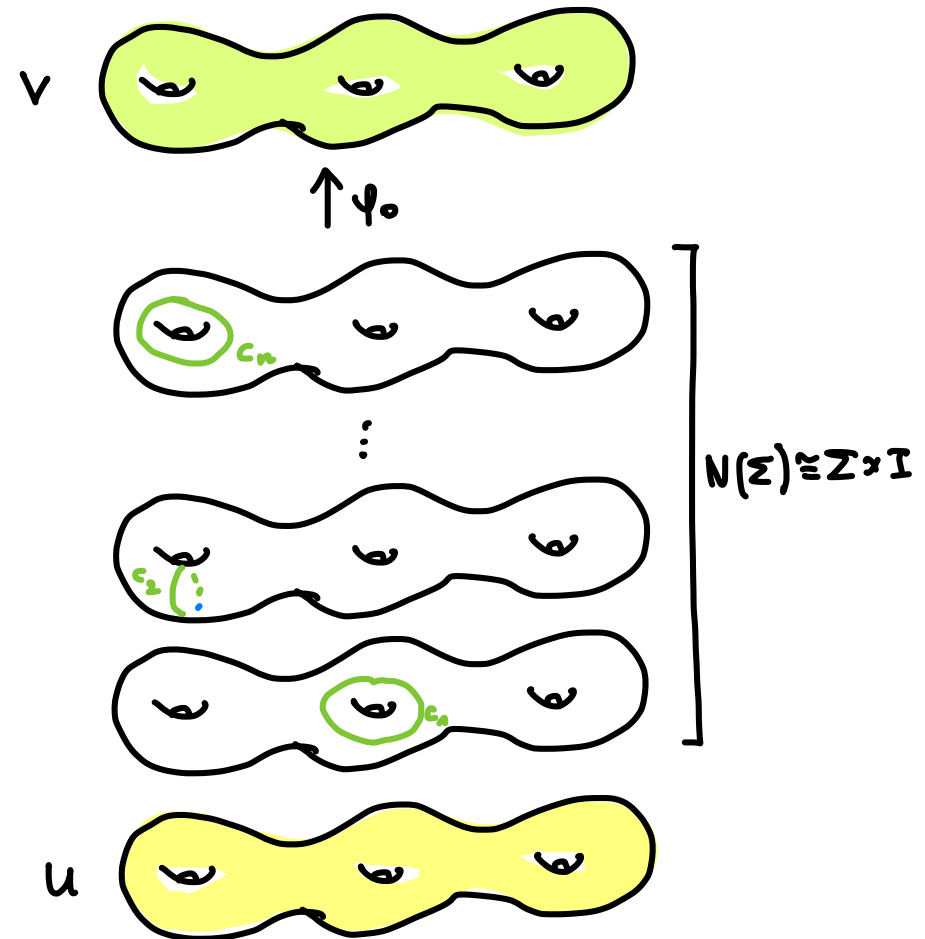
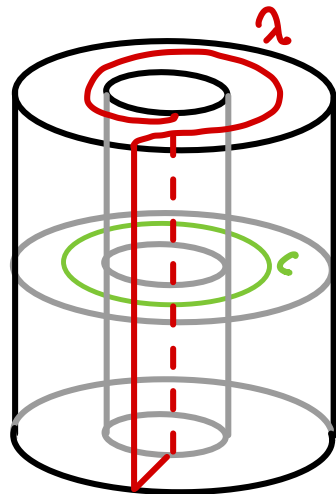


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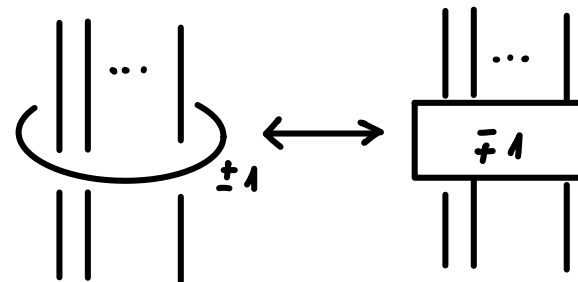
- $M = H_g \cup_{\psi} H_g$
- $\psi \circ \psi_0^{-1} = D_{c_1} \circ \dots \circ D_{c_n}$
- EMBED $c_i \hookrightarrow \mathbb{Z} \times \frac{i}{n} \subseteq N(\Sigma) : \mathbb{L}$

$\leadsto M$ IS OBTAINED VIA SURGERY
ALONG THE FRAMED LINK $\mathbb{L}$



QED

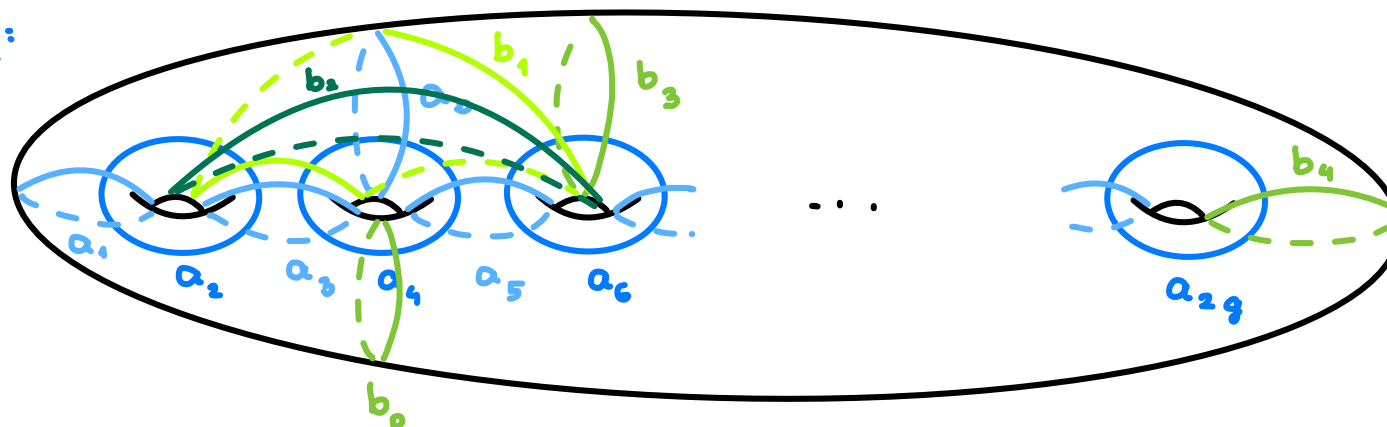
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 DIFFEOMORPHIC MANIFOLDS IFF
 $\mathbb{L}$ & $\mathbb{L}'$ ARE RELATED VIA



IDEA OF PROOF (N. LU '95)

• PRESENTATION OF $MC G(\Sigma)$ (HATCHER - THURSTON - WATNRYB '83)

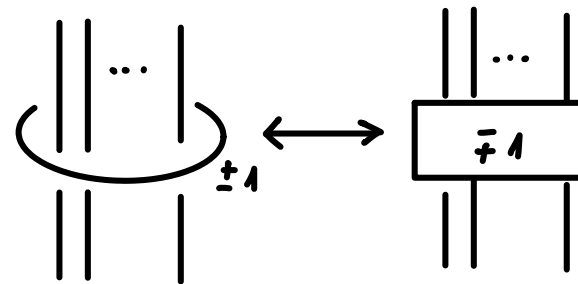
GENERATORS:



RELATIONS:

- $a_i a_j = a_j a_i$ IF $a_i \cap a_j = \emptyset$
 - $a_i a_j a_i = a_j a_i a_i$ IF $\# a_i \cap a_j = 1$
 - $a_0 b_0 = (a_1 a_2 a_3)^4$
 - $a_0 b_1 b_2 = a_1 a_3 a_5 b_3$
 - $b_4 = w b_4 w^{-1}$
 - $b_i = w' a_0 w'^{-1}$
- w & w' SOME WORDS IN a_i

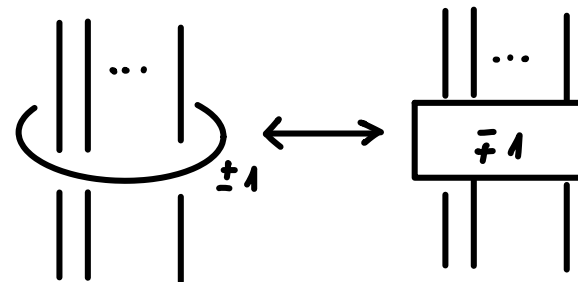
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IDEA OF PROOF (N. LU '95)

- EMBED $\mathbb{L}$ & $\mathbb{L}'$ INTO A STANDARD HS OF S^3 AS IN THE
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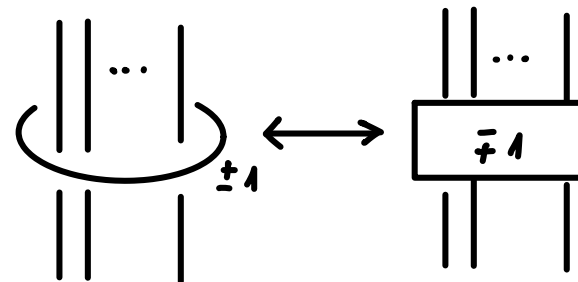


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- EMBED $\mathbb{L}$ & $\mathbb{L}'$ INTO A STANDARD HS OF S^3 AS IN THE PROOF OF LICKORISH-WALLACE (NEED TO BLOW-UP!)
- STABILISE THE HS'S TO HAVE THE SAME GENUS (BLOW-UP!)

$$\begin{array}{c} \mathbb{L} \rightsquigarrow D_{c_1} \circ \dots \circ D_{c_n} \\ \parallel \longleftarrow \text{IN } \text{MCG}(\Sigma) \\ \mathbb{L}' \rightsquigarrow D_{c'_1} \circ \dots \circ D_{c'_m} \end{array}$$

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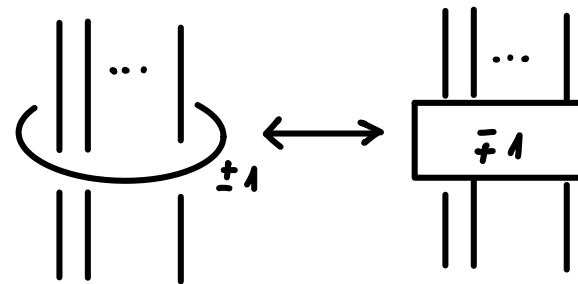


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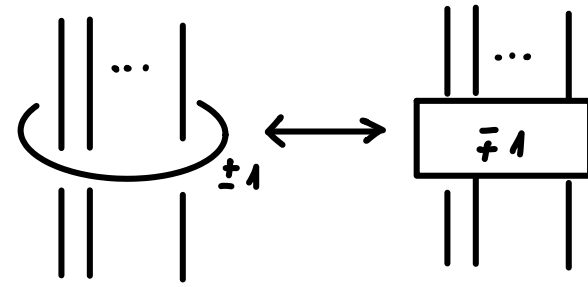


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- EACH RELATION CORRESPONDS TO BLOW-UPS

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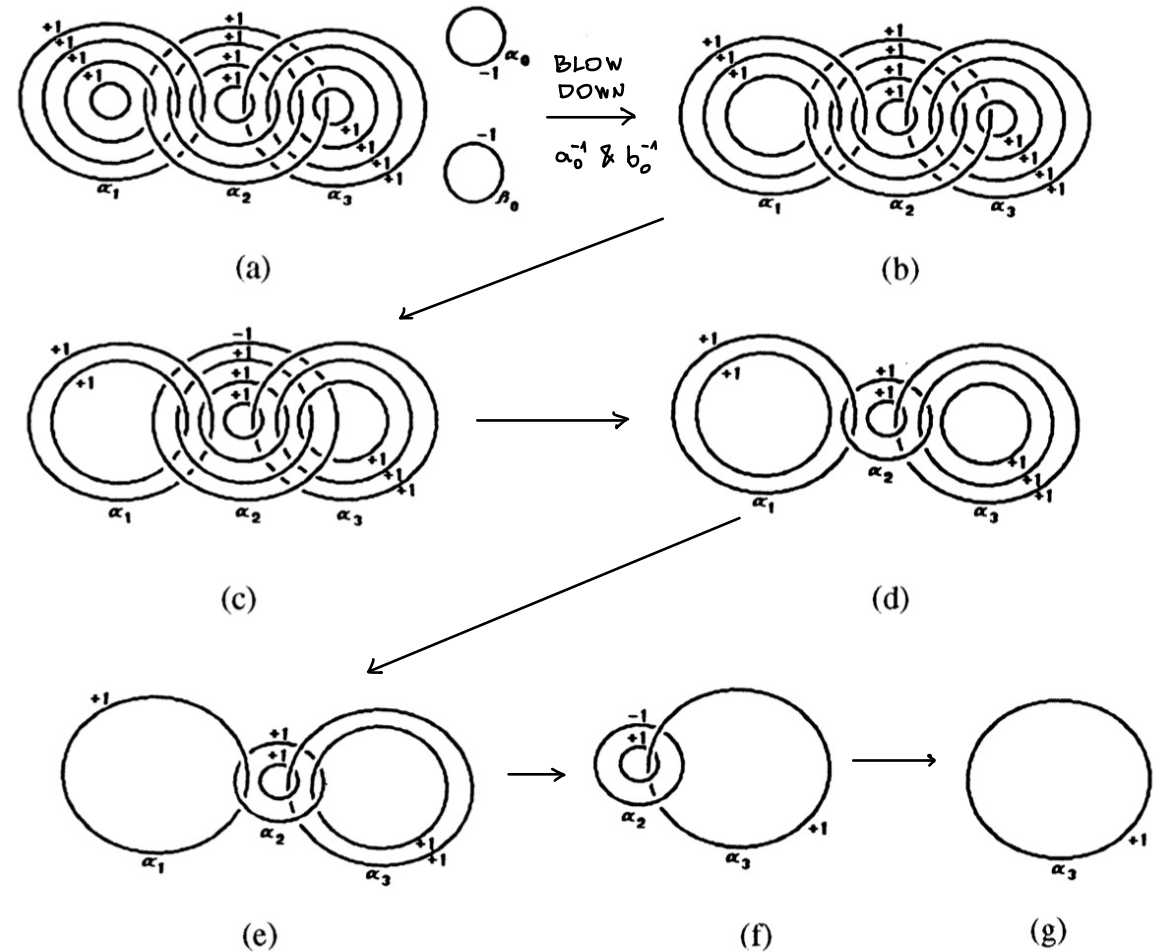
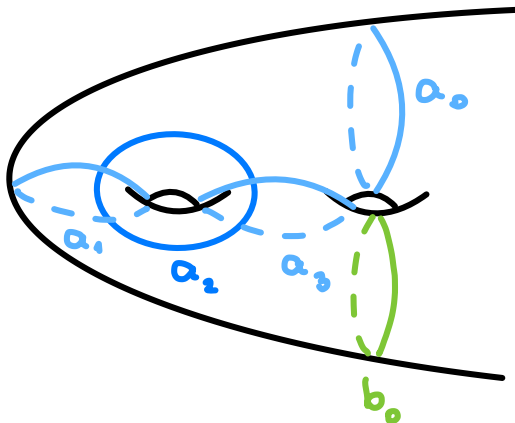
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EACH RELATION CORRESPONDS
 TO **BLOW-UPS**

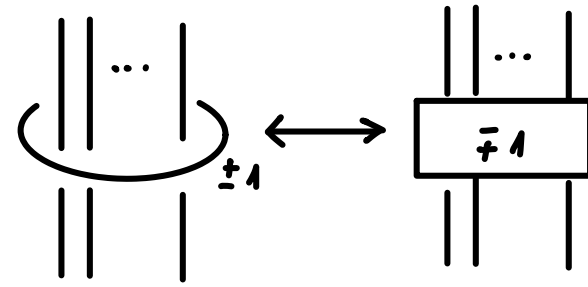
E.G.:

$$a_0 b_0 = (a_1 a_2 a_3)^4$$

WHERE



THM (KIRBY '78): SURGERY ALONG THE
 FRAMED LINKS $\mathbb{L}$ & $\mathbb{L}'$ CS^3 GIVE
 DIFFEOMORPHIC MANIFOLDS IFF
 $\mathbb{L}$ & $\mathbb{L}'$ ARE RELATED VIA



IDEA OF PROOF (N. LU '95)

- EMBED $\mathbb{L}$ & $\mathbb{L}'$ INTO A STANDARD HS OF S^3 AS IN THE PROOF OF LICKORISH-WALLACE (NEED TO BLOW-UP!)
- STABILISE THE HS'S TO HAVE THE SAME GENUS (BLOW-UP!)

$$\begin{array}{ccc} \mathbb{L} \rightsquigarrow D_{c_1} \circ \dots \circ D_{c_n} & & \\ \parallel \longleftarrow \text{IN } \text{MCG}(\Sigma) & & \\ \mathbb{L}' \rightsquigarrow D_{c'_1} \circ \dots \circ D_{c'_m} & & \end{array}$$
- EXCHANGE THE DEHN TWISTS TO THE GENERATORS OF $\text{MCG}(\Sigma)$ (BLOW-UP!) $\Rightarrow$ RELATED BY THE RELATIONS
- EACH RELATION CORRESPONDS TO BLOW-UPS ✓

QED

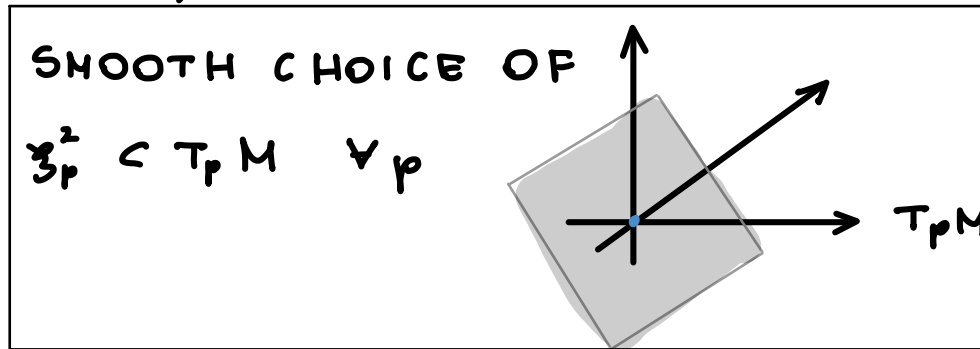
GOAL: GENERALISE
THESE
FOR
CONTACT
STRUCTURES

CONTACT STRUCTURES

DEF: A CONTACT STRUCTURE ON A CLOSED, ORIENTED SMOOTH
3-MANIFOLD M^3 IS A TOTALLY NONINTEGRABLE
2-PLANE-DISTRIBUTION $\xi \subset TM$

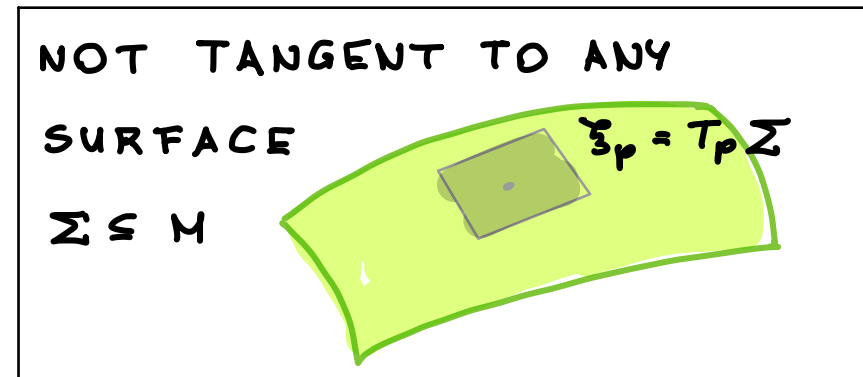
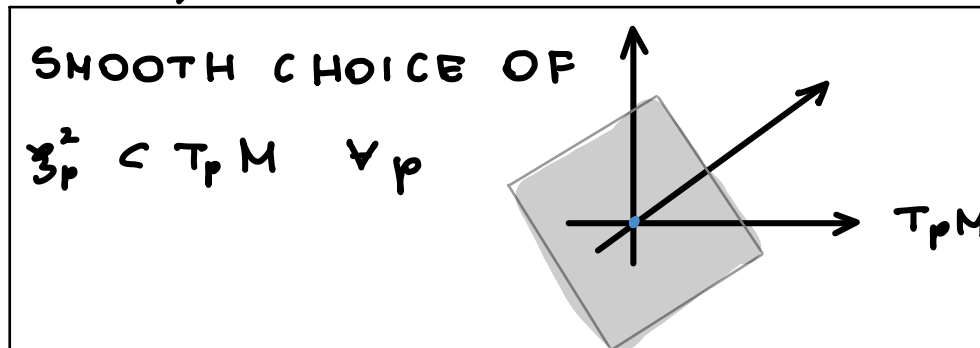
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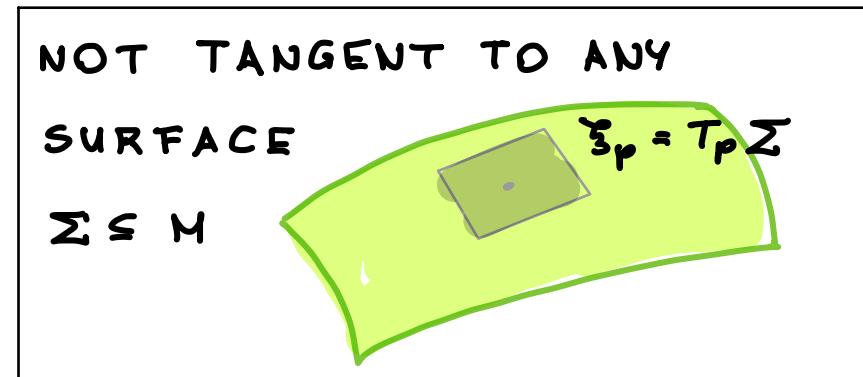
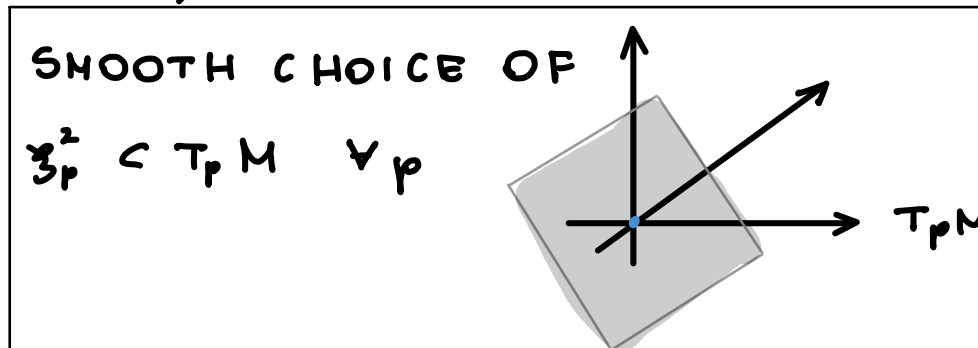


$\updownarrow$ FROBENIUS

$$\alpha \wedge d\alpha > 0$$

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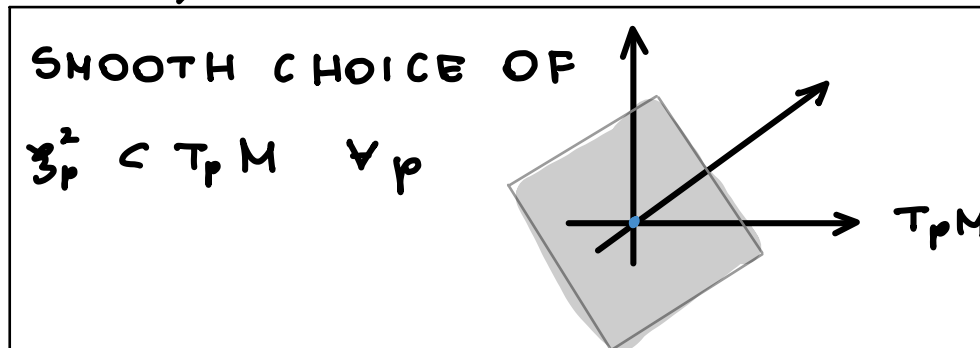
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LOCALLY: $\xi = \ker \alpha \quad \alpha \in \Omega^1(M)$

COORIENTED CONTACT STRUCTURE: GLOBAL α

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NOT TANGENT TO ANY SURFACE $\Sigma \subseteq M$

$\xi_p = T_p \Sigma$

A green curved surface Σ is shown. A small gray square representing a 2D plane is drawn on the surface. A vector ξ_p is shown originating from a point p on the surface and lying within the plane. The plane is labeled $T_p \Sigma$.

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$$\alpha \wedge d\alpha > 0$$

LOCALLY: $\xi = \ker \alpha \quad \alpha \in \Omega^1(M)$

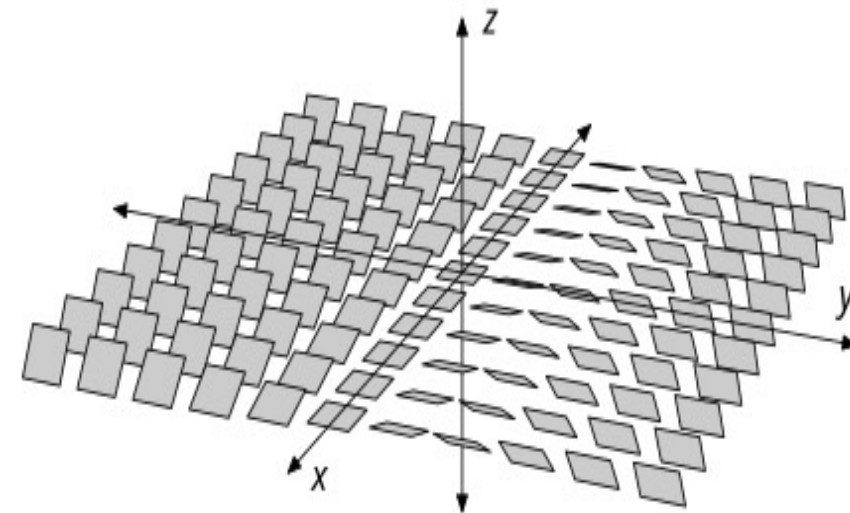
COORIENTED CONTACT STRUCTURE: GLOBAL α

DARBOUX THM: LOCALLY ANY CONTACT

STRUCTURE IS CONTACTOMORPHIC

TO $\mathbb{R}^3$, $\xi_{st} = \ker(dz - ydx)$

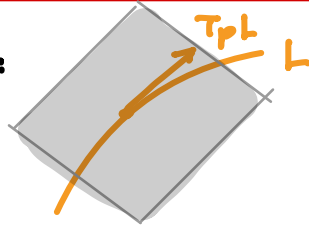
DIFFEOMORPHISM THAT CARRIES ξ TO ξ'



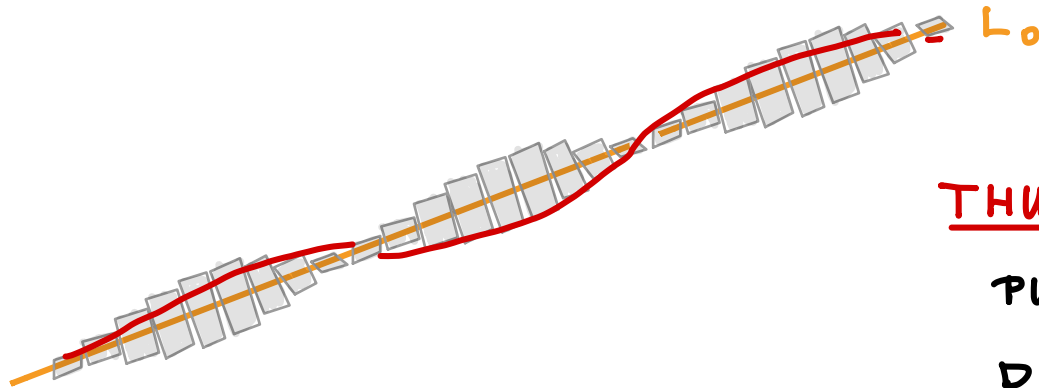
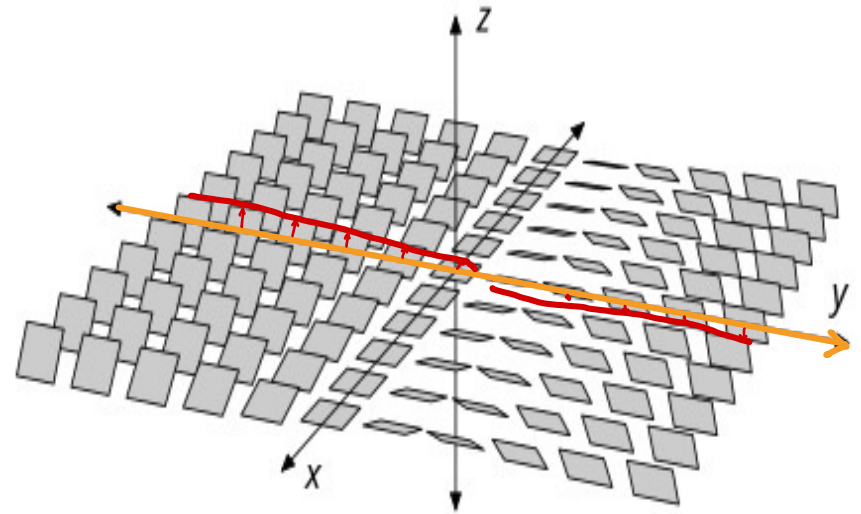
KNOTS IN CONTACT STRUCTURES

DEF: $L \subset M$ IS A LEGENDRIAN KNOT

IF $T_p L \subset \xi_p \quad \forall p:$



MOTTO: THE CONTACT STRUCTURE
ALWAYS "ROTATES"
ALONG LEGENDRIANS

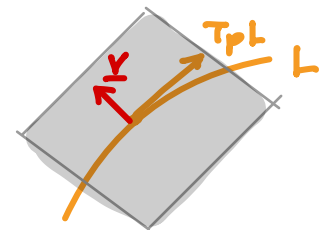


THURSTON-BENNEQUIN FRAMING:

PUSH L IN THE

DIRECTION OF $\underline{y}$

WHERE $\underline{y}_p \perp T_p L$ & $\underline{y}_p \in \xi_p$

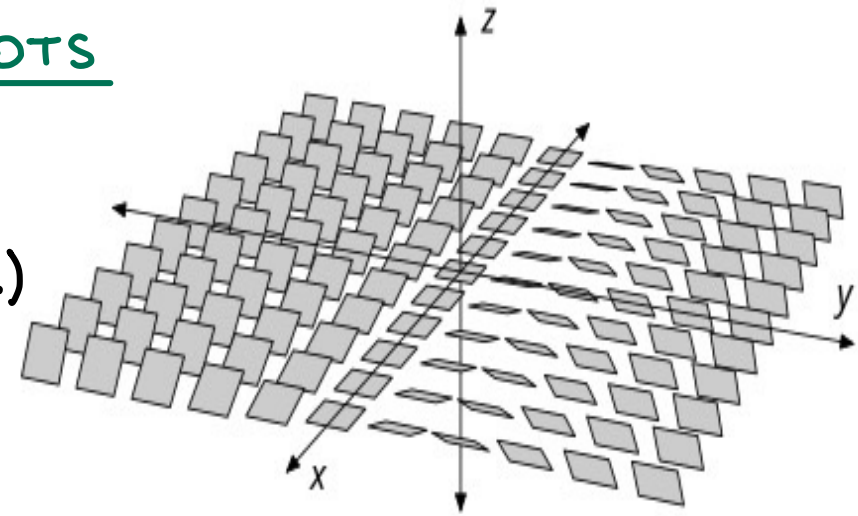
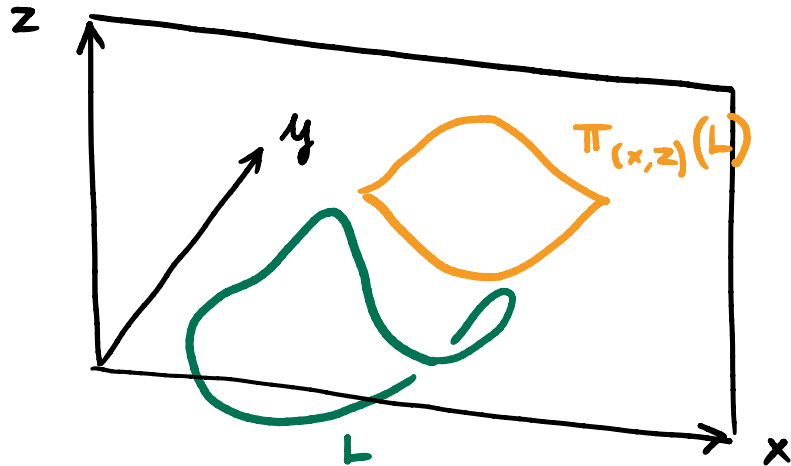


THM: ANY LEGENDRIAN KNOT $L \subset (M, \xi)$ HAS A NEIGHBOURHOOD $N(L)$
CONTACTOMORPHIC TO $N(L_0)$

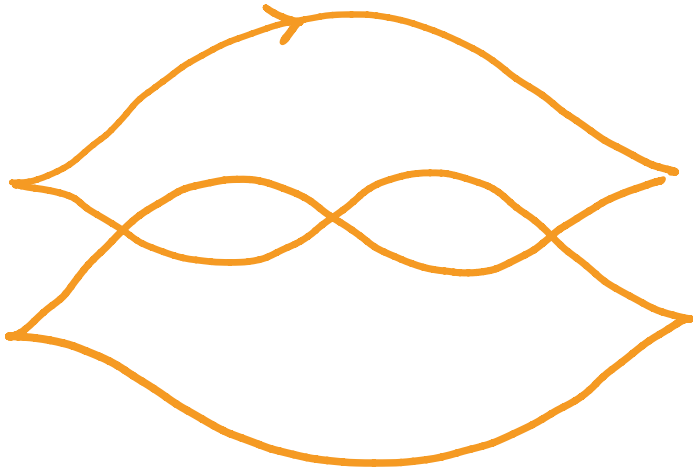
FRONT PROJECTION OF LEGENDRIAN KNOTS

L LEGENDRIAN IN $(\mathbb{R}^3, \xi_{st}) \Leftrightarrow y = \frac{dz}{dx}$

SO: y CAN BE RECOVERED FROM $\pi_{(x,z)}(L)$



$$\xi_{st} = \ker(dz - y dx)$$

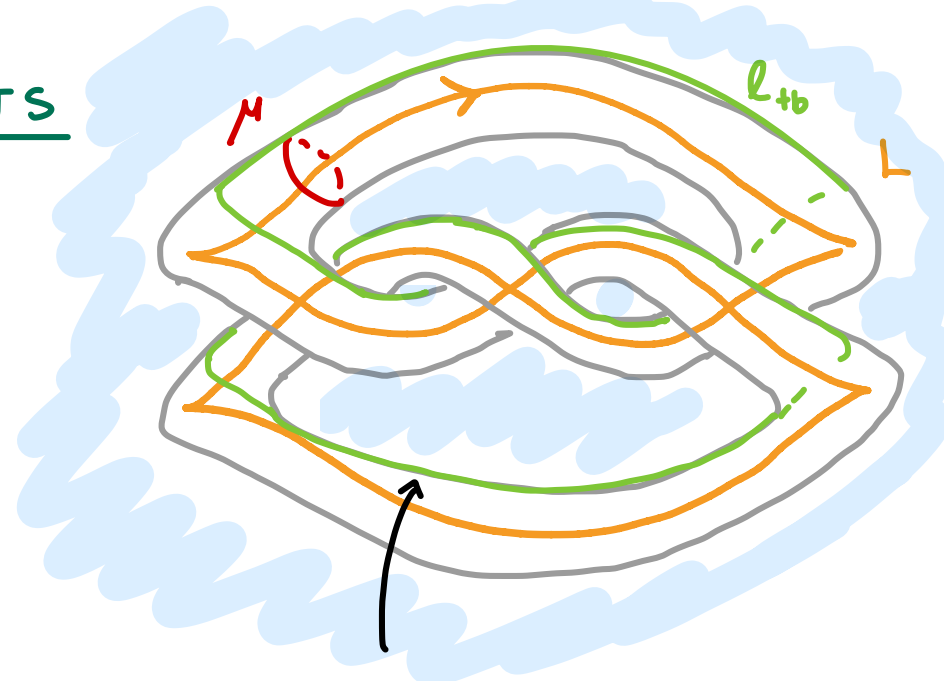


SURGERY ALONG LEGENDRIAN KNOTS

- GIVEN $L \hookrightarrow (S^3, \xi_{st})$ LEG KNOT
- $X := S^3 - \gamma(K) \leftarrow$ STANDARD NBHD

$$\leadsto S^3_{\pm}(L) = X \cup_{\psi} (D^2 \times S^1)$$

$$\text{WHERE } \psi(m) = \ell_{\pm b} \pm \mu$$



THURSTON-BENNEQUIN FR

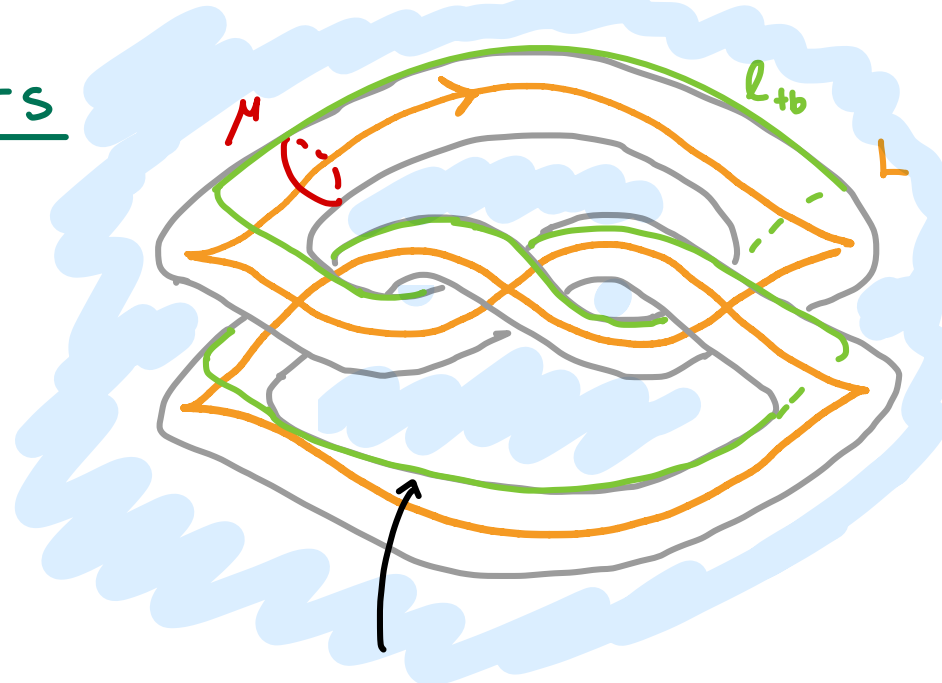
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FACT: THERE IS A UNIQUE
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THURSTON-BENNEQUIN FR

SURGERY ALONG LEGENDRIAN KNOTS

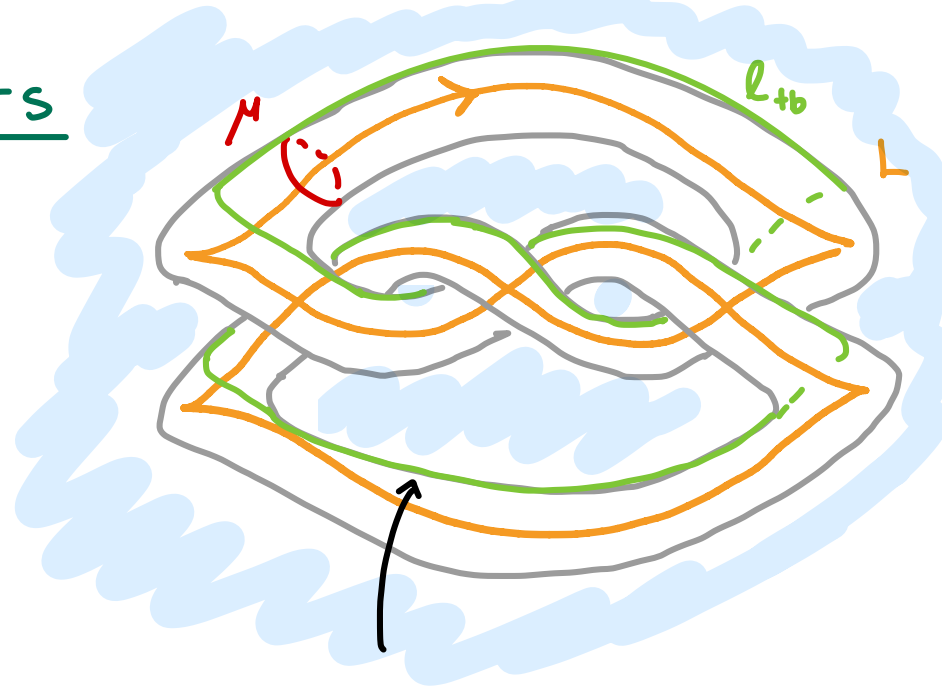
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THM (DING - GEIGES '04) ANY CONTACT 3-MANIFOLD (M, ξ)
CAN BE OBTAINED FROM (S^3, ξ_{st}) VIA ± 1 SURGERY
ALONG A LEGENDRIAN LINK $\mathcal{L} \hookrightarrow (S^3, \xi_{st})$

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IDEA OF PROOF:

• OPEN BOOK DECOMPOSITION

PAIR (B, π) , WHERE

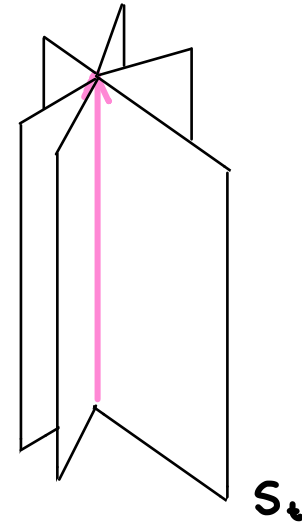
- $B \hookrightarrow M$ EMBEDDED 1-MANIFOLD: BINDING

- $\pi: M - B \longrightarrow S^1$ FIBRATION SUCH THAT

$\rightarrow \forall t \in S^1 \quad S_t := \overline{\pi^{-1}(t)}$ IS A SEIFERT SURFACE FOR B

$\rightarrow \& \text{ ON } N(B) \cong B \times D^2 \quad \pi = \text{ANGLE}$

$S_t := \pi^{-1}(t)$ ARE THE PAGES OF (B, π)



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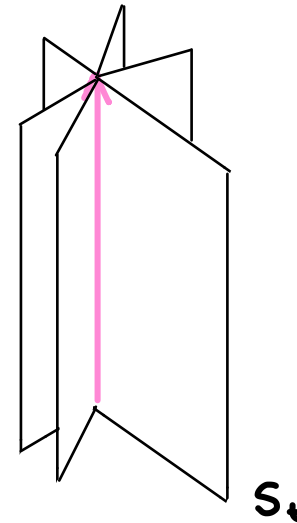
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• (B, π) COMPATIBLE WITH $(M, \xi = \ker(\alpha))$

- $\alpha(B) > 0$

- $d\alpha|_{S_t} > 0$

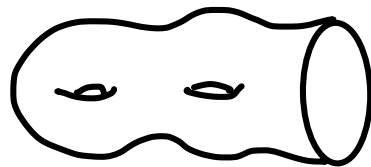
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IDEA OF PROOF:

• OPEN BOOK DECOMPOSITION

WE CAN THINK OF AN OB VIA ITS FIRST RETURN MAP (S, ψ)

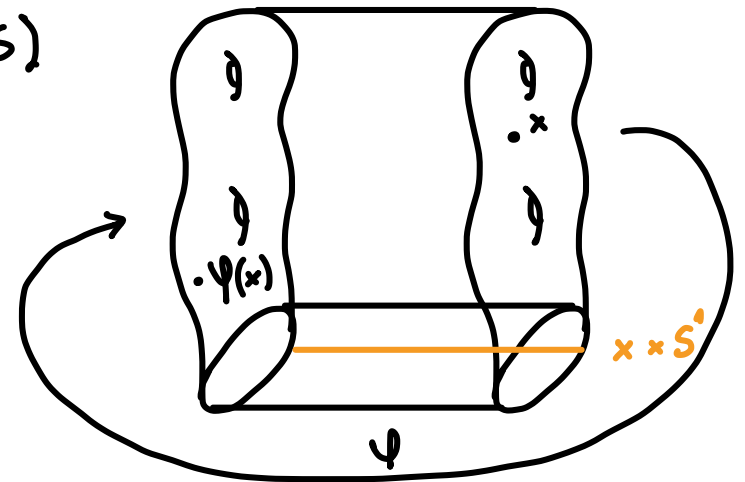
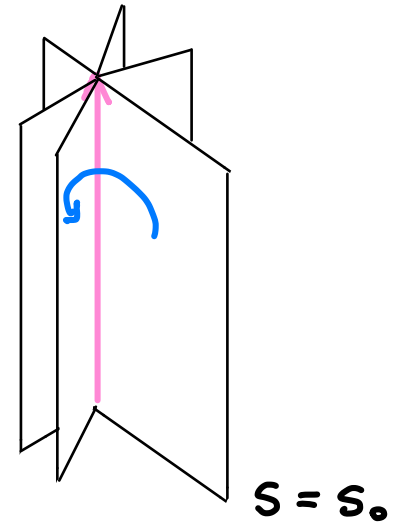
SURFACE W/ ∂



MONODROMY

$\in \text{MCG}(S)$

$$M \cong \frac{S \times I}{\begin{array}{l} (x, 1) \sim (\psi(x), 0) \\ (x, t) \sim (x, t') \quad x \in \partial S \end{array}}$$



• $\text{MCG}(S)$ IS STILL GENERATED BY DEHN TWISTS ALONG S.C.C.S

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 ALONG A LEGENDRIAN LINK $\mathcal{L} \hookrightarrow (S^3, \xi_{st})$

IDEA OF PROOF: SIMILAR TO SMOOTH CASE

- $M \leadsto (S, \psi)$ OB
- TAKE AN OB W/ PAGE S FOR S^3 : (S, ψ_0)
- WRITE $\psi \circ \psi_0^{-1} = D_{c_1} \circ \dots \circ D_{c_n}$, WHERE c_i IS NONSEPARATING ON S
 $\Rightarrow$ CAN EMBED c_i ON $S_{\frac{i}{n}} \subseteq S^3$ AS A LEGENDRIAN: $\mathcal{L}$
 (S.T. $S_{\frac{i}{n}}$ GIVES THE THURSTON - BENNEQUIN FRAMING FOR c_i)
- $\leadsto (M, \xi)$ IS OBTAINED VIA CONTACT SURGERY ALONG $\mathcal{L}$

QED

EARLIER RESULTS

MOVES THAT DON'T CHANGE (M, χ)

- DING - GEIGES '01: CANCELLATION
- DING - GEIGES '09: CONTACT HANDLE SLIDE
CONTACT ANNULUS TWIST
- LISCA - STIPSICZ '11: LANTERN DESTABILISATION
- CASALS - ETNYRE - KEGEL: CONTACT ROLFSEN TWIST
- AVDEK '13: RIBBON MOVES

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THM (AVDEK '13) ± 1 -SURGERY ALONG THE LEGENDRIAN LINKS
 $\mathcal{L} \# \mathcal{L}' \hookrightarrow (S^3, \xi_{\pm 1})$ GIVE CONTACTOMORPHIC CONTACT MANIFOLDS
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IFF $\mathcal{L} \ \& \ \mathcal{L}'$ ARE RELATED VIA RIBBON MOVES

BUT! RIBBON MOVES CAN BE ARBITRARILY COMPLICATED
& CANNOT BE RECOGNISED

TOWARDS A CONTACT KIRBY'S THEOREM

THE STRATEGY FROM THE SMOOTH CASE DOESN'T EASILY GENERALISE:

PROBLEMS:

1) THERE IS NO CONTACT BLOW UP

(THIS WAS KEY IN ALL THE SMOOTH STEPS)

2) THERE IS **NO** UNIQUE OB. OF (S^3, ξ_{st}) FOR A GIVEN PAGE-TYPE

3) ONLY NONSEPARATING CURVES ON S GIVE LEGENDRIANS

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WE STRUGGLED THE MOST W/ 3, EVEN THOUGH THE

SOLUTION ALREADY EXISTED HIDDEN IN A '96 PAPER

TOWARDS A CONTACT KIRBY'S THEOREM

- PRESENTATION OF $NCG(S)$ (GERVAIS '96)

GENERATORS: DEHN TWISTS ALONG NONSEPARATING CURVES

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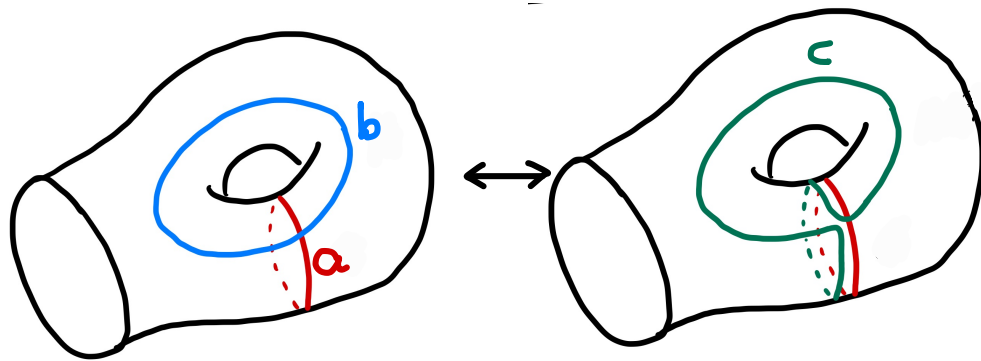
TOWARDS A CONTACT KIRBY'S THEOREM

• PRESENTATION OF $MC(S)$ (GERVAIS '96)

GENERATORS: DEHN TWISTS ALONG NONSEPARATING CURVES

RELATIONS: - COMMUTATIVITY: $ab = ba$ IF $a \cap b = 0$

- BRAID RELATIONS:



$$ab = ca$$

TOWARDS A CONTACT KIRBY'S THEOREM

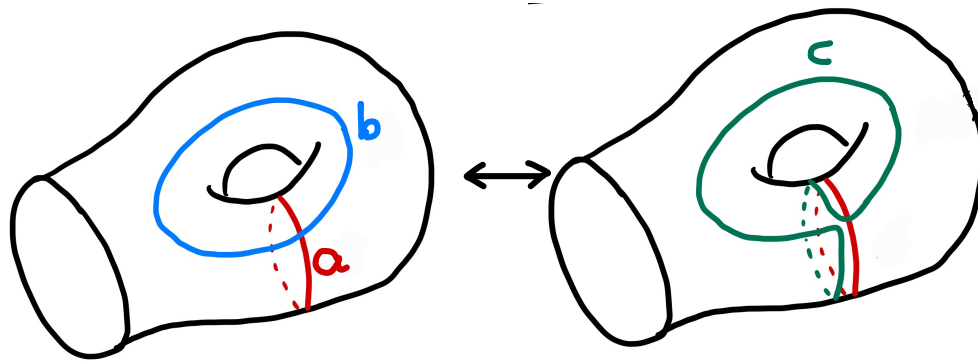
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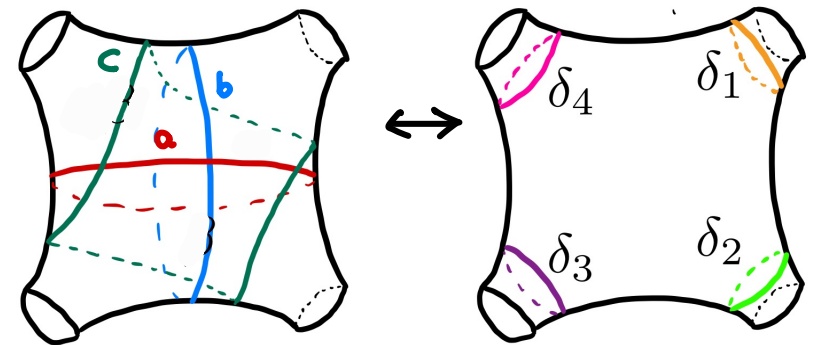
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$$abc = d_1 d_2 d_3 d_4$$

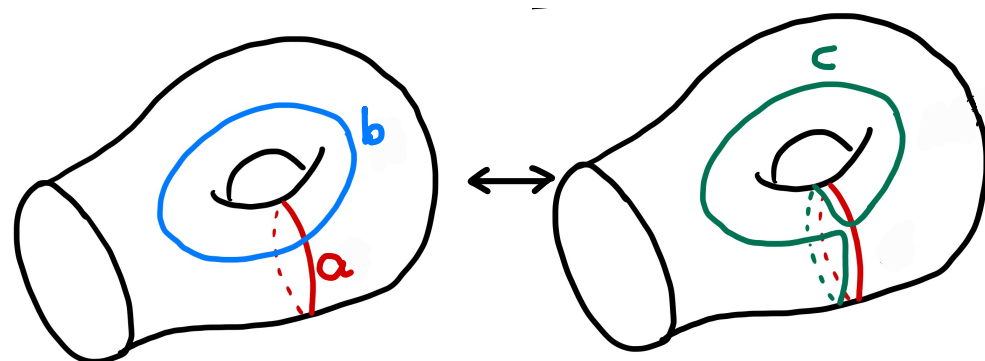
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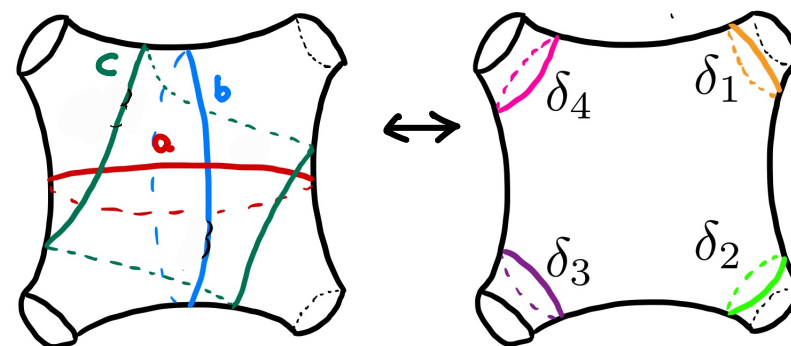
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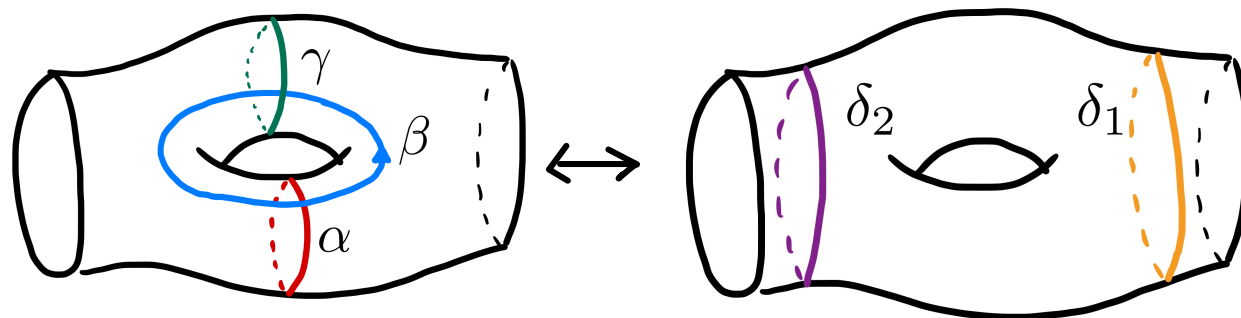
- 1 LANTERN RELATION



$$abc = d_1 d_2 d_3 d_4$$

- 1 CHAIN RELATION

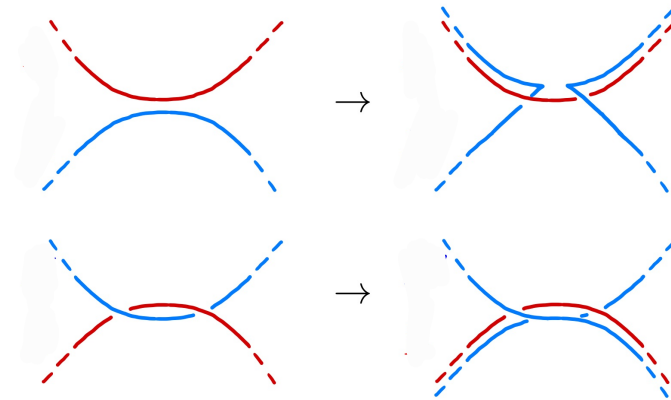
$$(abc)^4 = d_1 d_2$$



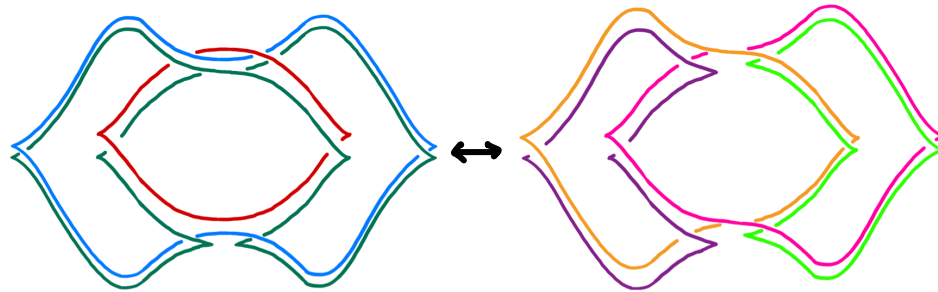
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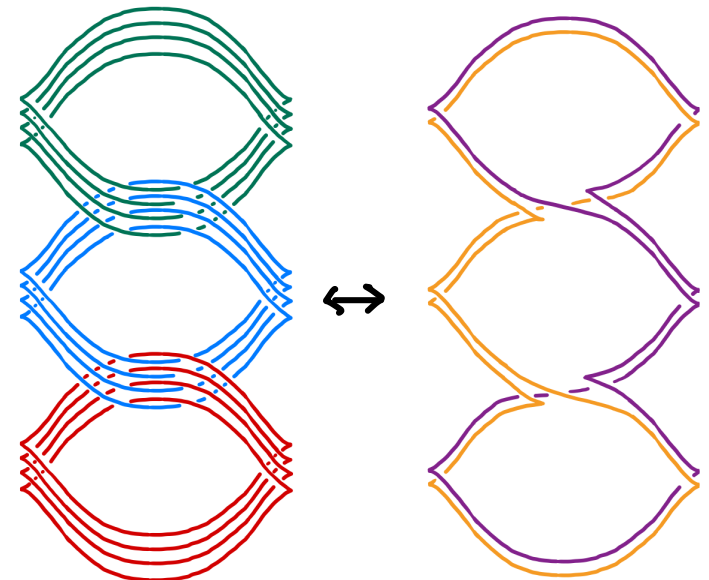
- LEGENDRIAN HANDSLIDE :



- LANTERN MOVE :



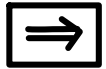
- CHAIN MOVE



IDEA OF PROOF

⇐ RIBBON MOVES ✓

IDEA OF PROOF



• EMBED $\mathcal{L}$ AND $\mathcal{L}'$ INTO PAGES OF OB'S (S, φ_0) OF $(S^2, \mathcal{L})$:

$\mathcal{L}$

ASSUME THEY ARE "FAR"
& EXTEND $\mathcal{L} \sqcup \mathcal{L}'$ INTO
A 'COMPLICATED ENOUGH'
LEGENDRIAN GRAPH

 $\mathcal{L}'$

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$$\leadsto \begin{array}{l} c_1, \dots, c_e \subset S \\ c'_1, \dots, c'_e \subset S \end{array} \quad 0 \neq [c_i^{(1)}] \in H_1(S)$$

IDEA OF PROOF



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& WE STABILISE (S, ψ_0) S.T

$c_i^{(n)}$ IS NONSEPARATING

$\left(\begin{array}{c} \text{CANCELLATION} \\ \& \\ \text{LEG. HSLIDE} \end{array} \right)$

IDEA OF PROOF



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& WE STABILISE (S, ψ_0) S.T

$c_i^{(n)}$ IS NONSEPARATING

$\rightsquigarrow$ TWO OB'S FOR (M, ξ) : $\begin{cases} (S, D_{c_1}^+ \cdots D_{c_k}^+ \cdot \psi_0) \\ (S, D_{c'_1}^+ \cdots D_{c'_k}^+ \cdot \psi_0) \end{cases}$

$\left(\begin{array}{c} \text{CANCELLATION} \\ \& \\ \text{LEG. HSLIDE} \end{array} \right)$

IDEA OF PROOF



• EMBED $\mathcal{L}$ AND $\mathcal{L}'$ INTO PAGES OF OB'S (S, ψ_0) OF (S^2, ξ) :

$\mathcal{L}$

ASSUME THEY ARE "FAR"
& EXTEND $\mathcal{L} \sqcup \mathcal{L}'$ INTO
A 'COMPLICATED ENOUGH'
LEGENDRIAN GRAPH

$\mathcal{L}'$

$\rightsquigarrow c_1, \dots, c_e \subset S$
 $c'_1, \dots, c'_e \subset S$

$0 \neq [c_i^{(n)}] \in H_1(S)$

& WE STABILISE (S, ψ_0) S.T

$c_i^{(n)}$ IS NONSEPARATING

(CANCELLATION
&
LEG. HSLIDE)

$\rightsquigarrow$ TWO OB'S FOR (M, ξ) : $(S, D_{c_1}^+ \cdot \dots \cdot D_{c_e}^+ \cdot \psi_0)$
 $(S, D_{c'_1}^+ \cdot \dots \cdot D_{c'_e}^+ \cdot \psi_0)$

GIRoux
 $\xRightarrow{\text{CORRES}}$

CAN BE STABILISED TO CONJUGATE OB'S



(CANCELLATION & LEG. HSLIDE)

IDEA OF PROOF

⇒ SO AFTER SOME CANCELLATIONS & LEG. SLIDES

WE CAN ASSUME - $c_1, \dots, c_k \subset S$ ARE NONSEPARATING,
- $c'_1, \dots, c'_k \subset S$

(S, ψ_0) DB FOR $(S^3, \mathfrak{F})$ & $(S, D_{c_1}^+ \cdots D_{c_k}^+ \cdot \psi_0)$ } ARE CONT
 $(S, D_{c'_1}^+ \cdots D_{c'_k}^+ \cdot \psi_0)$ } DB'S FOR $(M, \mathfrak{F})$

IDEA OF PROOF

⇒ SO AFTER SOME CANCELLATIONS & LEG. HSLIDES

WE CAN ASSUME - $c_1, \dots, c_k \subset S$ ARE NONSEPARATING,
- $c'_1, \dots, c'_k \subset S$

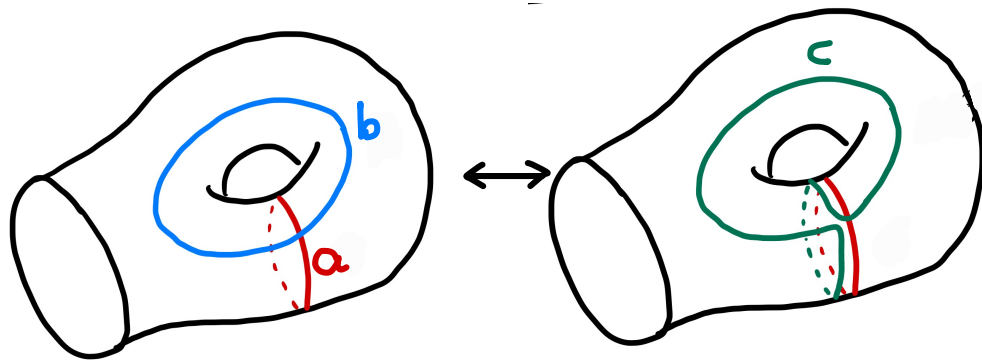
(S, ψ_0) DB FOR $(S^3, \mathcal{Y})$ & $(S, D_{c_1}^+ \cdot \dots \cdot D_{c_k}^+ \cdot \psi_0)$ } ARE CONT
 $(S, D_{c'_1}^+ \cdot \dots \cdot D_{c'_k}^+ \cdot \psi_0)$ } DB'S FOR $(M, \mathcal{Y})$

GERVAIS ⇒ WE CAN RELATE THE WORDS $D_{c_1}^+ \cdot \dots \cdot D_{c_k}^+ \cdot \psi_0$
&
 $D_{c'_1}^+ \cdot \dots \cdot D_{c'_k}^+ \cdot \psi_0$ BY

- | | | |
|--------------------|---|-----------------------|
| - COMMUTATION | ↔ | |
| - BRAID RELATION | ↔ | LEGENDRIAN HANDLESIDE |
| - LANTERN RELATION | ↔ | LANTERN MOVE |
| - CHAIN RELATION | ↔ | CHAIN MOVE |

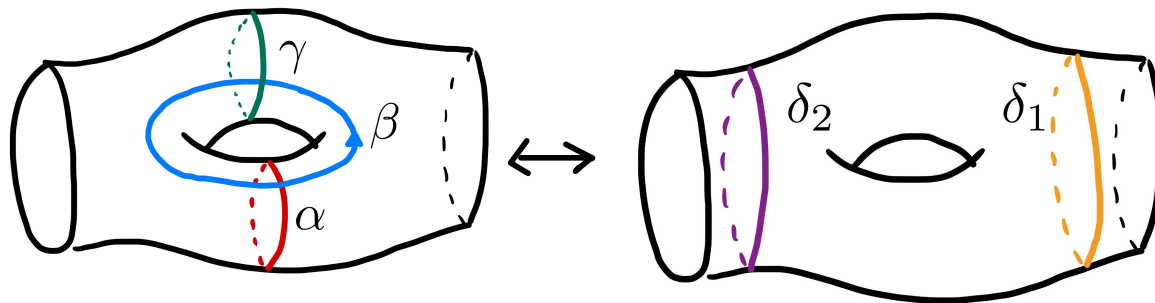
BRAID RELATION

$$ab = ca$$



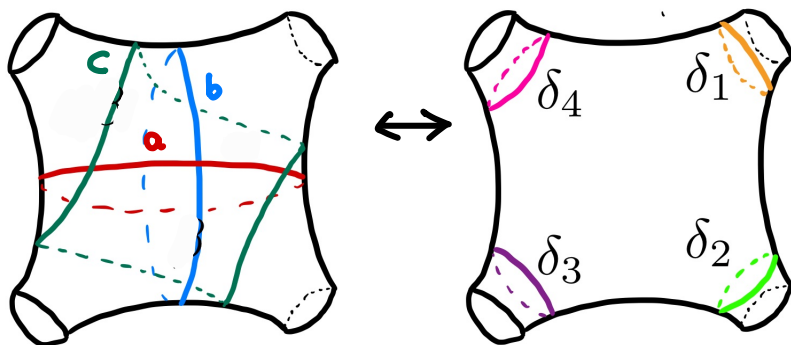
CHAIN RELATION

$$(abc)^4 = d_1 d_2$$

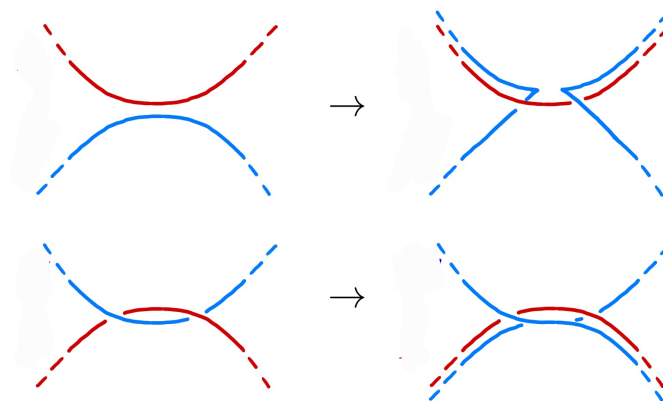


LANTERN RELATION

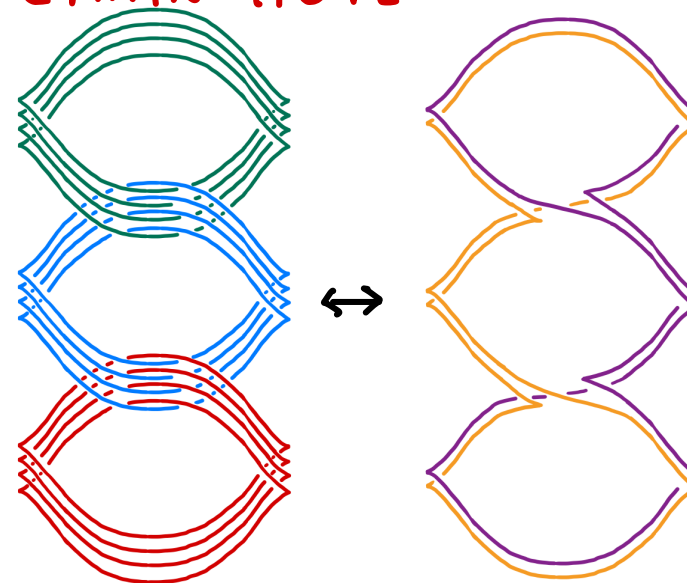
$$abc = d_1 d_2 d_3 d_4$$



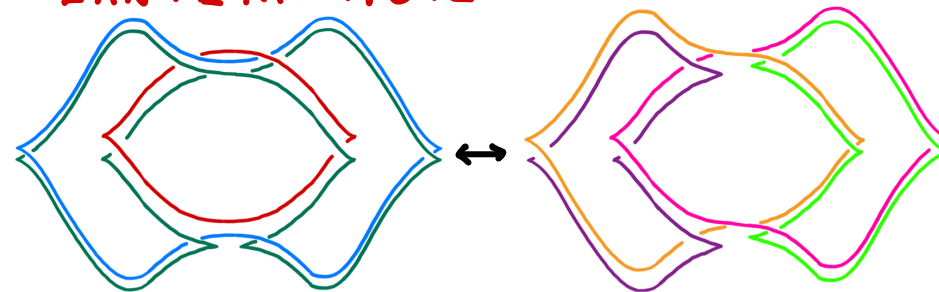
LEGENDRIAN HANDLESIDE



- CHAIN MOVE



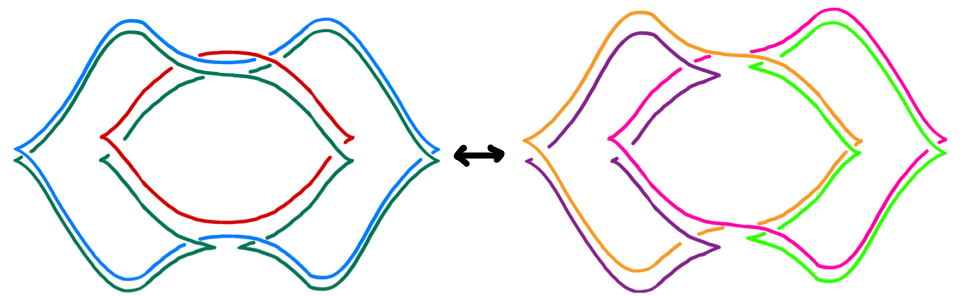
LANTERN MOVE :



THANKS FOR

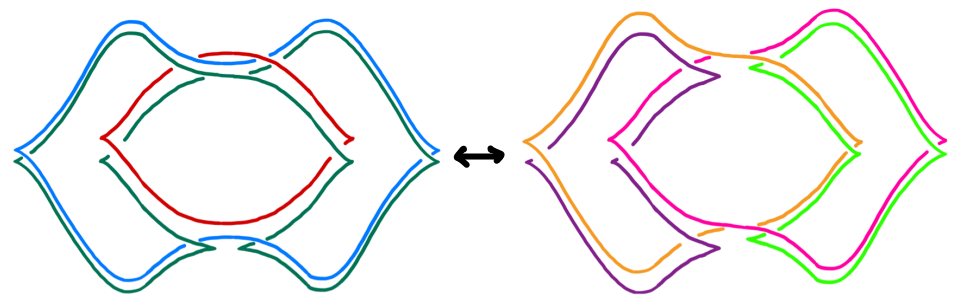
YOUR

ATTENTION!



THANKS FOR

THE



NICE CONFERENCE!