## TWO-JETS OF CONFORMAL FIELDS ALONG THEIR ZERO SETS IN ANY METRIC SIGNATURE

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http://www.math.ohio-state.edu/~andrzej/esi.pdf

## CONFORMAL VECTOR FIELDS

$(M, g)$ always denotes a pseudo-Riemannian manifold of dimension $n \geq 3$.

A vector field $v$ on $M$ is called conformal if its local flow consists of conformal diffeomorphisms. Equivalently, for some $\phi: M \rightarrow \mathbb{R}$,

$$
\begin{equation*}
2 \nabla v=A+\phi \operatorname{Id}, \quad \text { with } \quad A^{*}=-A \tag{1}
\end{equation*}
$$

Here $\nabla v$ is treated as a bundle morphism $T M \rightarrow T M$ (which sends each vector field $w$ to $\nabla_{w} v$ ), and $A=\nabla v-[\nabla v]^{*}$ is twice the skew-adjoint part of $\nabla v$.

Note that $\operatorname{div} v=n \phi / 2$.
Example: Killing fields $v$, characterized by $\phi=0$.
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## THE SIMULTANEOUS KERNEL

Manifolds need not be connected. A submanifold is always endowed with the subset topology.
$Z$ denotes the zero set of a given conformal field $v$.
If $x \in Z$, we use the symbol

$$
\mathcal{H}_{x}=\operatorname{Ker} \nabla v_{x} \cap \operatorname{Ker} d \phi_{x}
$$

for the simultaneous kernel, at $x$, of the differential $d \phi$ and the bundle morphism $\nabla v: T M \rightarrow T M$.

When $x$ is fixed, we also write $H$ instead of $\mathcal{H}_{x}$.

## (NON)ESSENTIAL AND (NON)SINGULAR ZEROS

$x \in Z$ is an essential zero of $v$ if no conformal change of $g$ on any neighborhood $U$ of $x$ turns $v$ into a Killing field for the new metric on $U$.

Otherwise, $x \in Z$ is a nonessential zero of $v$.

A nonsingular zero of $v$ is any $x \in Z$ such that, for some neighborhood $U$ of $x$ in $M$, the intersection $Z \cap U$ is a submanifold of $M$.

Zeros of $v$ not having a neighborhood with this property are from now on called singular.

## BEIG'S THEOREM (1992)

$x \in Z$ is nonessential if and only if

$$
\begin{equation*}
\phi(x)=0 \text { and } \nabla \phi_{x} \in \nabla v_{x}\left(T_{x} M\right) \tag{2}
\end{equation*}
$$

In other words: $x \in Z$ is essential if and only if

$$
\begin{equation*}
\text { either } \phi(x) \neq 0, \quad \text { or } \quad \phi(x)=0 \text { and } \nabla \phi_{x} \notin \nabla v_{x}\left(T_{x} M\right) \tag{3}
\end{equation*}
$$

For a proof, see a 1999 paper by Capocci.

## ESSENTIAL/NONESSENTIAL COMPONENTS OF Z

$Z$ is always locally pathwise connected. Thus, the connected components of $Z$ are pathwise connected, closed subsets of $M$.

From now on they are simply called the components of $Z$.

A component of $Z$ is referred to as essential if all of its points are essential zeros of $v$.

Otherwise, the component is said to be nonessential.

This definition allows a nonessential component $N$ to contain some essential zeros of $v$. We'll see, however, that essential zeros in $N$ then form a closed subset of $N$ without relatively-interior points.

## GEOMETRY OF AN ESSENTIAL COMPONENT $\Sigma$

Let $\Sigma$ be an essential component. Then
(i) $\Sigma$ is a null totally geodesic submanifold of $(M, g)$, closed as a subset of $M$.

In addition, for any $x \in \Sigma$, with $\mathcal{H}_{x}=\operatorname{Ker} \nabla v_{x} \cap \operatorname{Ker} d \phi_{x}$,
(ii) $T_{x} \Sigma=\mathcal{H}_{x} \cap \mathcal{H}_{x}^{\perp}$,
(iii) the metric $g_{x}$ restricted to $\mathcal{H}_{x}$ is semidefinite.

## GEOMETRY OF A NONESSENTIAL COMPONENT N

Assume $N$ to be nonessential, and let $\Sigma$ denote the set of all essential zeros of $Z$ lying in $N$. Then
(a) $\Sigma$, if nonempty, is a null totally geodesic submanifold of $(M, g)$, closed as a subset of $M$,
(b) $N \backslash \Sigma$ is a totally umbilical submanifold of $M$, with $\operatorname{dim}(N \backslash \Sigma)>\operatorname{dim} \Sigma$, and $g$ restricted to $N \backslash \Sigma$ has the same sign pattern (including rank) at all points,
(c) $\Sigma$ consists of singular, $N \backslash \Sigma$ of nonsingular zeros of $v$.

For any $x \in \Sigma$ and $y \in N \backslash \Sigma$, with $\mathcal{H}_{x}=\operatorname{Ker} \nabla v_{x} \cap \operatorname{Ker} d \phi_{x}$,
(d) $T_{y}(N \backslash \Sigma)=\operatorname{Ker} \nabla v_{y}$ and $T_{x} \Sigma=\mathcal{H}_{x} \cap \mathcal{H}_{x}^{\perp}$,
(e) $\operatorname{rank} \nabla v_{y}=2+\operatorname{rank} \nabla v_{x}$,
(f) the metric $g_{x}$ restricted to $\mathcal{H}_{x}$ is not semidefinite.
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## MORE ON NONESSENTIAL COMPONENTS N

Again, $N$ is nonessential, $\Sigma$ is the set of essential zeros of $Z$ lying in $N$, and $x \in \Sigma$.

Let $C=\left\{u \in T_{x} M: g_{x}(u, u)=0\right\}$ be the null cone, and $H=\mathcal{H}_{x}$ the simultaneous kernel at $x$, that is, $H=\operatorname{Ker} \nabla v_{x} \cap \operatorname{Ker} d \phi_{x}$.

For any sufficiently small neighborhoods $U$ of 0 in $T_{x} M$ and $U^{\prime}$ of $x$ in $M$ such that $\exp _{x}$ is a diffeomorphism $U \rightarrow U^{\prime}$,
(g) $Z \cap U^{\prime}$ corresponds under $\exp _{x}$ to $C \cap H \cap U$,
(h) $\Sigma \cap U^{\prime}$ corresponds under $\exp _{x}$ to $H \cap H^{\perp} \cap U$.
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## INDUCED STRUCTURES ON $\Sigma$ AND $N \backslash \Sigma$

Let $\Sigma$ be either an essential component, or the set of essential points (assumed nonempty) in a nonessential component $N$.
$N \backslash \Sigma$ is endowed with a possibly-degenerate conformal structure, or, in other words, a symmetric 2-tensor field, defined only up to multiplications by functions without zeros, and having the same sign pattern at all points (see (b) on p. 7).
$\Sigma$ carries a natural projective structure - a class of torsion-free connections having the same family of nonparametrized geodesics (see (i) on p. 6 and (a) on p. 7), as well as a distinguished codimension-zero-or-one distribution, which means: a 1 -form $\xi$ defined only up to multiplications by functions without zeros.

## HOW $g$ DETERMINES THE ONE-FORM $\xi$ on $\Sigma$

$\Sigma$ is again either an essential component, or the singular subset, assumed nonempty, of a nonessential component $N$.
$\phi=(2 / n) \operatorname{div} v$ is constant along every component of $Z$ (more on this later).

If $\phi=0$ on $\Sigma$, then $\Sigma \ni x \mapsto \mathcal{H}_{x}=\operatorname{Ker} \nabla v_{x} \cap \operatorname{Kerd} \phi_{x}$ is, in both cases, a parallel subbundle of $T_{\Sigma} M$ contained in $\operatorname{Ker} \nabla v$ as a codimension-one subbundle, and we set $\xi=g(w, \cdot)$, on $\Sigma$, for any section $w$ of $\operatorname{Ker} \nabla v$ over $\Sigma$ with $d_{w} \phi=1$.

If $\phi \neq 0$ on $\Sigma$, we set $\xi=0$ (consistent with the above).

## MORE ON THE ONE-FORM $\xi$ ON $\Sigma$

In both cases, $\Sigma$ the natural projective structure, and the codimension-zero-or-one distribution corresponding to $\xi$ is geodesic (although not necessarily integrable): if $\Gamma \subseteq \Sigma$ is a geodesic segment and $T_{x} \Gamma \subseteq \operatorname{Ker} \xi_{x}$ for some $x \in \Gamma$, then the same is true for every $x \in \Gamma$.

Equivalently: for any (torsion-free) connection D within the projective structure,

$$
\begin{equation*}
\operatorname{sym} \nabla \xi=\mu \odot \xi \text { for some 1-form } \mu \text { on } \Sigma \tag{4}
\end{equation*}
$$

In coordinates: $\xi_{j, k}+\xi_{k, j}=\mu_{j} \xi_{k}+\mu_{k} \xi_{j}$.
Note the invariance under changing the connection within the projective structure, and multiplications by functions without zeros.

## A UNIQUE CONTINUATION PROPERTY OF

Due to the "geodesic" property, if $\xi$ vanishes on a nonempty open subset of a connected component of $\Sigma$, then it must vanish on the whole connected component.

This remains true also if one replaces the words 'nonempty open subset' by 'codimension-one submanifold'.

## EXAMPLE: RIEMANN EXTENSIONS

Let D be a connection on a manifold $\Sigma$ (of any dimension).
We denote by $\pi: T^{*} \Sigma \rightarrow \Sigma$ the bundle projection of the cotangent bundle of $\Sigma$.

The Patterson-Walker Riemann extension metric on $M=T^{*} \Sigma$ is the neutral-signature metric $g^{\mathrm{D}}$ defined by requiring that

- all vertical and all D-horizontal vectors be $g^{\text {D}}$-null, while
- $g_{y}^{\mathrm{D}}(\zeta, w)=\zeta\left(d \pi_{y} w\right)$ for any $y \in M$, any vertical vector $\zeta \in \operatorname{Ker} d \pi_{y}=T_{x}^{*} \Sigma$, with $x=\pi(y)$, and any $w \in T_{y} M$.


## THE RADIAL VECTOR FIELD $v$ ON $T^{*} \Sigma$



The radial field $v$ is conformal for any Riemann extension metric.
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p. 14

## THE EXAMPLE, CONTINUED

If the original manifold $\Sigma$ is connected, the zero section $\Sigma \subseteq M$ is an essential component with $\phi \neq 0$.

## CONFORMAL EQUIVALENCE OF ONE-JETS OF

For $x \in Z$, the endomorphism $\nabla v_{x}$ of $T_{x} M$, independent of the choice of $\nabla$, is also known as the linear part, or Jacobian, or derivative, or differential of $v$ at the zero $x$. It coincides with the infinitesimal generator of the local flow of $v$ acting in $T_{x} M$.

Given $x, y \in Z$, we say that the 1 -jets of $v$ at $x$ and $y$ are conformally equivalent if, for some vertical-arrow conformal isomorphism $T_{x} M \rightarrow T_{y} M$, the following diagram commutes:

http://www.math.ohio-state.edu/~andrzej/esi.pdf

## ONE-JETS ALONG A NONESSENTIAL COMPONENT

For a nonessential component $N$, with $\Sigma \subseteq N$ denoting its set of essential points:

The 1-jets of $v$ at all points of any connected component of $N \backslash \Sigma$ are conformally equivalent to one another, but not conformally equivalent to the 1 -jet of $v$ at any $x \in \Sigma$.

In fact, $\nabla v$ is parallel along $N \backslash \Sigma$ with respect to a connection
D in $T_{N \backslash \Sigma} M$ which also preserves the conformal structure. The claim about $x \in \Sigma$ follows from (e) on p. 7 .

Such D arises by gluing together, via a partition of unity on $N \backslash \Sigma$, the Levi-Civita connections of locally-defined metrics conformal to $g$, for which $v$ is a Killing field.
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## CONSTANCY OF THE CHARACTERISTIC POLYNOMIAL

Denote by $\mathcal{P}_{n}$ the space of all polynomials in one real variable with degrees not exceeding $n=\operatorname{dim} M$.

Let $\chi: M \rightarrow \mathcal{P}_{n}$ be the function assigning to each $x \in M$ the characteristic polynomial of $\nabla v_{x}: T_{x} M \rightarrow T_{x} M$.

Then $\chi$ is constant along every component of $Z$.

As a consequence, $\phi=(2 / n) \operatorname{div} v$ is also constant along every component.
http://www.math.ohio-state.edu/~andrzej/esi.pdf

## ONE-JETS ALONG $\Sigma$ (THE GENERIC CASE)

Again, $\Sigma$ is either an essential component, or the singular subset (assumed nonempty) of a nonessential component $N$.

Suppose that $\xi$ is not identically zero on a given connected component of $\Sigma$.

Then the 1 -jets of $v$ at all points of this connected component of $\Sigma$ are conformally equivalent to one another. (See p. 24.)

## THE GENERAL CASE

Once more, $\Sigma$ denotes either an essential component, or the singular set (assumed nonempty) in a nonessential component $N$, but, this time, no assumptions are made about $\xi$.

Then, if $\Gamma \subseteq \Sigma$ is any geodesic segment, $\nabla v$ restricted to $\Gamma$ descends to a parallel section of the vector bundle $\mathfrak{c o n f}\left[(T \Gamma)^{\perp} /(T \Gamma)\right]$.

Equivalently: using the parallel transport to trivialize $T_{\Gamma} M$, we obtain, for any $x, y \in \Gamma$,

$$
\nabla v_{y}-\nabla v_{x}=w \wedge u
$$

where $w, u$ are (variable) vectors along $\Gamma$, and $u$ is tangent to $\Gamma$.
http://www.math.ohio-state.edu/~andrzej/esi.pdf

## THE CONFORMAL-EQUIVALENCE TYPE MAY VARY

It may change not only when one moves from $\Sigma$ to $N \backslash \Sigma$, but also within a connected component of $\Sigma$ (on which $\xi$ is identically zero):

For a pseudo-Euclidean space ( $V,\langle$,$\rangle ) of dimension n$, vectors $w, u \in V$, a skew-adjoint endomorphism $B$, and $c \in \mathbb{R}$, setting

$$
\begin{equation*}
v_{x}=w+B x+c x+2\langle u, x\rangle x-\langle x, x\rangle u \tag{5}
\end{equation*}
$$

we define a conformal field $v$. Choose $n$ even, $\langle$,$\rangle neutral, B$ with null $n$-dimensional eigenspaces for eigenvalues $c,-c$, and $u$ not lying in the $-c$ eigenspace, along with $w=0$. Then $\operatorname{Ker} \nabla v_{x}$ decreases when one moves from $x=0$ to nearby $x$ in the $-c$ eigenspace, orthogonal to $u$.
http://www.math.ohio-state.edu/~andrzej/esi.pdf

## CONFORMAL EQUIVALENCE OF TWO-JETS OF v

We say that the 2-jets of $v$ at $x \in Z$ and $y \in Z$ are conformally equivalent if the restrictions of $d \phi$ to $\operatorname{Ker} \nabla v$ at $x$ and $y$ correspond to each other under some conformal isomorphism $T_{x} M \rightarrow T_{y} M$ that, at the same time, realizes the conformal equivalence of the 1 -jets of $v$ at $x$ and $y$.
(As usual, $\phi=(2 / n) \operatorname{div} v$. )
This happens if and only if some diffeomorphism $F$ between neighborhoods of $x$ and $y$, with $F(x)=y$, sends the one 2-jet to the other, while, at the same time, for some function $\tau: U \rightarrow \mathbb{R}$, the metrics $F^{*} h$ and $e^{\tau} g$ have the same 1-jet at $x$.

## TWO-JETS ALONG A NONESSENTIAL COMPONENT

For a nonessential component $N$ and its essential set $\Sigma \subseteq N$ :
The 2-jets of $v$ at all points of any connected component of $N \backslash \Sigma$ are conformally equivalent to one another, but not conformally equivalent to the 2-jet of $v$ at any $x \in \Sigma$.

The reason is precisely the same as for 1 -jets, since $d \phi=0$ at every essential zero of $v$.

## TWO-JETS ALONG $\Sigma$, THE GENERIC CASE

For $\Sigma$ as before:

Let $\xi \neq 0$ somewhere in a given connected component of $\Sigma$.

Then the 2-jets of $v$ at all points of this connected component of $\Sigma$ are conformally equivalent to one another.

In fact, for any geodesic segment $\Gamma \subseteq \Sigma$ with a parametrization $t \mapsto x(t)$, if $\dot{x}$ is not in the image of $\nabla v$, we may choose $w=w(t) \in T_{x(t)} M$ so that $\nabla_{w} v$ equals $\nabla \phi$ plus a function times $\dot{x}$ and $d_{w} \phi=0$. Then both $\nabla v$ and the restriction of $d \phi$ to $\operatorname{Ker} \nabla v$ are D -parallel for the metric connection D in $T_{\Gamma} M$ given by $2 \mathrm{D}_{\dot{x}}=2 \nabla_{\dot{x}}+w \wedge \dot{x}$.
http://www.math.ohio-state.edu/~andrzej/esi.pdf

## PROOFS: NONESSENTIAL ZEROS

If $x \in Z$ is a nonessential zero of $v$, we may assume that $v$ is a Killing field (by changing the metric conformally near $x$ ).

Thus (Kobayashi, 1958): $x \in Z$ has a neighborhood $U^{\prime}$ in $M$ such that, for some star-shaped neighborhood $U$ of 0 in $T_{x} M$, the exponential mapping $\exp _{x}$ is a diffeomorphism $U \rightarrow U^{\prime}$ and

$$
Z \cap U^{\prime}=\exp _{x}[H \cap U]
$$

Here $H=\mathcal{H}_{x}=\operatorname{Ker} \nabla v_{x}$, since $\phi=0$.

## PROOFS: ESSENTIAL ZEROS

THEOREM 1 (D., Class. Quantum Gravity 28, 2011, 075011): Let $Z$ be the zero set of a conformal vector field $v$ on a pseudoRiemannian manifold ( $M, g$ ) of dimension $n \geq 3$.
If $x$ is an essential zero of $v$ and $H=\operatorname{Ker} \nabla v_{x} \cap \operatorname{Kerd} \phi_{x}$, then

$$
Z \cap U^{\prime}=\exp _{x}[C \cap H \cap U]
$$

for any sufficiently small star-shaped neighborhood $U$ of 0 in $T_{x} M$ mapped by $\exp _{x}$ diffeomorphically onto a neighborhood $U^{\prime}$ of $x$ in $M$, where $C=\left\{u \in T_{x} M: g_{x}(u, u)=0\right\}$ is the null cone. In other words:

The zero set $Z$ is, near any essential zero $x$, the $\exp _{x}$-image of a neighborhood of 0 in the null cone in the simultaneous kernel $H$. http://www.math.ohio-state.edu/~andrzej/esi.pdf

## THE COMPONENTS OF Z

In addition, $\phi$ is constant along each connected component of $Z$.

Away from singularities, the components of $Z$ are totally umbilical submanifolds of $(M, g)$, and their codimensions are even unless the component is a null totally geodesic submanifold.

## BACKGROUND

- Kobayashi (1958): for a Killing field $v$ on a Riemannian manifold $(M, g)$, the connected components of the zero set of $v$ are mutually isolated totally geodesic submanifolds of even codimensions.
- Blair (1974): if $M$ is compact, this remains true for conformal vector fields, as long as one replaces the word 'geodesic' by 'umbilical' and the codimension clause is relaxed in the case of one-point connected components.
- Belgun, Moroianu and Ornea (J. Geom. Phys. 61, no. 3, 2011, pp. 589-593): Blair's conclusion holds without the compactness hypothesis.


## LINEARIZABILITY

- The last result is also a direct consequence of the following theorem of Frances (2009, arXiv:0909:0044v2): at any zero $z$, a conformal field is linearizable unless $z$ has a conformally flat neighborhood.
- Frances and Melnick (2010, arXiv:1008.3781): the above statement is true in real-analytic Lorentzian manifolds as well.
- Leitner (1999): in Lorentzian manifolds, zeros of a conformal field with certain additional properties lie, locally, in a null geodesic.


## SINGULARITIES OF THE ZERO SET $Z$

## Consequently:

The singular subset of $Z \cap U^{\prime}$ equals $\exp _{z}\left[H \cap H^{\perp} \cap U\right]$, if the metric restricted to $H$ is not semidefinite, and is empty otherwise.

## WHY TOTALLY UMBILICAL

Let $b$ be the second fundamental form of a submanifold $K$ in a manifold $M$ endowed with a torsionfree connection $\nabla$.

If $x \in M$, a neighborhood $U$ of 0 in $T_{x} M$ is mapped by $\exp _{x}$ diffeomorphically onto a neighborhood of $x$ in $M$, and $K=\exp _{x}[V \cap U]$ for a vector subspace $V$ of $T_{x} M$, then $b_{x}=0$.

## THE CONFORMAL-FIELD CONDITION, REWRITTEN

We always denote by $t \mapsto x(t)$ a geodesic of $(M, g)$, by $\dot{x}=\dot{x}(t)$ its velocity, and write $\dot{f}=d[f(x(t))] / d t, \ddot{f}=d^{2}[f(x(t))] / d t^{2}$ for vector-valued functions $f$ on $M$.

The equality $2 \nabla v=A+\phi$ Id with $A^{*}=-A$, rewritten as $\nabla v+[\nabla v]^{*}=\phi \mathrm{Id}$, or

$$
v_{j, k}+v_{k, j}=\phi g_{j k}
$$

is obviously equivalent to the requirement that, along every geodesic,

$$
\begin{equation*}
\langle v, \dot{x}\rangle^{\cdot}=\phi\langle\dot{x}, \dot{x}\rangle, \tag{6}
\end{equation*}
$$

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## IDENTITIES RELATED TO THE CARTAN CONNECTION

If $t \mapsto u(t) \in T_{x(t)} M$ and $\nabla_{\dot{x}} u=0$, one has

$$
\begin{aligned}
& 2 \nabla_{\dot{x}} \nabla_{u} v=2 R(v \wedge \dot{x}) u+[(d \phi)(u)] \dot{x}+\dot{\phi} u-\langle\dot{x}, u\rangle \nabla \phi \\
& (1-n / 2)[(d \phi)(u)]^{\cdot}=\sigma\left(u, \nabla_{\dot{x}} v\right)+\sigma\left(\dot{x}, \nabla_{u} v\right)+\left[\nabla_{v} \sigma\right](u, \dot{x}),
\end{aligned}
$$

$\sigma=$ Ric $-(2 n-2)^{-1}$ Scal $g$ being the Schouten tensor. Thus,

$$
\begin{aligned}
& \nabla_{\dot{x}} \nabla_{\dot{x}} v=R(v \wedge \dot{x}) \dot{x}+\dot{\phi} \dot{x}-\langle\dot{x}, \dot{x}\rangle \nabla \phi / 2 \\
& (1-n / 2) \ddot{\phi}=2 \sigma\left(\dot{x}, \nabla_{\dot{x}} v\right)+\left[\nabla_{v} \sigma\right](\dot{x}, \dot{x})
\end{aligned}
$$

Hence: if the geodesic is null and $v, \nabla_{\dot{x}} v, \dot{\phi}$ vanish for some $t$, then they vanish for every $t$.

## ONE INCLUSION - FOR FREE

Once again: if the geodesic is null and $v, \nabla_{\dot{x}} v, \dot{\phi}$ vanish for some $t$, then they vanish for every $t$.

Therefore, for any zero $x$ of $v$, essential or not,

$$
\exp _{x}[C \cap H \cap U] \subseteq Z \cap U^{\prime}
$$

where $H=\operatorname{Ker} \nabla v_{x} \cap \operatorname{Ker} d \phi_{x}$. In other words:
The $\exp _{x}$-image of the null cone in the simultaneous kernel $H$ always consists of zeros of $v$.

The clause about constancy of $\phi$ will now follow immediately, once the above inclusion is shown to be an equality.

## INTERMEDIATE SUBMANIFOLDS

Given a zero $x$ of a section $\psi$ of a vector bundle $\mathcal{E}$ over a manifold $M$, we denote by $\partial \psi_{x}$ the linear operator $T_{x} M \rightarrow \mathcal{E}_{x}$ with the components $\partial_{j} \psi^{a}$. (Thus, $\partial \psi_{x}=\nabla \psi_{x}$ if $\nabla$ is a connection in $\mathcal{E}$.)

A trivial consequence of the rank theorem:
All zeros of $\psi$ near $x$ then lie in a submanifold $\Pi \subseteq M$ such that $T_{x} \Pi=\operatorname{Ker} \partial \psi_{x}$ and $\operatorname{Ker} \partial \psi_{y} \subseteq T_{y} \Pi$ for all $y \in \Pi$ with $\psi_{y}=0$.

Note that the zero set $Z$ of $\psi$ can, in general, be any closed subset of $M$. An intermediate submanifold $\Pi$ chosen as above provides some measure of control over $Z$.

## CONNECTING LIMITS

Whenever $M$ is a manifold, $x \in M$, and $L \subseteq T_{x} M$ is a line through 0 , while $y_{j}, z_{j} \in M, j=1,2, \ldots$, are sequences converging to $x$ with $y_{j} \neq z_{j}$ whenever $j$ is sufficiently large, let us call $L$ a connecting limit for this pair of sequences if some norm || in $T_{x} M$ and some diffeomorphism $\Psi$ of a neighborhood of 0 in $T_{x} M$ onto a neighborhood of $x$ in $M$ have the property that $\Psi(0)=x$ and $d \Psi_{0}=\mathrm{Id}$, while the limit of the sequence $\left(w_{j}-u_{j}\right) /\left|w_{j}-u_{j}\right|$ exists and spans $L$, the vectors $u_{j}, w_{j}$ being characterized by $\Psi\left(u_{j}\right)=y_{j}, \Psi\left(w_{j}\right)=z_{j}$ for large $j$.

## RADIAL LIMIT DIRECTIONS

For $M, x$ and $y_{j}, z_{j}$ as above, neither $L$ itself nor the fact of its existence depends on the choice of $|\mid$ and $\Psi$.

In the case where $\Pi \subseteq M$ is a submanifold, both sequences $y_{j}, z_{j}$ lie in $\Pi$, and $L$ is their connecting limit, one has $L \subseteq T_{x} \Pi$.

By a radial limit direction of a subset $Z \subseteq M$ at a point $x \in M$ we mean a connecting limit of for a pair of sequences as above, of which one is constant and equal to $x$, and the other lies in $Z$.

CASE I: $\phi(x) \neq 0$
Choose $U, U^{\prime}$ so that $\phi \neq 0$ everywhere in $U^{\prime}$. For $y \in\left(Z \cap U^{\prime}\right) \backslash\{x\}$, let $L_{y}=T_{x} \Gamma_{y}$ be the initial tangent direction of the geodesic segment $\Gamma_{y}$ joining $x$ to $y$ in $U^{\prime}$.

Recall that

$$
\langle v, \dot{x}\rangle^{\cdot}=\phi\langle\dot{x}, \dot{x}\rangle,
$$

and so $\Gamma_{y}$ is null.

CASE I: $\phi(x) \neq 0$ (CONTINUED)
Next, for $U, U^{\prime}$ small enough, $L_{y} \subseteq \operatorname{Ker} \nabla v_{x}$.
In fact, $\Gamma_{y}$ is rigid. Hence $v$ is tangent to $\Gamma_{y}$, and $L_{y} \subseteq \operatorname{Ker}\left(\nabla v_{x}-\lambda_{y} \mathrm{Id}\right)$ for some eigenvalue $\lambda_{y}$.

Now, if we had $\lambda_{y} \neq 0$ for some sequence $y \in\left(Z \cap U^{\prime}\right) \backslash\{x\}$ converging to $x$, passing to a suitable subsequence such that $L_{y} \rightarrow L$ for some $L$ we would get $\lambda_{y}=\lambda$ (independent of $y$ ), and a contradiction would ensue: $L \subseteq T_{x} \Pi=\operatorname{Ker} \partial \psi_{x}=\operatorname{Ker} \nabla v_{x}$, where $\Pi$ is an intermediate submanifold for $\psi=v$ and $x$.

CASE I: $\phi(x) \neq 0$ (STILL)
Furthermore, as $2 \nabla v=A+\phi \operatorname{Id}$ with $A^{*}=-A$, it follows that
both $\operatorname{Ker} \nabla v_{x}$ and $H \subseteq \operatorname{Ker} \nabla v_{x}$ are null subspaces of $T_{x} M$.

If $\operatorname{Ker} \nabla v_{x} \subseteq \operatorname{Ker} d \phi_{x}$, so that $H=\operatorname{Ker} \nabla v_{x}$, the one inclusion we already have completes the proof.

## CASE I: $\phi(x) \neq 0$ (FINAL STEP)

Therefore, assume that $\operatorname{Ker} \nabla v_{x}$ is not contained in $\operatorname{Ker} d \phi_{x}$. Thus, $K=\exp _{x}[H \cap U]$ is a codimension-one submanifold of $\Pi=\exp _{x}\left[\operatorname{Ker} \nabla v_{x} \cap U\right]$, while the restriction of $\phi$ to $\Pi$ has a nonzero differential at $x$, and $\phi=\phi(x)$ on K. Making $U, U^{\prime}$ smaller, we ensure that $\phi \neq \phi(x)$ everywhere in $\Pi \backslash K$. This shows that no zero $y$ of $v$ lies in $\Pi \backslash K$, for the existence of one would result in a contradiction: we have
$\nabla_{\dot{x}} \nabla_{\dot{x}}(v \wedge \dot{x})=[R(v \wedge \dot{x}) \dot{x}] \wedge \dot{x}$ (for null geodesics) and
$\nabla_{\dot{x}} \nabla_{\dot{x}} v=\dot{\phi} \dot{x}$ (for null geodesics to which $v$ is tangent); integrating the latter, one obtains $\nabla_{\dot{x}} v=[\phi-\phi(x)] \dot{x}$.

CASE II: $\phi(x)=0$ AND $\nabla \phi_{x} \notin \nabla v_{x}\left(T_{x} M\right)$
SUBCASE II-a: in addition, $\operatorname{Ker} \nabla v_{x}$ is not null.
For $K=\exp _{x}\left[H \cap H^{\perp} \cap U\right]$ and any $y \in K$ :
the parallel transport from $x$ to $y$ sends the simultaneous kernel $H=\operatorname{Ker} \nabla v_{x} \cap \operatorname{Ker} d \phi_{x}$ onto $\mathcal{H}_{y}=\operatorname{Ker} \nabla v_{y} \cap \operatorname{Ker} d \phi_{y}$,
while
$\operatorname{dim} \mathcal{H}_{y}$ is independent of $y \in K$, and
if $\phi(x)=0$, both rank $\nabla v_{y}$ and $\operatorname{dim} \operatorname{Ker} \nabla v_{y}$ are constant as functions of $y \in K$.
http://www.math.ohio-state.edu/~andrzej/esi.pdf

## SUBCASE II-a, PROOF OF THE ABOVE CLAIMS

From the "inclusion for free" and the second order identities related to the Cartan connection:

$$
2 \nabla_{\dot{x}} \nabla_{u} v=[(d \phi)(u)] \dot{x}, \quad(1-n / 2)[(d \phi)(u)]^{\cdot}=\sigma\left(\dot{x}, \nabla_{u} v\right) .
$$

Uniqueness of solutions: the parallel transport sends $H=\mathcal{H}_{x}$ INTO $\mathcal{H}_{y}$. Now 'ONTO' follows as $\operatorname{dim} \mathcal{H}_{y} \leq \operatorname{dim} \mathcal{H}_{x}$ (semicontinuity). Thus, for $y \in K$ and $p_{y}=\operatorname{dim} \operatorname{Ker} \nabla v_{y}$,
$p_{x}-1 \leq p_{y} \leq p_{x}$.
As $\phi(y)=0$, the codimension $n-p_{y}$ is even (note that $2 \nabla v=A+\phi \operatorname{Id}$ with $A^{*}=-A$ ). Hence $p_{y}=p_{x}$.

## SETS OF CONNECTING LIMITS

Suppose that $M$ is a manifold, $Y, Z \subseteq M$, and $x \in M$.

We denote by $\mathbb{L}_{x}(Y, Z)$ the set of all connecting limits for pairs $y_{j}, z_{j}$ of sequences in $Y$ and, respectively, $Z$, converging to $x$, with $y_{j} \neq z_{j}$ for all $j$.

For instance:
$\mathbb{L}_{x}(\{x\}, Z)$ is the set of all radial limit directions of a subset $Z \subseteq M$ at a point $x \in M$.

## INTERMEDIATE SUBMANIFOLDS REVISITED

As before: we are given a zero $x$ of a section $\psi$ of a vector bundle $\mathcal{E}$ over a manifold $M$.

For $r=$ rank $\partial \psi_{x}$, we choose an $r$-dimensional real vector space $W$ and a base-preserving bundle morphism $G: \mathcal{E} \rightarrow M \times W$ such that $G_{x}: \partial \psi_{x}\left(T_{x} M\right) \rightarrow W$ is an isomorphism. Now we may set $\Pi=U \cap F^{-1}(0)$ for a suitable neighborhood $U$ of $x$ in $M$ and $F: M \rightarrow W$ defined by $F(y)=G_{y} \psi_{y}$.

If $\xi$ is a section of $\mathcal{E}^{*}$ and $\partial \psi_{x}\left(T_{x} M\right) \subseteq \operatorname{Ker} \xi_{x}$, then $Q=\xi(\psi): \Pi \rightarrow \mathbb{R}$ has a critical point at $x$ with the Hessian of $Q$ characterized by $\partial d Q_{x}(u, u)=\xi\left(\left[\nabla_{u}(\nabla \psi)\right] u\right)$.

## SUBCASE II-a CONTINUED

Recall: this means that
$\phi(x)=0, \quad \nabla \phi_{x} \notin \nabla v_{x}\left(T_{x} M\right), \quad$ Ker $\nabla v_{x}$ not null.

Fix a section $w$ of the bundle $\operatorname{Ker} \nabla v$ over
$K=\exp _{x}\left[H \cap H^{\perp} \cap U\right]$ lying outside the subbundle Ker $\nabla v \cap \operatorname{Ker} d \phi$, and apply the intermediate submanifold construction to $\psi=v, \mathcal{E}=T M$ and $\xi=2 g(w, \cdot)$.

Then $Q=2 g(w, v): \Pi \rightarrow \mathbb{R}$ has, at $x$, the Hessian

$$
\partial d Q=d \phi \otimes g(w, \cdot)+g(w, \cdot) \otimes d \phi-[d \phi(w)] g .
$$

## THE MORSE-BOTT LEMMA

Given a manifold $\Pi$, a submanifold $K \subseteq \Pi$, a function $Q: \Pi \rightarrow \mathbb{R}$, and a point $x \in K \cap Q^{-1}(0)$, let $d Q=0$ on $K$, and let rank $\partial d Q_{x} \geq \operatorname{dim} \Pi-\operatorname{dim} K$.

Then, for some diffeomorphism $\Psi$ between neighborhoods $U$ of 0 in $T_{x} \Pi$ and $U^{\prime}$ of $x$ in $\Pi$, such that $\Psi(0)=x$ and $d \Psi_{0}=I d$, the composition $Q \circ \Psi$ equals the restriction to $U$ of the quadratic function of $\partial d Q_{x}$.

Consequently, $U^{\prime} \cap Q^{-1}(0)=\Psi(C \cap U)$ and $K \cap U^{\prime}=\Psi(V \cap U)$, where $C, V \subseteq T_{x} M$ are the null cone and nullspace of $\partial d Q_{x}$.

## QUADRICS

Given a subset $Z$ of a manifold $\Pi$, and a point $x \in Z$, and a symmetric bilinear form (,) in $T_{x} M$, we say that $Z$ is a quadric at $x$ in $\Pi$ modelled on (,) if some diffeomorphism $\Psi$ between neighborhoods of 0 in $T_{x} \Pi$ and of $x$ in $\Pi$, with $\Psi(0)=x$ and $d \Psi_{0}=$ Id, makes $Z$, (near $x$ ) correspond to the null cone of $($, (near 0). For instance:

- the conclusion of the Morse-Bott lemma states, in particular, that $Q^{-1}(0)$ is a quadric at $x$ in $\Pi$, modelled on $\partial d Q_{x}$,
- our Theorem 1 implies that the zero set $Z$ is a quadric at $x$ in $\exp _{x}[H \cap U]$, modelled on the restriction of $g_{x}$ to $H$.


## CONSEQUENCES OF THE MORSE-BOTT LEMMA

In Subcase II-a, one has the equality

$$
Z \cap \phi^{-1}(0) \cap U^{\prime}=\exp _{x}[C \cap H \cap U]
$$

Secondly, lying in $H$ but not in $H \cap H^{\perp}$ is forbidden for connecting limit between $Z \backslash \phi^{-1}(0)$ and $K$ :

$$
\mathbb{L}_{x}\left(Z \backslash \phi^{-1}(0), K\right) \cap \mathbb{P}(H) \subseteq \mathbb{P}\left(H \cap H^{\perp}\right)
$$

where $\mathbb{P}()$ is the projective-space functor. Note:
$H \cap H^{\perp}=T_{x} K$ and $T_{x}\left(\Pi \cap \phi^{-1}(0)\right)=H$ is a codimension-one subspace of $\operatorname{Ker} \nabla v_{x}=T_{x} \Pi$.
http://www.math.ohio-state.edu/~andrzej/esi.pdf

## PROOF OF THE FIRST RELATION

For suitably chosen $w$, both $Q=2 g(w, v): \Pi \rightarrow \mathbb{R}$ and the restriction of $Q$ to $\Pi \cap \phi^{-1}(0)$ satisfy, along with our $x$ and $K=\exp _{x}\left[H \cap H^{\perp} \cap U\right]$, the hypotheses of the Morse-Bott lemma.
(FINALLY, the assumption "Ker $\nabla v_{x}$ not null" is used!)

So:

$$
Z \cap \phi^{-1}(0) \cap U^{\prime}=\exp _{x}[C \cap H \cap U]
$$

since two quadrics modelled on the same symmetric bilinear form, such that one contains the other, must, essentially, coincide.
http://www.math.ohio-state.edu/~andrzej/esi.pdf

## OUTLINE OF PROOF OF THE SECOND RELATION

The Morse-Bott lemma for $Q, \Pi$ and $K$ allows us to identify $Q$ with the quadratic function of a direct-sum symmetric bilinear form on $W \oplus V$, where the summand form on $W$ is nondegenerate and that on $V$ is zero. If $L \in \mathbb{L}_{x}\left(Z \backslash \phi^{-1}(0), K\right) \cap \mathbb{P}(H)$, we have the convergence

$$
\frac{s_{j} u_{j}+y_{j}-z_{j}}{\left|s_{j} u_{j}+y_{j}-z_{j}\right|} \rightarrow c u+x \in L \quad \text { as } j \rightarrow \infty,
$$

for a fixed Euclidean sphere $S \subseteq W$, a neighborhood $K$ of 0 in $V$, some $u_{j}, u \in \Sigma, s_{j} \in \mathbb{R}$ and $y_{j}, z_{j} \in K$ with $u_{j} \rightarrow u$ and $\left|s_{j}\right|+\left|y_{j}\right|+\left|z_{j}\right| \rightarrow 0$. From the Hessian formula at the bottom of $p$. 46, $d \phi_{x}(u) \neq 0$. Hence $c=0$, which proves that $L \in \mathbb{P}\left(H \cap H^{\perp}\right)$.

## THE CRUCIAL IMPLICATION

In Subcase II-a, the inclusion

$$
\mathbb{L}_{x}\left(Z \backslash \phi^{-1}(0), K\right) \cap \mathbb{P}(H) \subseteq \mathbb{P}\left(H \cap H^{\perp}\right)
$$

implies, BY ITSELF, that

$$
Z \cap U^{\prime} \subseteq \phi^{-1}(0)
$$

Here is why.

## NONVANISHING OF $\phi$

First, for a fixed positive-definite metric $h$, any $y \in U^{\prime} \backslash K$ is joined by a "rigid" $g$-geodesic segment $\Gamma_{y}$ to a point $p_{y} \in K$ is such a way that that $\Gamma_{y}$ is $h$-normal to $K$ at $p_{y}$. Now:
if $y \in\left(Z \cap U^{\prime}\right) \backslash \phi^{-1}(0)$, then $\phi \neq 0$ everywhere in $\Gamma_{y} \backslash\left\{y, p_{y}\right\}$.

For, otherwise, a subsequence of a sequence of points $y$ falsifying this claim and converging to $x$ would produce, as the limit of their $T_{y} \Gamma_{y}$, an element $L$ of $\mathbb{L}_{x}\left(Z \backslash \phi^{-1}(0), K\right) \cap \mathbb{P}(H)$, and hence of $\mathbb{P}\left(H \cap H^{\perp}\right)$, which cannot happen as $L$ would also be $h$-orthogonal to $H \cap H^{\perp}=T_{x} K$.

## PROOF OF THE CRUCIAL IMPLICATION, CONTINUED

Next, whenever a conformal vector field $v$ is tangent to a null geodesic segment $\Gamma$, so that $x(0)=y$ and $\nabla_{\dot{x}} v=\lambda \dot{x}$ at $t=0$ for some $y \in M$ and $\lambda \in \mathbb{R}$, we have

- $\nabla_{\dot{x}} v=[\lambda+\phi-\phi(y)] \dot{x}$ along $\Gamma$,
- $\quad \nabla v$ restricted to $\Gamma$ descends to a parallel section of conf $\left[(T \Gamma)^{\perp} /(T \Gamma)\right]$ and has the same characteristic polynomial at all points of $\Gamma$, if, in addition, $\phi$ is constant along $\Gamma$.

To see this, it suffices to integrate the equality $\nabla_{\dot{x}} \nabla_{\dot{\chi}} v=\dot{\phi} \dot{x}$ (see the final step of Case I), and, respectively, use the first one of the second-order identities related to the Cartan connection.
http://www.math.ohio-state.edu/~andrzej/esi.pdf

## PROOF OF THE CRUCIAL IMPLICATION, FINAL STEP

We prove that $Z \cap U^{\prime} \subseteq \phi^{-1}(0)$ by contradiction. Suppose that some points $y \in Z \cap U^{\prime}$ with $\phi(y) \neq 0$ form a sequence converging to $x$. Our $\Gamma_{y}$ are tangent to $v$, so (see p. 54) $\nabla_{\dot{x}} v=[\lambda+\phi-\phi(y)] \dot{x}, x(0)=y, x(1)=p_{y}$, where $\lambda$ may depend on $y$, but not on the curve parameter $t$. Thus, $\dot{x}(1)$ is an eigenvector of $\nabla v$ at $p_{y}$ for the eigenvalue $\lambda_{y}=\lambda-\phi(y)$. Constancy of the spectrum of $\nabla v$ along $\Gamma$ (see p. 54) implies that $\lambda_{y}$ is an eigenvalue of $\nabla v_{x}$ and, as the limit $L$ of any convergent subsequence of the directions $T_{y} \Gamma_{y}$ must lie in $T_{x} \Pi=\operatorname{Ker} \nabla v_{x}$, we eventually have $\lambda_{y}=0$, that is, $\lambda=\phi(y)$. The equality $\nabla_{\dot{x}} v=[\lambda+\phi-\phi(y)] \dot{x}$ now becomes $\nabla_{\dot{x}} v=\phi \dot{x}$, and Rolle's theorem contradicts the conclusion about nonvanishing of $\phi$ on p. 53.
http://www.math.ohio-state.edu/~andrzej/esi.pdf

## SUBCASE II-a WRAPPED UP

The inclusion on p. 49 combined with the crucial implication (p. 52) shows that $\phi(y)=0$ for every $y \in Z$, near $x$.

The equality on p. 49 now proves the assertion of Theorem 1 in Subcase II-a.

CASE II: $\phi(x)=0$ AND $\nabla \phi_{x} \notin \nabla v_{x}\left(T_{x} M\right)$
SUBCASE II-b: in addition, $\operatorname{Ker} \nabla v_{x}$ is null.
Since $\operatorname{Ker} \nabla v_{x}$ is null, so is $H \subseteq \operatorname{Ker} \nabla v_{x}$. Hence $H=H \cap H^{\perp}$ and the inclusion on p .31 is satisfied trivially. The crucial implication (p. 52) now gives $Z \cap U^{\prime} \subseteq \phi^{-1}(0)$.

We choose an intermediate submanifold $N$ containing $K=\exp _{x}\left[H \cap H^{\perp} \cap U\right]$ (that is, $\left.K=\exp _{x}[H \cap U]\right)$ as a codimension-one submanifold.

Since $T_{x} \Pi \cap \operatorname{Ker} d \phi_{x}=T_{x} K$, it follows that $U^{\prime} \cap \phi^{-1}(0) \subseteq K$, and so $X \cap U^{\prime} \subseteq K$.
This completes the proof of Theorem 1.
http://www.math.ohio-state.edu/~andrzej/esi.pdf

