



On the Shape Operator of Biconservative Hypersurfaces in Euclid and Minkowski Spaces

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- 1 Preliminaries
 - Notation
 - Biconservative Submanifolds
 - Hypersurfaces of Riemannian Space Forms
- 2 Hypersurfaces of \mathbb{E}_1^4
 - Uniqueness of Biconservative Hypersurfaces
 - Local Classification
- 3 Biconservative Hypersurfaces in Euclidean Spaces



Section 1:

Preliminaries



Basic Notation

Let \mathbb{E}_r^n denote the pseudo-Euclidean n space with the index r given by the metric

$$\tilde{g} = \langle \cdot, \cdot \rangle = - \sum_{i=1}^r dx_i^2 + \sum_{i=r+1}^n dx_i^2$$

Note: We drop r in the Riemannian case $r = 0$.



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Put

$$\mathbb{S}_r^n = \{x \in \mathbb{E}_r^{n+1} : \langle x, x \rangle = 1\}$$

and

$$\mathbb{H}_r^n = \{x \in \mathbb{E}_{r+1}^{n+1} : \langle x, x \rangle = -1\}.$$

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Further we use the notation

$$R_r^n(c) = \begin{cases} \mathbb{S}_r^n & \text{if } c = 1, \\ \mathbb{H}_r^n & \text{if } c = -1, \\ \mathbb{E}_r^n & \text{if } c = 0, \end{cases}$$

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Basic Definitions

Let (Ω, g) be a semi-Riemannian manifold and $f : (\Omega, g) \hookrightarrow R_r^n(c)$ an isometric immersion.



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Then, the Gauss and Weingarten formulas for the submanifold $M = f(\Omega)$ of $R_r^n(c)$:

$$\begin{aligned}\tilde{\nabla}_X Y &= \nabla_X Y + \alpha_f(X, Y), \\ \tilde{\nabla}_X \xi &= -A_\xi^f X + \nabla_X^\perp \xi.\end{aligned}$$



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The mean curvature vector field of f is defined by

$$H_f = \frac{1}{m} \text{trace } \alpha_f.$$



Basic Equations

The following equations is satisfied for a given $f : (\Omega, g) \hookrightarrow R_r^n(c)$:

$$R(X, Y)Z = c(X \wedge Y)Z + A_{\alpha_f(Y, Z)}^f X - A_{\alpha_f(X, Z)}^f Y, \quad (\text{G})$$

$$(\bar{\nabla}_X \alpha_f)(Y, Z) = (\bar{\nabla}_Y \alpha_f)(X, Z) \quad (\text{C})$$

$$R^D(X, Y)\zeta = \alpha_f(X, A_\zeta^f Y) - \alpha_f(A_\zeta^f X, Y), \quad (\text{R})$$



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$$R^D(X, Y)\zeta = \alpha_f(X, A_\zeta^f Y) - \alpha_f(A_\zeta^f X, Y), \quad (R)$$

where we put

$$(\bar{\nabla}_X \alpha_f)(Y, Z) = D_X^f \alpha_f(Y, Z) - \alpha_f(\nabla_X Y, Z) - \alpha_f(Y, \nabla_X Z)$$

and $(X \wedge Y)Z = g(Y, Z)X - g(X, Z)Y$.



Section 1.2:

Biconservative Submanifolds



Biharmonic Maps

Consider a smooth map $\psi : (M, g) \rightarrow (N, \tilde{g})$.



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Bienergy Functional

The bienergy functional is defined by

$$E_2(\psi) = \int_M |\tau(\psi)|^2 dv$$



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Biharmonic map

A mapping ψ is said to be biharmonic if it is a critical point of the energy functional E_2 .



Biharmonic Mappings

In ¹G.Y. Jiang studied the first and second variation formulas of E_2 in order to understand its critical points, called biharmonic maps (See also ²).

¹G. Y. Jiang, *2-harmonic maps and their first and second variational formulas*, 1986.

²G. Y. Jiang, *2-harmonic isometric immersions between Riemannian manifolds*, 1986.



Biharmonic Mappings

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He proved that a mapping $\psi : M \rightarrow N$ is biharmonic if and only if the associated Euler-Lagrange equation

$$\tau_2(\psi) = 0$$

is satisfied, where

$$\tau_2(\psi) = \Delta\tau(\psi) - \text{trace } \tilde{R}(d\psi, \tau(\psi))d\psi$$

is the bi-tension field.

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Remark

It is obvious that a harmonic map is biharmonic.

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Biharmonic immersions

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Biharmonic immersions

Let $f : (\Omega, g) \hookrightarrow (N, \tilde{g})$ be an isometric immersion. In this case, we have

$$\tau_2(f) = 0 \Leftrightarrow \begin{cases} m\nabla\|H\|^2 + 4 \operatorname{trace} A_{\nabla^\perp H}(\cdot) + 4 \operatorname{trace} (\tilde{R}(\cdot, H)\cdot)^T = 0, & (\text{T}) \\ \operatorname{trace} \alpha_f(A_H(\cdot), \cdot) - \Delta^\perp H + \operatorname{trace} (\tilde{R}(\cdot, H)\cdot)^\perp = 0 & (\perp), \end{cases}$$

where we simply put $A^f = A$ and $H = H_f$.



Biconservative Immersions

Definition

An immersion $\psi : (M, g) \hookrightarrow (N, \tilde{g})$ is said to be biconservative if the equation

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Biharmonic Immersions

Every biharmonic immersion is biconservative.



Section 1.3:

Hypersurfaces of Riemannian Space Forms



Biconservative Hypersurfaces

In ³, we study biconservative hypersurfaces of non-flat Riemannian space forms.

- When $N = R_r^n(c)$, we have $\text{trace}(\tilde{R}(\cdot, H)\cdot)^T = 0$

³[nCt, Upadhyay, Mathematische Nachrichten, 2019]



Biconservative Hypersurfaces

In ³, we study biconservative hypersurfaces of non-flat Riemannian space forms.

- When $N = R_r^n(c)$, we have $\text{trace}(\tilde{R}(\cdot, H)\cdot)^T = 0$
- Therefore, the biconservativity equation

$$m\nabla\|H\|^2 + 4\text{trace}A_{D,H}(\cdot) + 4\text{trace}(\tilde{R}(\cdot, H)\cdot)^T = 0, \quad (\text{T})$$

turns into

$$S(\nabla H) = -\frac{nH}{2}\nabla H. \quad (\text{T})$$

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Proposition

We assume that H is not constant.



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Proposition

A hypersurface of $N = R^{n+1}(c)$ is biconservative if and only if

$$S = \begin{pmatrix} -\frac{nH}{2} & & & \\ & k_2 & & \\ & & \ddots & \\ & & & k_n \end{pmatrix}$$

for a function H such that $e_i(H) = 0$, $i = 2, 3, \dots, n$.



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We have the following parametrization of the hypersurface M :

Theorem

Let M be a proper biconservative hypersurface of $R^{n+1}(c)$, $c \in \{-1, 1\}$ with the mean curvature H and $m \in M$.



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If $c = -1$, assume that $H(m) \neq 2/n$.



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$$x(s, t_1, t_2, \dots, t_{n-1}) = \Theta(t_1, t_2, \dots, t_{n-1}) + \alpha_1(s)\xi_1(t_1, t_2, \dots, t_{n-1}) + \alpha_2(s)\xi_2(t_1, t_2, \dots, t_{n-1}) + \alpha_3(s)\xi_3(t_1, t_2, \dots, t_{n-1})$$

for any parallel, orthonormal base $\{\xi_1, \xi_2, \xi_3\}$ of the normal space of \hat{M} in $E(n+1, c)$.



Biconservative hypersurfaces of \mathbb{H}^4



$$x(s, t, u) = (\alpha_1(s), \alpha_2(s) \cos t, \alpha_2(s) \sin t, \alpha_3(s) \cos u, \alpha_3(s) \sin u),$$



$$x(s, t, u) = (\alpha_1(s) \cosh u, \alpha_1(s) \sinh u, \alpha_2(s) \cos t, \alpha_2(s) \sin t, \alpha_3(s)),$$



$$x(s, t, u) = \left(\frac{aA(s)^2 + a}{s} + asu^2 + \frac{s}{4a}, su, A(s) \cos t, A(s) \sin t, \frac{aA(s)^2 + a}{s} + asu^2 - \frac{s}{4a} \right)$$



$$x(s, t, u) = \left(\frac{aA(s)^2}{s} + as(t^2 + u^2) + \frac{s}{4a} + \frac{a}{s}, st, su, A(s), \frac{aA(s)^2}{s} + as(t^2 + u^2) - \frac{s}{4a} + \frac{a}{s} \right)$$



Section 2:

Hypersurfaces of \mathbb{E}_1^4



Shape Operator of Hypersurfaces I

Let M be a Lorentzian surface, $p \in M$ and A be a symmetric endomorphism of T_pM . Then, by choosing an appropriated base for T_pM , A can put into one of the following four canonical forms:

$$\text{Case (i). } A \sim \begin{bmatrix} a_1 & & & \\ & a_2 & & \\ & & \ddots & \\ & & & a_n \end{bmatrix},$$

with respect to an orthonormal base.

$$\text{Case (ii). } A \sim \begin{bmatrix} a_0 & & & & \\ -1 & a_0 & & & \\ & & a_1 & & \\ & & & \ddots & \\ & & & & a_{n-2} \end{bmatrix}$$

with respect to an pseudo-orthonormal base.



Shape Operator of Hypersurfaces II

$$\text{Case (iii). } A \sim \begin{bmatrix} a_0 & 0 & 0 & & & \\ 0 & a_0 & 1 & & & \\ -1 & 0 & a_0 & & & \\ & & & a_1 & & \\ & & & & \ddots & \\ & & & & & a_{n-3} \end{bmatrix},$$

with respect to an pseudo-orthonormal base.

$$\text{Case (iv). } A \sim \begin{bmatrix} a_0 & b_0 & & & & \\ -b_0 & a_0 & & & & \\ & & a_1 & & & \\ & & & \ddots & & \\ & & & & & a_{n-2} \end{bmatrix}.$$

with respect to an orthonormal base



Some References

- Biconservative hypersurfaces with diagonalizable shape operator were classified in ⁴
- Biharmonic hypersurfaces with non-diagonalizable shape operator were studied in ⁵
- Biconservative hypersurfaces with complex principle curvature were studied by ⁶

⁴[Fu, nCt, International Journal of Mathematics, 2015]

⁵[Arvanitoyeorgos, Kaimakamis, Magid, Illinois Journal of Mathematics, 2009]

⁶[Deepika, Mediterr. J. Math., 2017]



Section 2.1:

Uniqueness of Biconservative Hypersurfaces



Shape Operator of Biconservative Hypersurfaces

Assume that a hypersurface M in \mathbb{E}_1^4 with non-diagonalizable shape operator is proper biconservative. Then, we have

$$S(\text{grad } H) = \frac{-3H}{2} \text{grad } H. \quad (1)$$



Shape Operator of Biconservative Hypersurfaces

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$$S(\text{grad } H) = \frac{-3H}{2} \text{grad } H. \quad (1)$$

We have the following two cases subject to the causality of $\text{grad } H$:

Case (i). There exists a pseudo-orthonormal base field $\{e_1, e_2, e_3\}$ such that

$$S \sim \begin{bmatrix} -3H/2 & 1 & 0 \\ 0 & -3H/2 & 0 \\ 0 & 0 & 6H \end{bmatrix}, \quad (2)$$

where the **null vector** e_1 is proportional to $\text{grad } H$.



Shape Operator of Biconservative Hypersurfaces

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where the **null vector** e_1 is proportional to $\text{grad } H$.

Case (ii). There exists a pseudo-orthonormal base field $\{e_1, e_2, e_3\}$ such that

$$S \sim \begin{bmatrix} 9H/4 & 1 & 0 \\ 0 & 9H/4 & 0 \\ 0 & 0 & -3H/2 \end{bmatrix}, \quad (3)$$

where the **space-like vector** e_3 is proportional to $\text{grad } H$.



Sketch Proof

Lemma

Let M be a proper biconservative hypersurface of \mathbb{E}_1^4 with non-diagonalized shape operator. Then, its shape operator s has the matrix representation

$$S \sim \begin{bmatrix} 9H/4 & 1 & 0 \\ 0 & 9H/4 & 0 \\ 0 & 0 & -3H/2 \end{bmatrix}.$$



Main Theorem

Theorem

Let (Ω, g) be a 3-dimensional, connected Lorentzian manifold. If (Ω, g) admits two proper biconservative isometric immersion $x, \tilde{x} : (\Omega, g) \hookrightarrow \mathbb{E}_1^4$ with non-diagonalizable shape operator then there exists an isometry $\tau : \mathbb{E}_1^4 \rightarrow \mathbb{E}_1^4$ such that $\tilde{x} = \tau \circ x$.



Sketch Proof

Assume the existence of $x : (\Omega, g) \hookrightarrow \mathbb{E}_1^4$ with the shape operator

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We first prove that H, e_1, e_2, e_3 can be obtained intrinsically:



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- It turns out that the scalar curvature of is $S = \frac{27}{16} H^2$



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- It turns out that the scalar curvature of is $S = \frac{27}{16} H^2$
- Then, we obtain $e_3 = x_* E_3$, where

$$E_3 = \frac{\text{grad } S}{\|\text{grad } S\|}.$$



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- Then, we obtain $e_3 = x_* E_3$, where

$$E_3 = \frac{\text{grad } S}{\|\text{grad } S\|}.$$

- Finally, we proved that $e_1 = x_* E_1$, $e_2 = x_* E_2$, where E_1, E_2 are the only vectors satisfying

$$\begin{aligned} R(E_1, E_3)E_1 &= 0, & R(E_3, E_2)E_3 &= -\frac{3H}{2}E_1, \\ R(E_2, E_3)E_2 &= \frac{3H}{2}E_3. & & \end{aligned}$$



Section 2.2:

Local Classification



Construction of Hypersurface



Construction of Hypersurface

Let α be a null curve which admits a pseudo-orthonormal base $\{T, U, \alpha_1, \alpha_2\}$ such that

$$\begin{aligned}\alpha' &= T, \\ T' &= A_2\alpha_2 + A_1T, \\ U' &= A_3\alpha_1 + A_4\alpha_2 - A_1U, \\ \alpha_1' &= A_3T, \\ \alpha_2' &= A_2U + A_4T\end{aligned}$$

for some smooth functions A_j .



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for some smooth functions A_j .
Consider the hypersurface

$$g(s, u, w) = \alpha(s) + uT(s) + w\alpha_1(s) + f(w)\alpha_2(s),$$

where f is a smooth function.



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Construction of Hypersurface

$$g(s, u, w) = \alpha(s) + uT(s) + w\alpha_1(s) + f(w)\alpha_2(s),$$

The shape operator of this hypersurface has the form

$$\begin{pmatrix} \frac{1}{f(w)\sqrt{f'(w)^2+1}} & -\frac{A_3(s)(w+f(w)f'(w))+1}{f(w)^2 A_2(s)\sqrt{f'(w)^2+1}} & 0 \\ 0 & \frac{1}{f(w)\sqrt{f'(w)^2+1}} & 0 \\ 0 & 0 & -\frac{f''(w)}{(f'(w)^2+1)^{3/2}} \end{pmatrix}.$$

Therefore, this hypersurface is biconservative if and only if

$$-3f(w)f''(w) + 2f'(w)^2 + 2 = 0$$



Local Classification Result

Theorem

A hypersurface M in \mathbb{E}_1^4 with non-diagonalizable shape operator is proper biconservative if and only if it is locally congruent to the hypersurface previously constructed



Section 3:

Biconservative Hypersurfaces in Euclidean Spaces



Biconservative Hypersurfaces

Let $f : (\Omega, g) \rightarrow \mathbb{E}^{n+1}$ be a proper biconservative immersion, where (Ω, g) is an n dimensional Riemannian manifold. Then, we have

$$S(\text{grad } H) = \frac{-nH}{2} \text{grad } H.$$



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Therefore,

- $e_1 = \frac{\text{grad } H}{\|\text{grad } H\|}$ is a principle direction of f
- with the corresponding principle curvature

$$k_1 = \frac{-nH}{2}.$$



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- with the corresponding principle curvature

$$k_1 = \frac{-nH}{2}.$$

Consider an orthonormal frame field $\{e_1, e_2, \dots, e_n\}$ of $T\Omega$ such that

$$S e_i = k_i e_i.$$

Corollary

f is biconservative if and only if

$$-3k_1 + k_2 + \dots + k_n = 0 \text{ and } e_a(k_1) = 0, \quad a = 2, 3, \dots, n.$$



Uniqueness Theorem

Theorem

Let (Ω, g) be an n -dimensional, connected Riemannian manifold. If (Ω, g) admits two proper biconservative isometric immersion $f, \tilde{f} : (\Omega, g) \hookrightarrow \mathbb{E}^{n+1}$, then there exists an isometry $\tau : \mathbb{E}^{n+1} \rightarrow \mathbb{E}^{n+1}$ such that $\tilde{f} = \tau \circ f$.



Sketch Proof

We try to determine e_1, e_2, \dots, e_n intrinsically.

Consider the Ricci tensor Ric of (Ω, g) defined to be

$$\text{Ric}(X) = \text{tr}(R(\cdot, X)\cdot).$$



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Consider the Ricci tensor Ric of (Ω, g) defined to be

$$\text{Ric}(X) = \text{tr}(R(\cdot, X)\cdot).$$

Then, by the Gauss equation, we have

- $\text{Ric}(e_1) = -3k_1^2 e_1$
- $\text{Ric}(e_a) = (2k_1 k_1 + k_a^2) e_a$



Sketch Proof

We try to determine e_1, e_2, \dots, e_n intrinsically.

Consider the Ricci tensor Ric of (Ω, g) defined to be

$$\text{Ric}(X) = \text{tr}(R(\cdot, X)\cdot).$$

Then, by the Gauss equation, we have

- $\text{Ric}(e_1) = -3k_1^2 e_1$
- $\text{Ric}(e_a) = (2k_1 k_1 + k_a^2) e_a$

Let $\lambda_1, \lambda_2, \dots, \lambda_n$ denote the eigenvectors of Ric .



Sketch Proof

Note that $X = e_1$ satisfies

$$\nabla_X X = 0,$$

$$\text{Ric}(X) = \lambda X,$$

$$Y(\lambda) = 0$$

whenever $g(X, Y) = 0,$

$$\nabla_Y X = a_Y Y$$

whenever $\text{Ric}(Y) = \zeta Y.$



Sketch Proof

Note that $X = e_1$ satisfies

$$\begin{aligned} \nabla_X X &= 0, & \text{Ric}(X) &= \lambda X, \\ & & Y(\lambda) &= 0 && \text{whenever } g(X, Y) = 0, \\ & & \nabla_Y X &= a_Y Y && \text{whenever Ric}(Y) = \zeta Y. \end{aligned}$$

By a computation we proved that

Claim

If X is a unit tangent vector field satisfying the properties above, then either $X = e_1$ or $X = -e_1$.



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Claim

If X is a unit tangent vector field satisfying the properties above, then either $X = e_1$ or $X = -e_1$.

Consequently, e_1 and $k_1 = \sqrt{-\lambda_1/3}$ can be determined intrinsically.



Sketch Proof

Next, in order to determine k_a , we consider the map

$$L : (\langle e_1 \rangle)^\perp \rightarrow (\langle e_1 \rangle)^\perp, LX = \nabla_X e_1.$$

Note that, by using Codazzi equations, we have

$$e_a \text{ is a principle curvature} \Leftrightarrow Le_a = \mu_a e_a.$$



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By a further computation we observe that k_a can be determined by using the equations

$$\begin{aligned} k_a &= -k_1 + \varepsilon \sqrt{k_1^2 + \lambda_a} \\ 2k_a \mu_a + e_1(k_1) &= \varepsilon \left(\mu_a \sqrt{k_1^2 + \lambda_a} + e_1(\sqrt{k_1^2 + \lambda_a}) \right). \end{aligned}$$



THANK YOU