

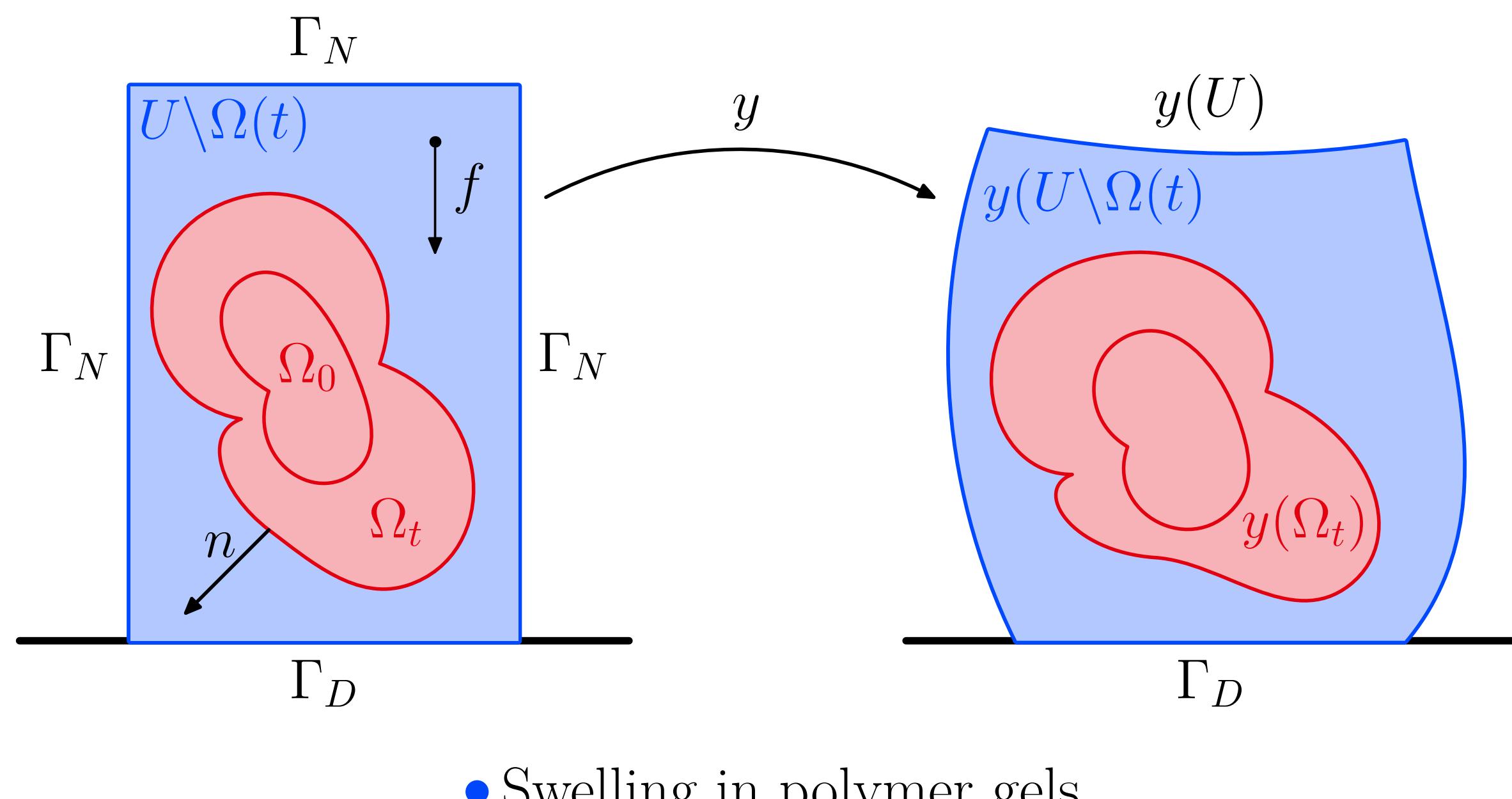
# Viscoelasticity and accretive phase-change at finite strains

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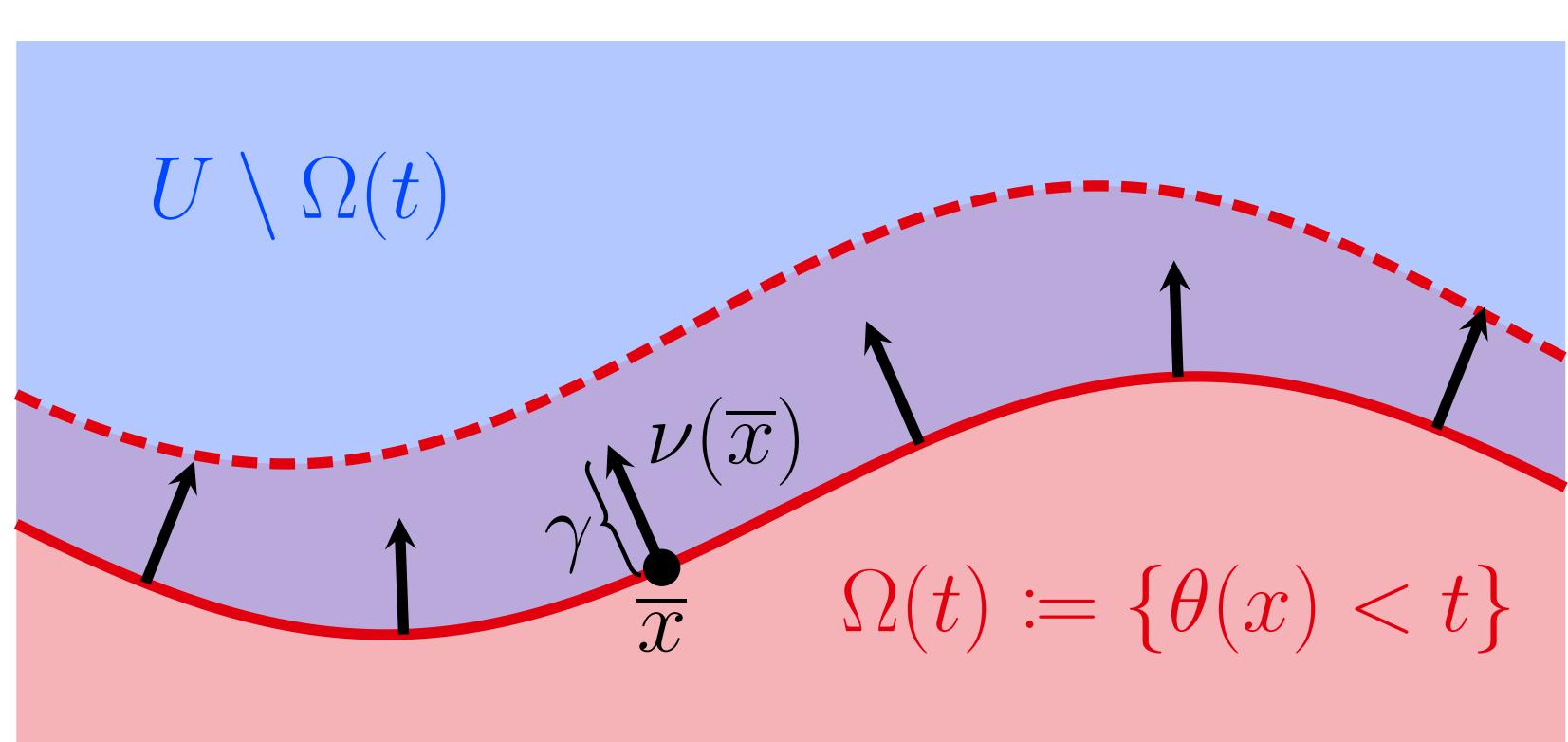
## The model

Evolution of a viscoelastic solid + phase change (accretive growth)



- Swelling in polymer gels
- Solidification processes
- Early tumor development

$$\left\{ \begin{array}{l} \text{Viscoelastic equilibrium} \\ -\operatorname{div}(\partial_{\nabla y} W_{\varepsilon}(\theta(x)-t, \nabla y) + \partial_{\nabla \dot{y}} R_{\varepsilon}(\theta(x)-t, \nabla y, \nabla \dot{y}) - \operatorname{div} D H(\nabla^2 y)) \\ = f(\theta(x)-t, x) \quad \text{in } [0, T] \times U, \\ \text{Boundary and initial conditions} \\ \gamma(y(\theta(x), x), \nabla y(\theta(x), x)) |\nabla(-\theta)(x)| = 1 \quad \text{in } U \setminus \overline{\Omega_0}, \\ \theta = 0 \quad \text{on } \Omega_0. \end{array} \right.$$



## Definition (Weak/viscosity solution)

$$(y, \theta) \in (L^\infty(0, T; W^{2,p}(U; \mathbb{R}^d)) \cap H^1(0, T; H^1(U; \mathbb{R}^d))) \times C^{0,1}(\overline{U})$$

is a *weak/viscosity solution* to the initial-boundary-value problem if  $\det \nabla y(t, \cdot) > 0$  for all  $t \in (0, T)$ ,  $y(0, \cdot) = y_0$ , and

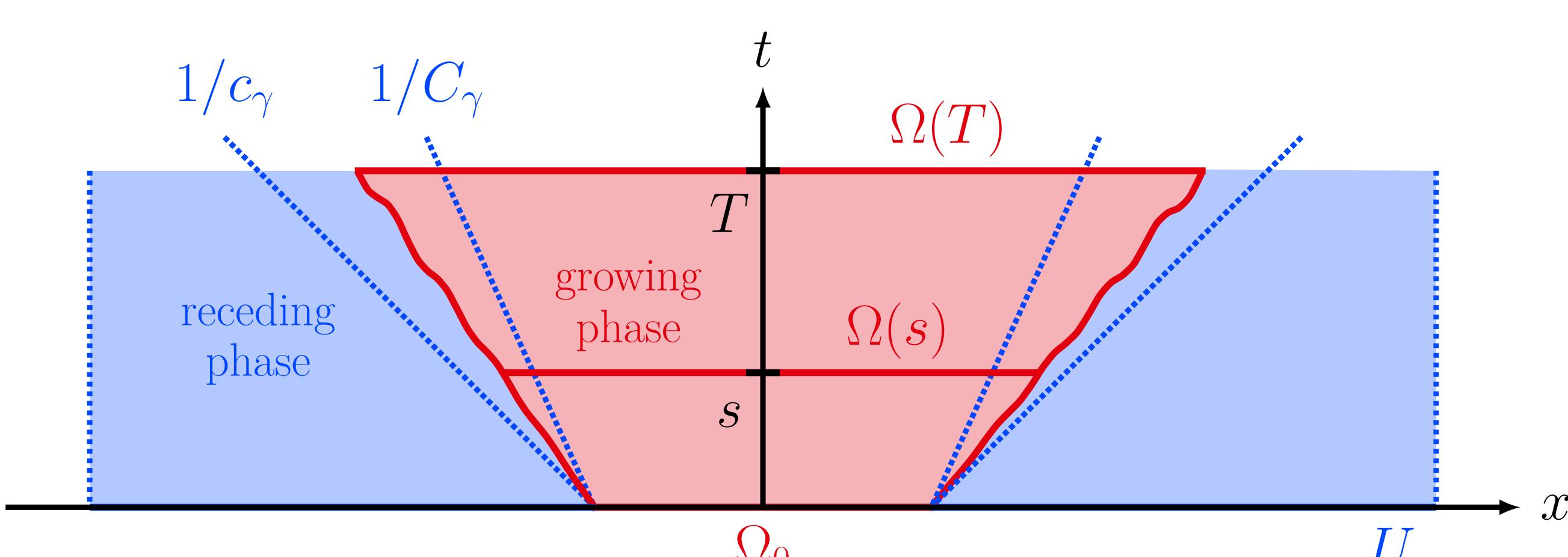
$$\begin{aligned} & \int_0^T \int_U (\partial_F W_{\varepsilon}(\theta-t, \nabla y) : \nabla z + \partial_F R_{\varepsilon}(\theta-t, \nabla y, \nabla \dot{y}) : \nabla z + D H(\nabla^2 y) : \nabla^2 z) dx dt \\ &= \int_0^T \int_U f(\theta-t) \cdot z dx dt \quad \forall z \in C^\infty(\overline{Q}; \mathbb{R}^d) \text{ with } z = 0 \text{ on } \Sigma_D, \end{aligned}$$

and  $\theta$  is a *viscosity* solution to

$$\left\{ \begin{array}{l} \gamma(y(\theta(x), x), \nabla y(\theta(x), x)) |\nabla(-\theta)(x)| = 1 \quad \text{in } U \setminus \overline{\Omega_0}, \\ \theta = 0 \quad \text{in } \Omega_0. \end{array} \right.$$

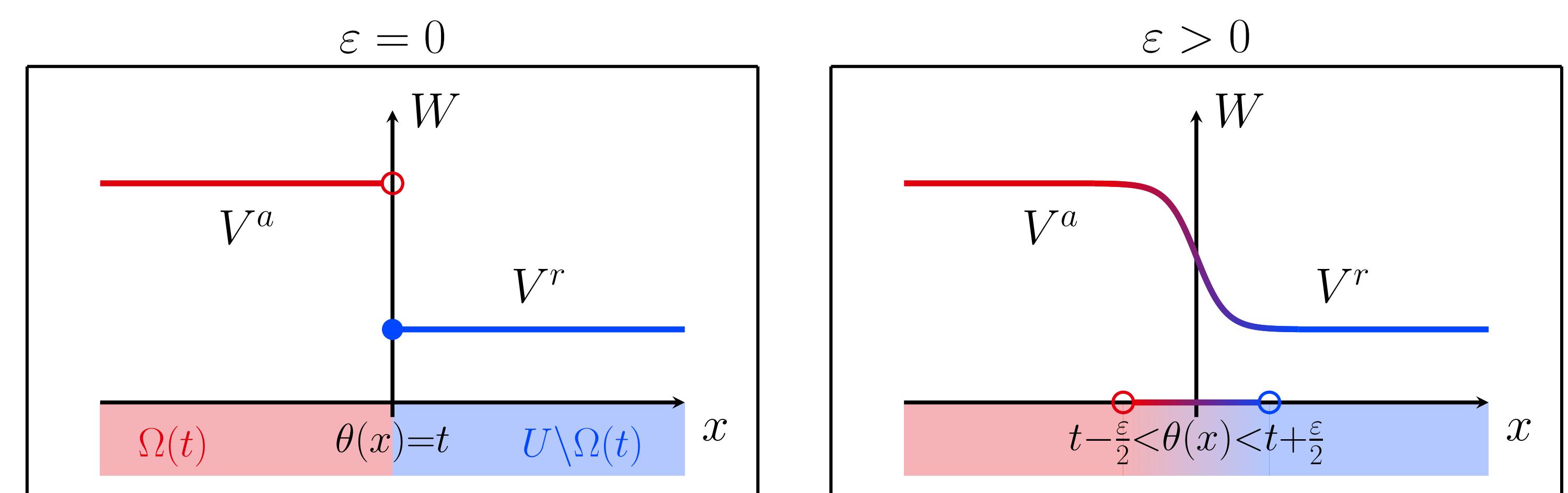
## Assumptions: growth

- $\gamma \in C^{0,1}(\mathbb{R}^d \times \operatorname{GL}_+(d))$  with  $0 < c_\gamma \leq \gamma(\cdot) \leq C_\gamma$



## Assumptions: viscoelasticity

- $W_{\varepsilon}(\sigma, F) := (1 - h_{\varepsilon}(\sigma))V^a(F) + h_{\varepsilon}(\sigma)V^r(F) + V^J(F)$
- $V^a, V^r, V^J \in C^1(\operatorname{GL}_+(d); [0, \infty))$
- $V^a(F), V^r(F) \geq c_W |F|^p - \frac{1}{c_W}$
- $V^a(F) - V^r(F) \leq \frac{1}{c_W}(1 + |F|^p)$
- $\exists q > \frac{pd}{p-d} : V^J(F) \geq \frac{c_W}{(\det F)^q}$



- $R_{\varepsilon}(\sigma, \dot{F}) := (1 - h_{\varepsilon}(\sigma))R^a(F, \dot{F}) + h_{\varepsilon}(\sigma)R^r(F, \dot{F})$
- $R^i(F, \dot{F}) := \frac{1}{2}\dot{C}:\mathbb{D}^i(C):\dot{C}, \quad i = a, r, C := F^\top F, \dot{C} := \dot{F}^\top F + F^\top \dot{F}$
- $H(G) = |G|^p, \quad p > d$
- $f \in W^{1,\infty}(\mathbb{R}; L^2(U; \mathbb{R}^d))$

## Theorem (Existence and energy equality) [1]

For all given  $\varepsilon \geq 0$  there exists a weak/viscosity solution  $(y_\varepsilon, \theta_\varepsilon)$  and  $(y_\varepsilon, \theta_\varepsilon) \rightarrow (y_0, \theta_0)$  uniformly as  $\varepsilon \rightarrow 0$ .

Moreover, in the diffused-interface case  $\varepsilon > 0$ ,  $(y, \theta)$  fulfills for all  $t \in [0, T]$

$$\begin{aligned} & \int_U (W_{\varepsilon}(\theta-t, \nabla y) + H(\nabla^2 y) - f(\theta-t) \cdot y) - (W_{\varepsilon}(\theta, \nabla y_0) + H(\nabla^2 y_0) - f(\theta) \cdot y_0) dx \\ &= - \int_0^t \int_U 2R_{\varepsilon}(\theta-s, \nabla y, \nabla \dot{y}) + \dot{f}(\theta-s) \cdot y dx ds - \int_0^t \int_U \partial_\sigma W_{\varepsilon}(\theta-s, \nabla y) dx ds. \end{aligned}$$

In the sharp-interface case  $\varepsilon = 0$ , for all  $t \in [0, T]$ ,

$$\begin{aligned} & \int_U (W_0(\theta-t, \nabla y) + H(\nabla^2 y) - f(\theta-t) \cdot y) - (W_0(\theta, \nabla y_0) + H(\nabla^2 y_0) - f(\theta) \cdot y_0) dx \\ &= - \int_0^t \int_U 2R_0(\theta-s, \nabla y, \nabla \dot{y}) + \dot{f}(\theta-s) \cdot y dx ds + \int_0^t \int_{\{\theta=s\}} \frac{V^a(\nabla y) - V^r(\nabla y)}{|\nabla \theta|} d\mathcal{H}^{d-1} ds. \end{aligned}$$

## What comes next?

- Backstrain
- One phase problem
- Temperature
- Different growth models

## References

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