

Viscoelasticity and accretive phase-change at finite strains

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Taming Complexity in
Partial Differential Systems



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of Mathematics



Outline

- Model
- Assumptions
- Existence result

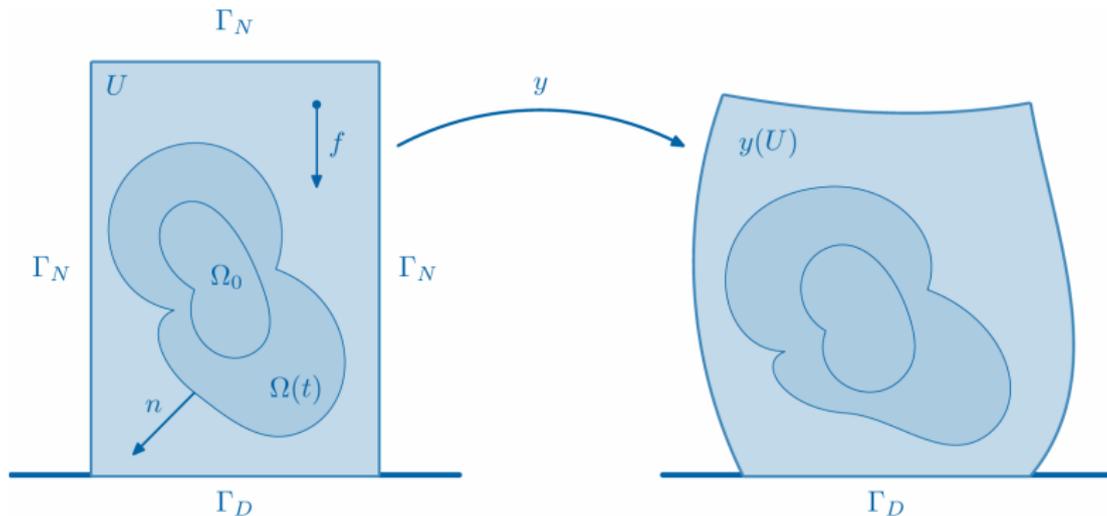
Model



Evolution of a viscoelastic solid + phase change (accretive growth)

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- Swelling in polymer gels
- Solidification processes
- Early tumor development



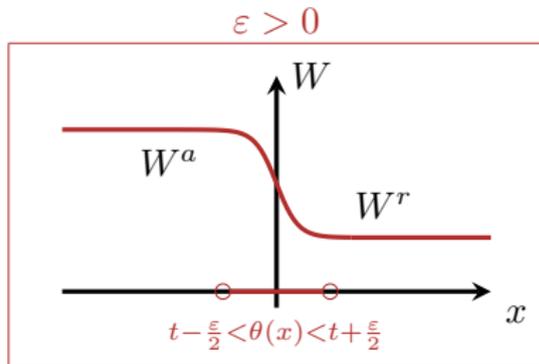
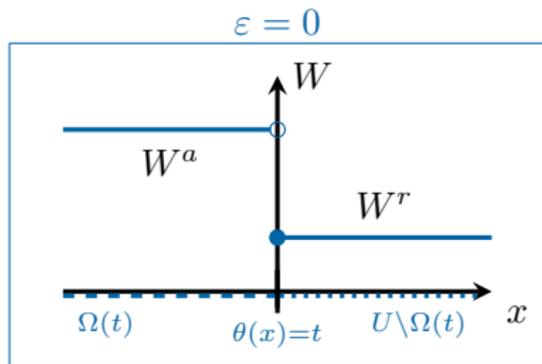


Evolution of a viscoelastic solid

$$\left\{ \begin{array}{l} -\operatorname{div} (\partial_{\nabla y} W_\varepsilon(\theta(x)-t, \nabla y) + \partial_{\nabla \dot{y}} R_\varepsilon(\theta(x)-t, \nabla y, \nabla \dot{y}) - \operatorname{div} DH(\nabla^2 y)) \\ \quad = f(\theta(x)-t, x) \quad \text{in } [0, T] \times U, \\ \text{Boundary and initial conditions} \end{array} \right.$$

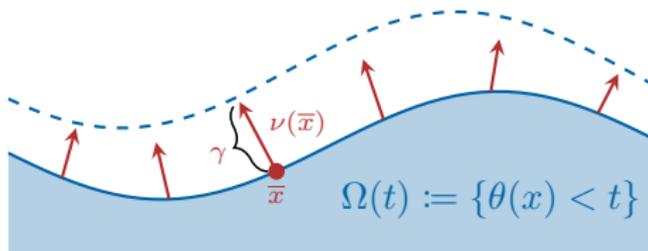
Evolution of a viscoelastic solid + phase change (accretive growth)

$$\left\{ \begin{array}{l} -\operatorname{div}(\partial_{\nabla y} W_\varepsilon(\theta(x)-t, \nabla y) + \partial_{\nabla \dot{y}} R_\varepsilon(\theta(x)-t, \nabla y, \nabla \dot{y})) - \operatorname{div} DH(\nabla^2 y) \\ \quad = f(\theta(x)-t, x) \quad \text{in } [0, T] \times U, \\ \text{Boundary and initial conditions} \\ \\ \Omega(t) := \{x \in U \mid \theta(x) < t\} \end{array} \right.$$



Evolution of a viscoelastic solid + phase change (accretive growth)

$$\left\{ \begin{array}{l} -\operatorname{div} (\partial_{\nabla y} W_\varepsilon(\theta(x)-t, \nabla y) + \partial_{\nabla \dot{y}} R_\varepsilon(\theta(x)-t, \nabla y, \nabla \dot{y})) - \operatorname{div} DH(\nabla^2 y) \\ \quad = f(\theta(x)-t, x) \quad \text{in } [0, T] \times U, \\ \text{Boundary and initial conditions} \\ \gamma(y(\theta(x), x), \nabla y(\theta(x), x)) | \nabla(-\theta)(x)| = 1 \quad \text{in } U \setminus \overline{\Omega_0}, \\ \theta = 0 \quad \text{on } \Omega_0. \end{array} \right.$$



Definition (Weak/viscosity solution)

$$(y, \theta) \in (L^\infty(0, T; W^{2,p}(U; \mathbb{R}^d)) \cap H^1(0, T; H^1(U; \mathbb{R}^d))) \times C^{0,1}(\bar{U})$$

is a *weak/viscosity solution* to the initial-boundary-value problem if $\det \nabla y(t, \cdot) > 0$ for all $t \in (0, T)$, $y(0, \cdot) = y_0$, and

$$\begin{aligned} & \int_0^T \int_U (\partial_F W_\varepsilon(\theta-t, \nabla y) : \nabla z + \partial_{\bar{F}} R_\varepsilon(\theta-t, \nabla y, \nabla \dot{y}) : \nabla z + DH(\nabla^2 y) : \nabla^2 z) dx dt \\ & = \int_0^T \int_U f(\theta-t) \cdot z dx dt \quad \forall z \in C^\infty(\bar{Q}; \mathbb{R}^d) \text{ with } z = 0 \text{ on } \Sigma_D, \end{aligned}$$

and θ is a *viscosity solution* to

$$\begin{cases} \gamma(y(\theta(x), x), \nabla y(\theta(x), x)) |\nabla(-\theta)(x)| = 1 & \text{in } U \setminus \bar{\Omega}_0, \\ \theta = 0 & \text{in } \Omega_0. \end{cases}$$

Assumptions



$$\int_0^T \int_U (\partial_F W_\varepsilon(\theta-t, \nabla y) + \partial_{\dot{F}} R_\varepsilon(\theta-t, \nabla y, \nabla \dot{y})) : \nabla z + DH(\nabla^2 y) : \nabla^2 z - f(\theta-t) \cdot z = 0$$

$$R_\varepsilon(\sigma, F, \dot{F}) := (1 - h_\varepsilon(\sigma)) R^a(F, \dot{F}) + h_\varepsilon(\sigma) R^r(F, \dot{F})$$

$$R^*(F, \dot{F}) := \frac{1}{2} \dot{C} : \mathbb{D}^*(C) : \dot{C}, \quad C := F^\top F, \quad \dot{C} := \dot{F}^\top F + F^\top \dot{F}$$

$$H(G) = |G|^p, \quad p > d$$

$$f \in W^{1,\infty}(\mathbb{R}; L^2(U; \mathbb{R}^d))$$



Assumptions: viscoelastic evolution

$$\int_0^T \int_U (\partial_F W_\varepsilon(\theta-t, \nabla y) + \partial_{\dot{F}} R_\varepsilon(\theta-t, \nabla y, \nabla \dot{y})) : \nabla z + DH(\nabla^2 y) : \nabla^2 z - f(\theta-t) \cdot z = 0$$

$$W_\varepsilon(\sigma, F) := (1 - h_\varepsilon(\sigma))V^a(F) + h_\varepsilon(\sigma)V^r(F) + V^J(F)$$

$$V^a, V^r, V^J \in C^1(\text{GL}_+(d); [0, \infty))$$

$$V^a(F), V^r(F) \geq c_W |F|^p - \frac{1}{c_W}$$

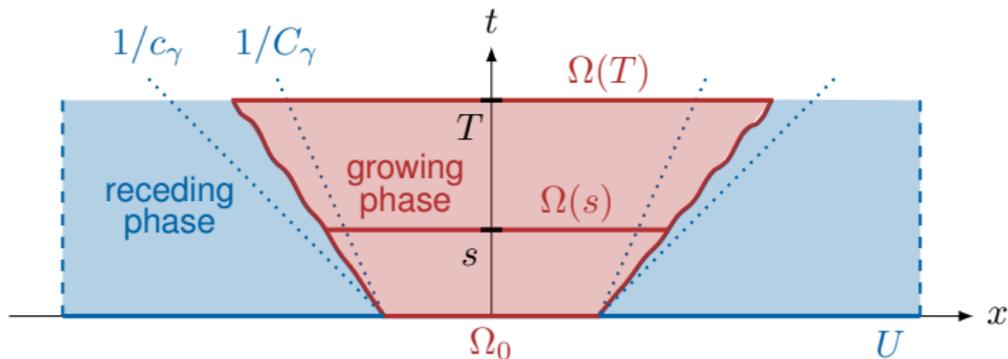
$$V^a(F) - V^r(F) \leq \frac{1}{c_W} (1 + |F|^p)$$

$$\exists q > \frac{pd}{p-d} : V^J(F) \geq \frac{c_W}{(\det F)^q}$$



$$\begin{cases} \gamma(y(\theta(x), x), \nabla y(\theta(x), x)) |\nabla(-\theta)(x)| = 1 & \text{in } U \setminus \overline{\Omega_0} \\ \theta = 0 & \text{in } \Omega_0 \subset\subset U \end{cases}$$

$\gamma \in C^{0,1}(\mathbb{R}^d \times \text{GL}_+(d))$ with $0 < c_\gamma \leq \gamma(\cdot) \leq C_\gamma$



Existence result



Main result

Theorem (Existence and Energy equality)

*For all given $\varepsilon \geq 0$ there exists a weak/viscosity solution $(y_\varepsilon, \theta_\varepsilon)$
and $(y_\varepsilon, \theta_\varepsilon) \rightarrow (y_0, \theta_0)$ as $\varepsilon \rightarrow 0$.*

Theorem (Existence and Energy equality)

For all given $\varepsilon \geq 0$ there exists a weak/viscosity solution $(y_\varepsilon, \theta_\varepsilon)$
and $(y_\varepsilon, \theta_\varepsilon) \rightarrow (y_0, \theta_0)$ as $\varepsilon \rightarrow 0$.

Moreover, in the diffused-interface case $\varepsilon > 0$, (y, θ) fulfills for all $t \in [0, T]$

$$\int_U (W_\varepsilon(\theta-t, \nabla y) + H(\nabla^2 y) - f(\theta-t) \cdot y) - (W_\varepsilon(\theta, \nabla y_0) + H(\nabla^2 y_0) - f(\theta) \cdot y_0) \, dx \\ = - \int_0^t \int_U 2R_\varepsilon(\theta-s, \nabla y, \nabla \dot{y}) + \dot{f}(\theta-s) \cdot y \, dx \, ds - \int_0^t \int_U \partial_\sigma W_\varepsilon(\theta-s, \nabla y) \, dx \, ds.$$

In the sharp-interface case $\varepsilon = 0$, for all $t \in [0, T]$,

$$\int_U (W_0(\theta-t, \nabla y) + H(\nabla^2 y) - f(\theta-t) \cdot y) - (W_0(\theta, \nabla y_0) + H(\nabla^2 y_0) - f(\theta) \cdot y_0) \, dx \\ = - \int_0^t \int_U 2R_0(\theta-s, \nabla y, \nabla \dot{y}) + \dot{f}(\theta-s) \cdot y \, dx \, ds + \int_0^t \int_{\{\theta=s\}} \frac{V^a(\nabla y) - V^r(\nabla y)}{|\nabla \theta|} \, d\mathcal{H}^{d-1} \, ds.$$



Energy inequality estimate

$$\begin{aligned} & \int_U (W_0(\theta-t, \nabla y) + H(\nabla^2 y) - f(\theta-t) \cdot y) - (W_0(\theta, \nabla y_0) + H(\nabla^2 y_0) - f(\theta) \cdot y_0) \, dx \\ &= - \int_0^t \int_U 2R_0(\theta-s, \nabla y, \nabla \dot{y}) + \dot{f}(\theta-s) \cdot y \, dx \, ds + \int_0^t \int_{\{\theta=s\}} \frac{V^a(\nabla y) - V^r(\nabla y)}{|\nabla \theta|} \, d\mathcal{H}^{d-1} \, ds \end{aligned}$$

$$\|y(t)\|_{W^{2,p}(U)}^p \lesssim \int_U (W_0(\theta-t, \nabla y) + H(\nabla^2 y)) \, dx + \int_0^t \int_U 2R_0(\theta-s, \nabla y, \nabla \dot{y}) \, dx \, ds$$



Energy inequality estimate

$$\int_U (W_0(\theta-t, \nabla y) + H(\nabla^2 y) - f(\theta-t) \cdot y) - (W_0(\theta, \nabla y_0) + H(\nabla^2 y_0) - f(\theta) \cdot y_0) \, dx$$

$$= - \int_0^t \int_U 2R_0(\theta-s, \nabla y, \nabla \dot{y}) + \dot{f}(\theta-s) \cdot y \, dx \, ds + \int_0^t \int_{\{\theta=s\}} \frac{V^a(\nabla y) - V^r(\nabla y)}{|\nabla \theta|} \, d\mathcal{H}^{d-1} \, ds$$

$$\|y(t)\|_{W^{2,p}(U)}^p \lesssim \int_U (W_0(\theta-t, \nabla y) + H(\nabla^2 y)) \, dx + \int_0^t \int_U 2R_0(\theta-s, \nabla y, \nabla \dot{y}) \, dx \, ds$$

$$\lesssim E_0 + \|f\|_{W^{1,\infty}(0,T;L^2(U))} + \int_0^t \int_{\{\theta=s\}} \frac{V^a(\nabla y) - V^r(\nabla y)}{|\nabla \theta|} \, d\mathcal{H}^{d-1} \, ds$$

$$\int_U (W_0(\theta-t, \nabla y) + H(\nabla^2 y) - f(\theta-t) \cdot y) - (W_0(\theta, \nabla y_0) + H(\nabla^2 y_0) - f(\theta) \cdot y_0) \, dx$$

$$= - \int_0^t \int_U 2R_0(\theta-s, \nabla y, \nabla \dot{y}) + \dot{f}(\theta-s) \cdot y \, dx \, ds + \int_0^t \int_{\{\theta=s\}} \frac{V^a(\nabla y) - V^r(\nabla y)}{|\nabla \theta|} \, d\mathcal{H}^{d-1} \, ds$$

$$\|y(t)\|_{W^{2,p}(U)}^p \lesssim \int_U (W_0(\theta-t, \nabla y) + H(\nabla^2 y)) \, dx + \int_0^t \int_U 2R_0(\theta-s, \nabla y, \nabla \dot{y}) \, dx \, ds$$

$$\lesssim E_0 + \|f\|_{W^{1,\infty}(0,T;L^2(U))} + \int_0^t \int_{\{\theta=s\}} \frac{V^a(\nabla y) - V^r(\nabla y)}{|\nabla \theta|} \, d\mathcal{H}^{d-1} \, ds$$

$$\lesssim \int_0^t \|\nabla y(s)\|_{L^\infty(U)}^p \int_{\{\theta=s\}} \, d\mathcal{H}^{d-1} \, ds \lesssim \int_0^t \|y(s)\|_{W^{2,p}(U)}^p \int_{\{\theta=s\}} \, d\mathcal{H}^{d-1} \, ds$$

control from above

$$\begin{aligned} & \int_U (W_0(\theta-t, \nabla y) + H(\nabla^2 y) - f(\theta-t) \cdot y) - (W_0(\theta, \nabla y_0) + H(\nabla^2 y_0) - f(\theta) \cdot y_0) \, dx \\ &= - \int_0^t \int_U 2R_0(\theta-s, \nabla y, \nabla \dot{y}) + \dot{f}(\theta-s) \cdot y \, dx \, ds + \int_0^t \int_{\{\theta=s\}} \frac{V^a(\nabla y) - V^r(\nabla y)}{|\nabla \theta|} \, d\mathcal{H}^{d-1} \, ds \end{aligned}$$

$$\begin{aligned} \|y(t)\|_{W^{2,p}(U)}^p &\lesssim \int_U (W_0(\theta-t, \nabla y) + H(\nabla^2 y)) \, dx + \int_0^t \int_U 2R_0(\theta-s, \nabla y, \nabla \dot{y}) \, dx \, ds \\ &\lesssim E_0 + \|f\|_{W^{1,\infty}(0,T;L^2(U))} + \int_0^t \int_{\{\theta=s\}} \frac{V^a(\nabla y) - V^r(\nabla y)}{|\nabla \theta|} \, d\mathcal{H}^{d-1} \, ds \\ &\lesssim \int_0^t \|\nabla y(s)\|_{L^\infty(U)}^p \int_{\{\theta=s\}} \, d\mathcal{H}^{d-1} \, ds \lesssim \int_0^t \|y(s)\|_{W^{2,p}(U)}^p \int_{\{\theta=s\}} \, d\mathcal{H}^{d-1} \, ds \end{aligned}$$

$$\stackrel{\text{Grönwall}}{\implies} \|y(t)\|_{W^{2,p}(U)}^p \lesssim \exp\left(\int_0^t \int_{\{\theta=s\}} \, d\mathcal{H}^{d-1} \, ds\right) \lesssim \exp(|\Omega(t)|)$$



What comes next?

- Backstrain
- Temperature
- One phase problem on a growing domain
- Different growth models

- [1] A. Chiesa, U. Stefanelli. Viscoelasticity and accretive phase-change at finite strains. *To appear in Z. Angew. Math. Phys.*
- [2] E. Davoli, K. Nik, U. Stefanelli, G. Tomassetti. An existence result for accretive growth in elastic solids. *Math. Models Methods Appl.* 34 (2024), no. 11, 2169–2190.
- [3] G. Zurlo, L. Truskinovsky. Inelastic surface growth. *Mech. Res. Comm.* 93 (2018), 174–179.

Thank you for your attention!
