



Adaptive Eigenvalue Computation for Elliptic Operators

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A Model Eigenvalue Problem

Poisson eigenvalue problem on $\Omega \subset \mathbb{R}^d$ with Dirichlet bc.:

$$-\Delta u = \lambda u, \quad u|_{\partial\Omega} = 0.$$

Weak formulation on $H_0^1(\Omega)$:

$$\underbrace{\int_{\Omega} \nabla u(x) \cdot \nabla v(x) \, dx}_{:=a(u,v)} = \lambda \underbrace{\int_{\Omega} u(x)v(x) \, dx}_{L_2(\Omega) \text{ inner product}}, \quad \text{for all } v \in H_0^1.$$

Properties of bilinear form $a : H_0^1(\Omega) \times H_0^1(\Omega) \rightarrow \mathbb{R}$:

- $a(u, v) = a(v, u)$ **symmetric**
- $a(u, v) \lesssim \|u\|_{H_0^1(\Omega)} \|v\|_{H_0^1(\Omega)}$ **bounded**
- $a(u, u) \gtrsim \|u\|_{H_0^1(\Omega)}^2$ **strongly positive**

for all $u, v \in H_0^1(\Omega)$.

$a(\cdot, \cdot)$ induces energy norm on $H_0^1(\Omega)$ equivalent to $\|\cdot\|_{H_0^1(\Omega)}$.

Abstract Eigenvalue Problems

Gelfand-triple of Hilbert- $(H, (\cdot, \cdot), |\cdot|)$ and Banach-space $(V, \|\cdot\|)$

$$V \xhookrightarrow{d} H \cong H^* \xhookrightarrow{d} V^*,$$

with dual pairing $\langle \cdot, \cdot \rangle$ on $V^* \times V$.

In model problem: $V = H_0^1(\Omega)$, $H = L_2(\Omega)$

Operator formulation:

$$Au = \lambda Eu \quad \text{in } V^*$$

with operators $A : V \rightarrow V^*$ and $E : H \rightarrow H^*$ such that

$$\langle Au, v \rangle = a(u, v), \quad \langle Eu, v \rangle = (u, v),$$

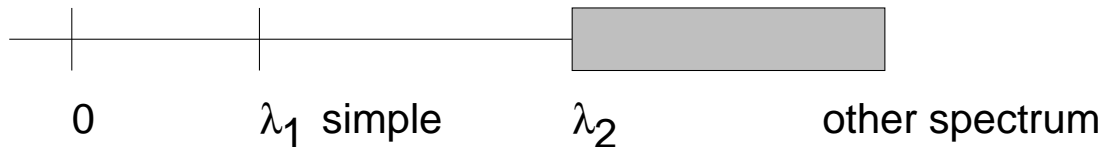
for given bounded, symmetric, strongly positive bilinear form $a : V \times V \rightarrow \mathbb{R}$.

In model problem: $A : H_0^1(\Omega) \rightarrow H^{-1}(\Omega)$.

Goal

Find lowest eigenpair (λ_1, u_1) of abstract eigenvalue problem

$$Au = \lambda Eu \quad \text{in } V^*.$$



Desired properties of algorithm:

- convergent with desired accuracy in finite number of steps,
- adaptive with quasi-optimal number of degrees of freedom,
- computational complexity linear in number of degrees of freedom.

Boundary value problems

Solution of boundary value problem

$$Au = f \quad \text{in } V^*$$

Optimal adaptive algorithm (Cohen/Dahmen/deVore 2001):

- Richardson-iteration with damping parameter γ^n :

$$u^{n+1} = u^n - \gamma^n B^{-1}(Au^n - f),$$

- stable wavelet-discretization for equivalent formulation in ℓ_2 ,
- approximation of operators (compressibility),
- nonlinear best N -term approximation.

Outline of the talk

- (I) Iteration scheme and perturbations
- (II) Numerical realization
- (III) Optimality
- (IV) (Preliminary) numerical results

Part I: Iteration scheme

Preconditioned inverse iteration

Steepest descent of Rayleigh-quotient

$$\mu(v) = \frac{\langle Av, v \rangle}{\langle Ev, v \rangle}, \quad \nabla \mu(v) \sim Av - \mu(v)Ev.$$

Recursion:

$$v' = v - \alpha B^{-1}(Av - \mu(v)Ev), \quad (\text{PINVIT})$$

Preconditioner $B : V \rightarrow V^*$ with

$$\delta_0 \langle Bv, v \rangle \leq \langle Av, v \rangle \leq \delta_1 \langle Bv, v \rangle$$

Perfect preconditioner ($B = A$):

$$v' = \alpha \mu(v) A^{-1} Ev.$$

Convergence of PINVIT (I)

Thm 1 (D'yakonov/Orekhov, 1980). *(matrix case)*

If $\mu(v) < \lambda_2$ then the error in the Rayleigh-quotient decreases like

$$\mu(v') - \lambda_1 \leq q \cdot (\mu(v) - \lambda_1), \quad q = q(\mu(v)) < 1,$$

from step to step, where the monotonically decreasing function $q(\mu)$ depends asymptotically only on δ_1/δ_0 and λ_2/λ_1 .

Improvements: Samokish (1958), Bramble/Knyacev/Pasciak (1996), Neymeyr (2001), Knyacev/Neymeyr (200x)

Convergence of PINVIT (II)

Thm 2 (Rohwedder/Schneider/Z., 2007). *(operator case)*

If $\mu(v) < \lambda_2$ then the error in the Rayleigh-quotient decreases like

$$\mu(v') - \lambda_1 \leq q \cdot (\mu(v) - \lambda_1), \quad q = q(\mu(v)) < 1,$$

from step to step, where the monotonically decreasing function $q(\mu)$ depends asymptotically only on δ_1/δ_0 and λ_2/λ_1 .

Sketch of proof.

Main estimate. Temple-Kato like inequality:

$$\|Av - \mu(v)Ev\|_{A^{-1}}^2 \geq \mu(v) \frac{(\mu(v) - \lambda_1)(\lambda_2 - \mu(v))}{\lambda_1 \lambda_2} |v|^2,$$

through spectral resolution. Rest of the proof: algebraic reasoning, analogously to D'yakonov/Orekhov (1980). □

Perturbed PINVIT

For every $\epsilon > 0$ perturbed preconditioned inverse iteration

$$v'_\epsilon = v - \alpha B^{-1}(A_\epsilon(v) - \mu_\epsilon(v)E_\epsilon(v)), \quad (\text{PPINVIT}).$$

with nonlinear approximations

$$\|A_\epsilon(v) - Av\|_* \leq \epsilon \|v\|, \quad |E_\epsilon(v) - Ev|_* \leq \epsilon |v|$$

and perturbed Rayleigh quotient

$$\mu_\epsilon(v) = \frac{\langle A_\epsilon(v), v \rangle}{\langle E_\epsilon(v), v \rangle}.$$

Convergence of PPINVIT (I)

Thm 3 (Rohwedder/Schneider/Z., 2007). *(perturbed scheme)*

If $\mu(v) < \lambda_2$ then the error in the Rayleigh-quotient decreases like

$$\mu(v'_\epsilon) - \lambda_1 \leq q \cdot (\mu(v) - \lambda_1) + C\epsilon, \quad q = q(\mu(v)) < 1,$$

from step to step, where the monotonically decreasing function $q(\mu)$ depends asymptotically only on δ_1/δ_0 and λ_2/λ_1 . C can be bounded independently of v and ϵ .

Sketch of proof.

Perturbation argument, i.e. bound perturbations by multiple of ϵ , e.g.

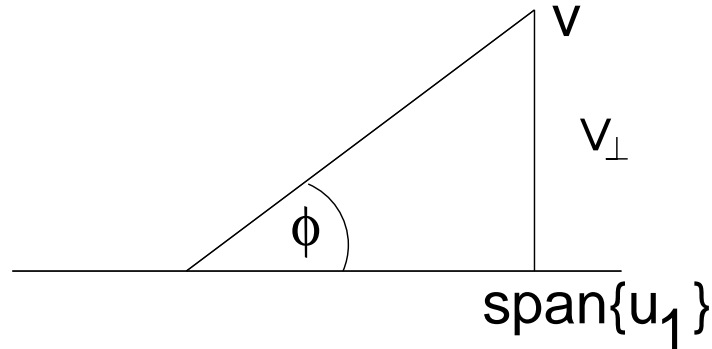
$$|\mu_\epsilon(v) - \mu(v)| \lesssim \epsilon, \quad \|v' - v'_\epsilon\| \lesssim \epsilon.$$

Resulting Rayleigh-quotient satisfies

$$|\mu(v') - \mu(v'_\epsilon)| \lesssim \epsilon,$$

proof by similar arguments as for matrices, see D'yakonov (1996). \square

Subspace convergence



Estimate for angle $\sin \phi \lesssim (\mu(v) - \lambda_1)^{1/2}$ (with respect to $\langle A \cdot, \cdot \rangle$).

For appropriately scaled vectors:

accuracy ϵ in $(V, \|\cdot\|) \sim$ application of A, E with tolerance ϵ^2

Convergence of PPINVIT (II)

Thm 4 (Dahmen/Rohwedder/Schneider/Z., 2007). *(improvement)*
If $\angle(v, u_1)$ is sufficiently small then the angle decreases like

$$\angle(v'_\epsilon, u_1) \leq \tilde{q} \cdot \angle(v, u_1) + \tilde{C}\epsilon, \quad \tilde{q} < 1$$

from step to step, and \tilde{C} can be bounded independently of v and ϵ .

Sketch of proof.

Concentration on vector and its projection onto eigenspace.
Estimation of reduction perpendicular to eigenspace through ellipticity. □

For appropriately scaled vectors:

accuracy ϵ in $(V, \|\cdot\|) \sim$ application of A, E with tolerance ϵ

A convergent algorithm

Starting vector v^0 and target accuracy τ

ADAPTIVE(v^0, τ)

Require: $\angle(v^0, u_1)$ sufficiently small

$\tau^0 \leftarrow \angle(v^0, u_1)$

$i \leftarrow 0$

while $\tau^i > \tau$ **do**

$v^{i+1} \leftarrow \text{PPINVIT}(v^i, \alpha\tau^i, N)$ $\{N$ steps with tolerance $\alpha\tau^i\}$

$\tau^{i+1} \leftarrow \frac{1}{2}\tau^i$

$i \leftarrow i + 1$

end while

return v^i .

N steps of PPINVIT to halve the error, independent of v^i and τ^i .

Part II: Numerical realization

Stable wavelet bases

For basis $(\psi_i)_{i \in \mathcal{I}}$ with index set \mathcal{I}

$$u = \sum_{i \in \mathcal{I}} u_i \psi_i \in V \Leftrightarrow \mathbf{u} = \begin{pmatrix} \vdots \\ u_i \\ \vdots \end{pmatrix} \in \ell_2(\mathcal{I}).$$

Stable bases (Riesz bases) for H and V :

$$\|\mathbf{u}\|_{\ell_2(\mathcal{I})} \sim \|u\|, \quad \|\mathbf{D}^{-1}\mathbf{u}\|_{\ell_2(\mathcal{I})} \sim |u|, \quad \mathbf{D} \text{ diagonal.}$$

Standard example:

$$V = H^t(\Omega), \quad H = L_2(\Omega), \quad \mathbf{D} = (\delta_{ij} 2^{t|i|})_{i,j \in \mathcal{I}},$$

where $|i|$ level of ψ_i .

Equivalent ℓ_2 problem

With stable basis $(\psi_i)_{i \in \mathcal{I}}$

$$Au = \lambda Eu \Leftrightarrow \mathbf{A}\mathbf{u} = \lambda \mathbf{E}\mathbf{u},$$

where

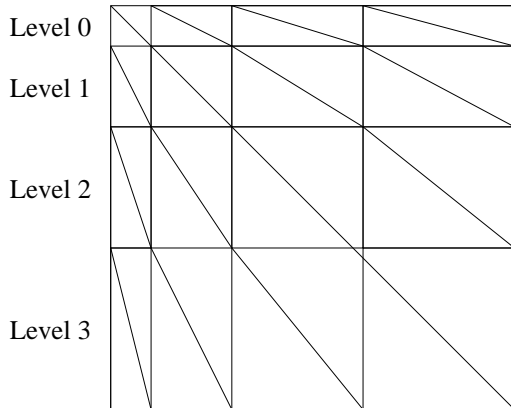
$$\mathbf{A} = (\langle A\psi_i, \psi_j \rangle)_{i,j \in \mathcal{I}}, \quad \mathbf{E} = (\langle E\psi_i, \psi_j \rangle)_{i,j \in \mathcal{I}}.$$

Built-in preconditioning:

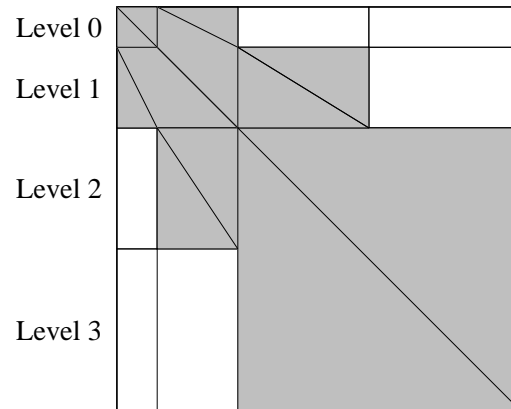
$$\langle \mathbf{A}\mathbf{u}, \mathbf{u} \rangle_{\ell_2} \sim \|\mathbf{u}\|_{\ell_2}^2$$

equivalent problem to $Au = \lambda Eu$ through norm-equivalence

Quasi-sparsity



Original matrix \mathbf{B} .



Compressed matrix \mathbf{B}_j .

Controlled approximation: $\|\mathbf{B} - \mathbf{B}_j\|_{\ell_2} \approx 2^{-js}$, with $\approx 2^j$ entries per row/column (s^* -computable).

- wide class of discretized operators quasi-sparse
- simple approximation of $\mathbf{A}\mathbf{u}$ through

$$\mathbf{B}_\epsilon(\mathbf{u}) = \mathbf{B}_j\mathbf{u}, \quad j \text{ appropriate.}$$

- more advanced nonlinear scheme in Cohen/Dahmen/deVore (2001).

Exploding support

Approximate operator application:

$$\#\mathbf{v} < \infty \Rightarrow \#\mathbf{A}_\epsilon(\mathbf{v}), \#\mathbf{E}_\epsilon(\mathbf{v}) < \infty$$

with $\#\mathbf{v}$ number of non-zero entries.

A computable algorithm:

- Initial vector \mathbf{v}^0 with $\#\mathbf{v}^0 < \infty$
- Iterate

$$\mathbf{v}^{n+1} = \mathbf{v}^n - \alpha (\mathbf{A}_\epsilon(\mathbf{v}^n) - \mu_\epsilon(\mathbf{v}^n)\mathbf{E}_\epsilon(\mathbf{v}^n))$$

Support of \mathbf{v}^n stays finite but explodes:

$$\#\mathbf{v}^n \sim C^n, \quad C > 1.$$

Non-optimal behavior in number of degrees of freedom.

Part III: Optimality

Adaptivity

Let $u \in V$

$$u = \sum_{i \in \mathcal{I}} u_i \psi_i \Rightarrow \mathbf{u} = \begin{pmatrix} \vdots \\ u_i \\ \vdots \end{pmatrix}.$$

For finite index set \mathcal{I}_0 with $u_i = 0, i \notin \mathcal{I}_0$:

$$u = \sum_{i \in \mathcal{I}_0} u_i \psi_i \quad \text{finite sum} \Leftrightarrow \mathbf{u} = \begin{pmatrix} \vdots \\ 0 \\ * \\ \vdots \end{pmatrix} \quad \text{finite number of entries.}$$

Non-zero entry $u_i \leftrightarrow$ basis function ψ_i needed in expansion.

Best- N -term approximation

Best-approximation in $\ell_2(\mathcal{I})$ with N non-zero elements:

$$\sigma_N(\mathbf{u}) = \inf\{\|\mathbf{u} - \mathbf{v}\|_{\ell_2}, \#\mathbf{v} \leq N\}.$$

Approximation space

$$\mathcal{A}^s = \{\mathbf{u} \in \ell_2(\mathcal{I}) : \|\mathbf{u}\|_{\ell_2} + |\mathbf{u}|_{\mathcal{A}^s} < \infty\}, \quad |\mathbf{u}|_{\mathcal{A}^s} = \sup_{N \geq 1} N^s \sigma_N(\mathbf{u}).$$

Approximation of $\mathbf{u} \in \mathcal{A}^s$

$$\text{accuracy } \epsilon \leftrightarrow \text{number of degrees of freedom } \epsilon^{-1/s} |\mathbf{u}|_{\mathcal{A}^s}$$

Coarsening and approximation

Thm 5 (Cohen/Dahmen/deVore, 2001).

Coarsening with appropriate tolerance of approximation \mathbf{v} with

$$\|\mathbf{v} - \mathbf{u}\| \leq \epsilon, \quad \mathbf{u} \in \mathcal{A}^s$$

leads to quasi-optimal approximation \mathbf{w} :

$$\|\mathbf{w}\|_{\mathcal{A}^s} \lesssim \|\mathbf{u}\|_{\mathcal{A}^s}, \quad \#\mathbf{w} \lesssim \|\mathbf{u}\|_{\mathcal{A}^s}^{1/s} \epsilon^{-1/s}, \quad \|\mathbf{u} - \mathbf{w}\| \lesssim \epsilon.$$

Time to time coarsening prevents exponential growth of the iterates.

Optimal adaptive algorithm

Starting vector v^0 , target accuracy τ .

MINIEIG(v^0, τ)

Require: $\angle(v^0, u_1)$ sufficiently small

$$\tau^0 \leftarrow \angle(v^0, u_1)$$

$$i \leftarrow 0$$

while $\tau^i > \tau$ **do**

$$\check{v}^{i+1} \leftarrow \text{PPINVIT}(v^i, \alpha_1 \tau^i, N) \{ \alpha_1 \text{ fixed} \}$$

$$v^{i+1} \leftarrow \text{APPROX}(\check{v}^{i+1}, \alpha_2 \tau^i) \{ \alpha_2 \text{ fixed, Coarsening step} \}$$

$$\tau^{i+1} \leftarrow \frac{1}{2} \tau^i$$

$$i \leftarrow i + 1$$

end while

return v^i

Simplified version from Dahmen/Rohwedder/Schneider/Z. (2007).
Includes efficient and reliable error estimator.

Optimal convergence

Thm 6 (Dahmen/Rohwedder/Schneider/Z., 2007).

For compressible operators \mathbf{A} and \mathbf{E} , the algorithm gives for each target accuracy τ a vector \mathbf{u}_τ :

$$\angle(\mathbf{u}_\tau, \mathbf{u}_1) \lesssim \tau, \quad |\mu_\tau(\mathbf{u}_\tau) - \lambda_1| \lesssim \tau.$$

If the eigenvector $\mathbf{u}_1 \in \mathcal{A}^s$ then

$$\#\mathbf{u}_\tau \lesssim \tau^{-1/s}$$

given sufficiently compressible operators. The floating point operations remain bounded linearly.

Sketch of proof.

Convergence of PPINVIT, estimate perturbation due to coarsening.

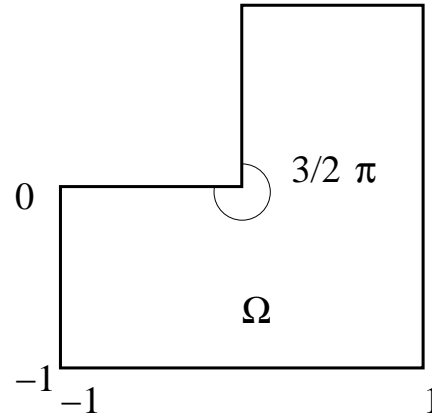
Bookkeeping of $\|\cdot\|_{\mathcal{A}^s}$, support sizes and flops. □

Part IV: (Preliminary) numerical results

A model problem

Poisson eigenvalue problem in \mathbb{R}^2 :

$$\begin{aligned} -\Delta u &= \lambda u \quad \text{on } \Omega, \\ u|_{\partial\Omega} &= 0. \end{aligned}$$



- Reduced Sobolev regularity due to corner. Classical theory:

$$u_1 \in H^s, \quad s < 1 + \frac{\pi}{\alpha} = \frac{5}{3}$$

$$\text{rates: } \|u_1 - u_h\| \lesssim N^{-1/3}, \quad |\lambda_1 - \mu(u_h)| \lesssim N^{-2/3}.$$

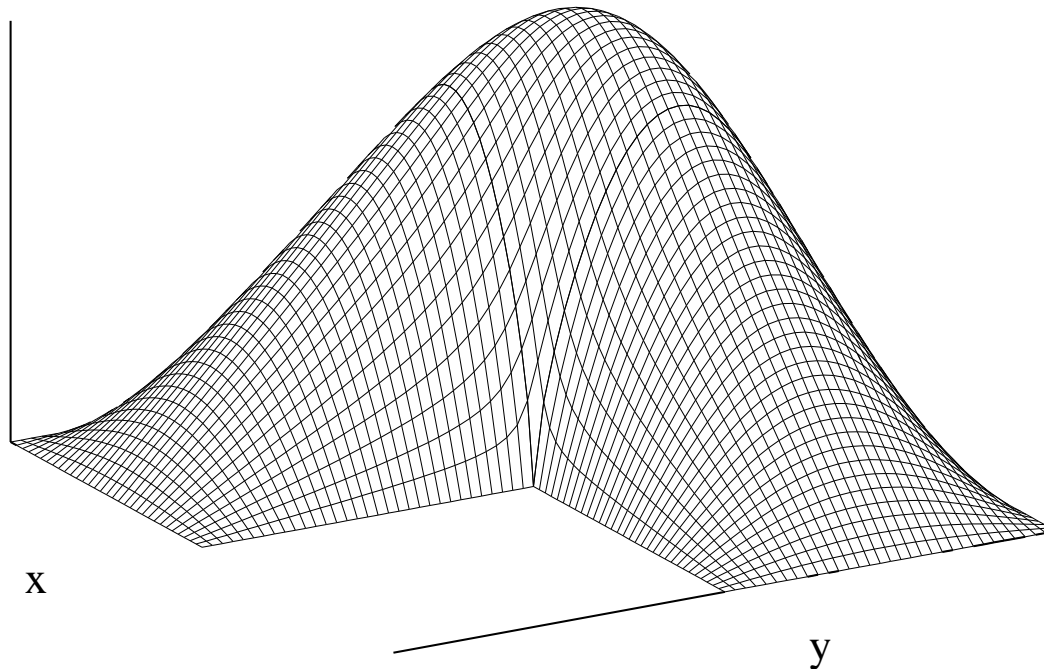
- Higher Besov regularity (Dahlke 1999)

$$u_1 \in B_{\tau,\tau}^{2s+1}, \quad \frac{1}{\tau} = s + \frac{1}{2}, \quad 0 < s < \frac{13}{12}.$$

$$\text{rates: } \|u_1 - u_h\| \lesssim N^{-1/2}, \quad |\lambda_1 - \mu(u_h)| \lesssim N^{-1}$$

due to linear wavelets. Likely not optimal (bootstrapping).

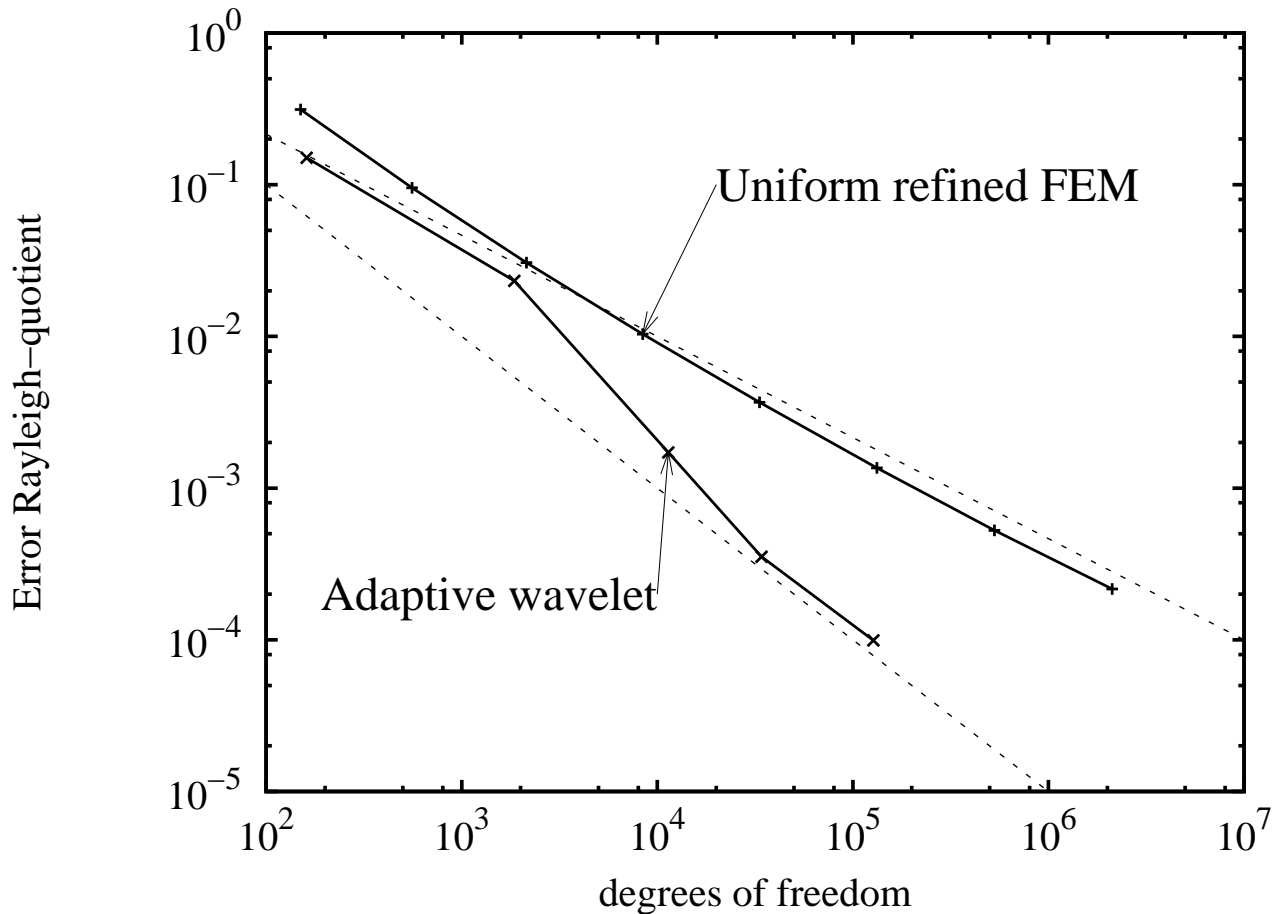
Numerical result



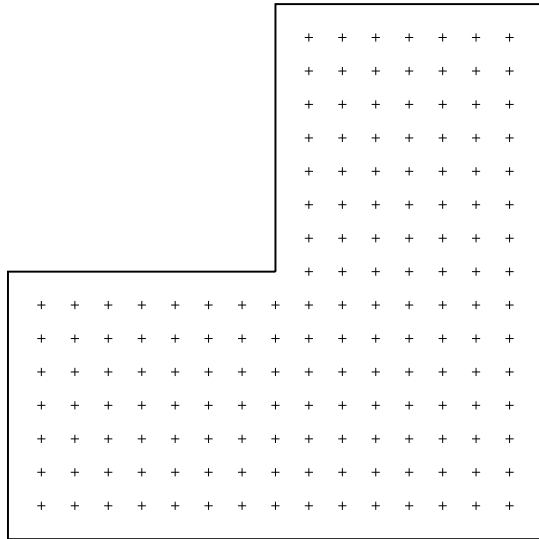
Joint work with Jürgen Vorloeper (RWTH Aachen).

- Linear wavelets with tree-structured index sets
- Exact application of operators for given index set
- Galerkin-solution with frozen index sets

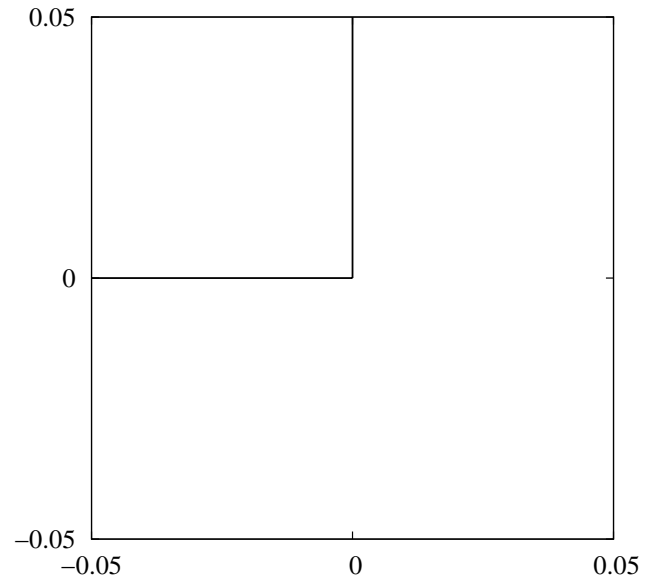
Convergence rates



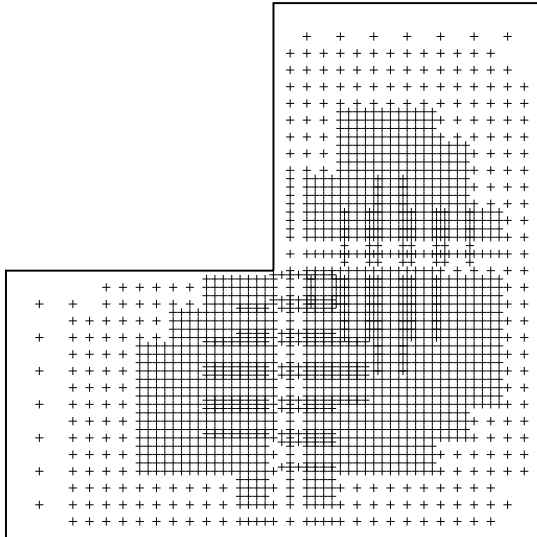
Index sets - Initial iterate



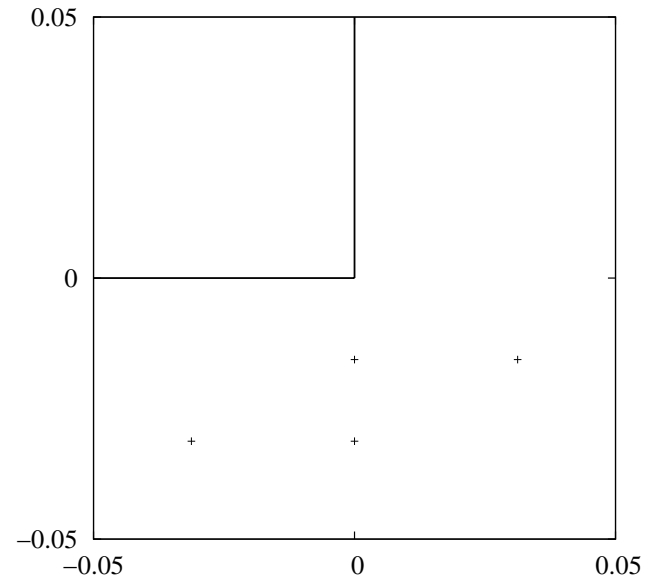
161 degrees of freedom



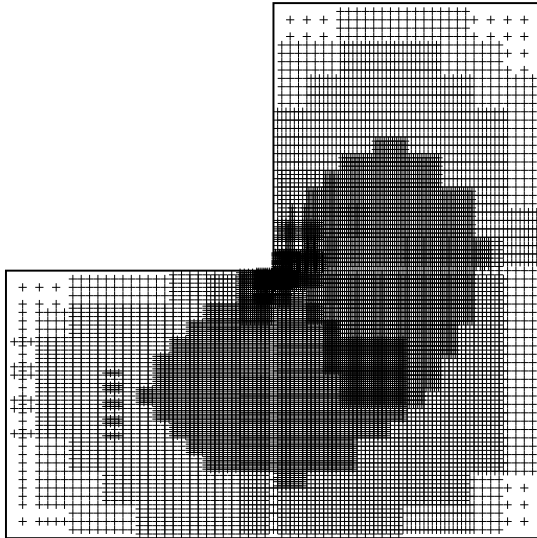
Index sets - 1st iterate



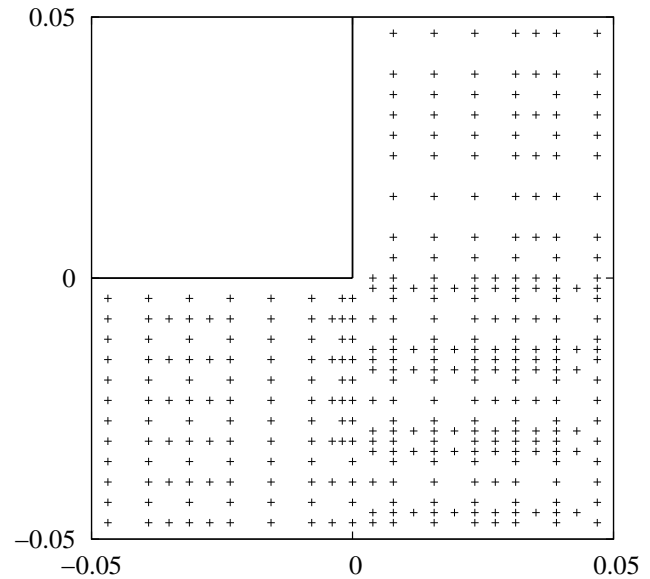
1859 degrees of freedom



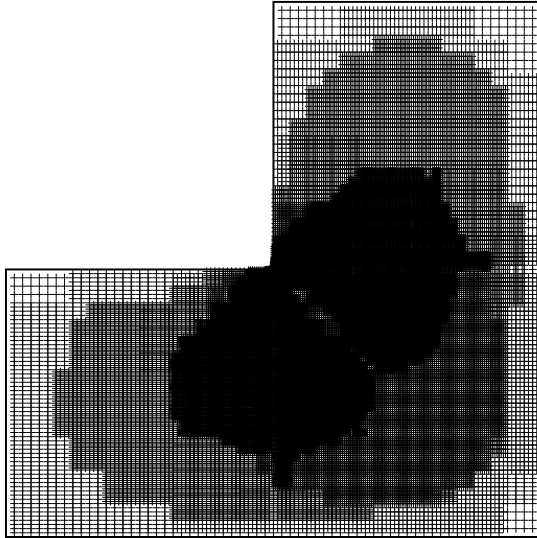
Index sets - 2nd iterate



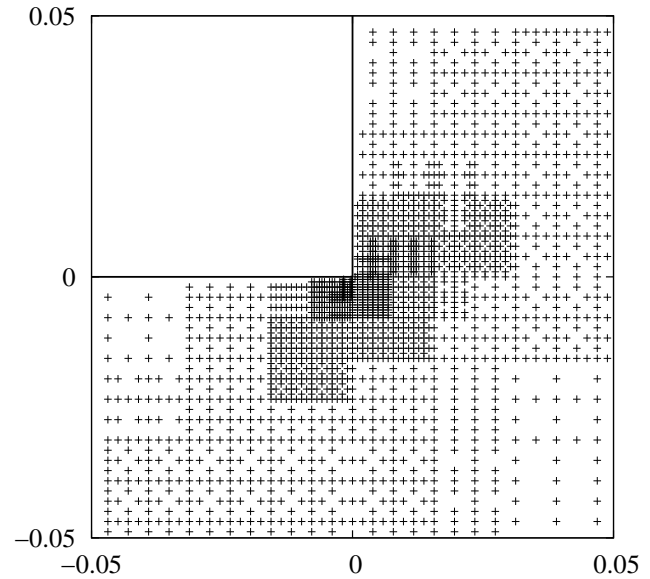
11393 degrees of freedom



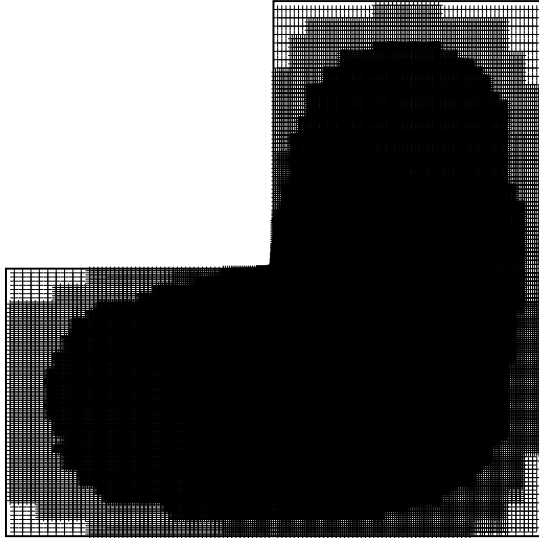
Index sets - 3rd iterate



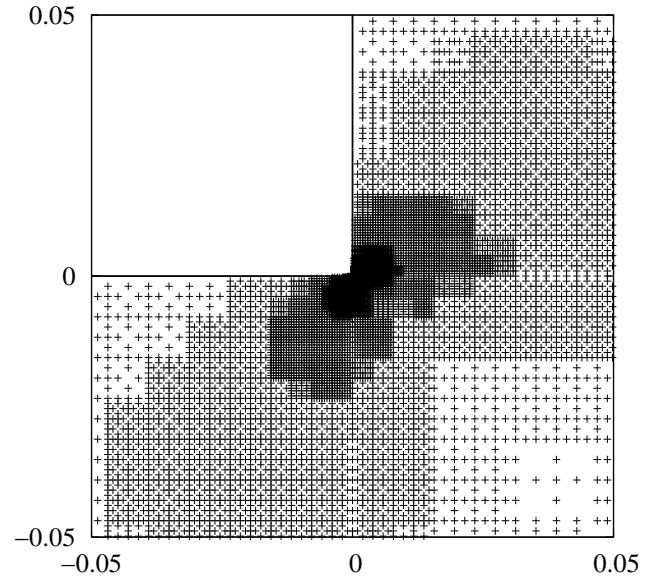
34124 degrees of freedom



Index sets - 4th iterate



127355 degrees of freedom



Summary

- Preconditioned inverse iteration as abstract iteration scheme
- Robustness of PINVIT against perturbations
- Numerical realization through stable wavelet bases
- Optimality through coarsening
- First (preliminary) numerical realization

References

- [1] T. Rohwedder, R. Schneider, A. Zeiser, *Perturbed preconditioned inverse iteration for operator eigenvalue problems with applications to adaptive wavelet discretizations*, submitted 2007.
- [2] W. Dahmen, T. Rohwedder, R. Schneider, A. Zeiser, *Adaptive Eigenvalue Computation – Complexity Estimates*, submitted 2007.

available at <http://www.math.tu-berlin.de/~zeiser>.

Thank you for your attention.